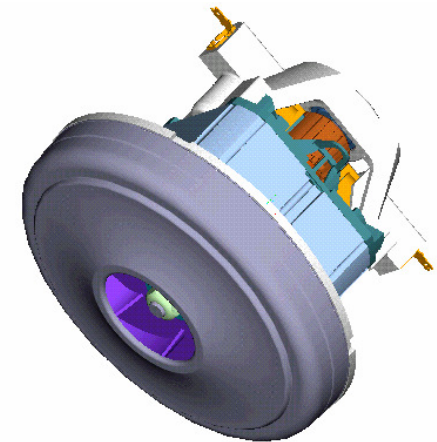


# Integrated approach for noise reduction on vacuum motors

## Tutorial

Dr. Jože Tavčar  
DOMEL d.d.  
Slovenia



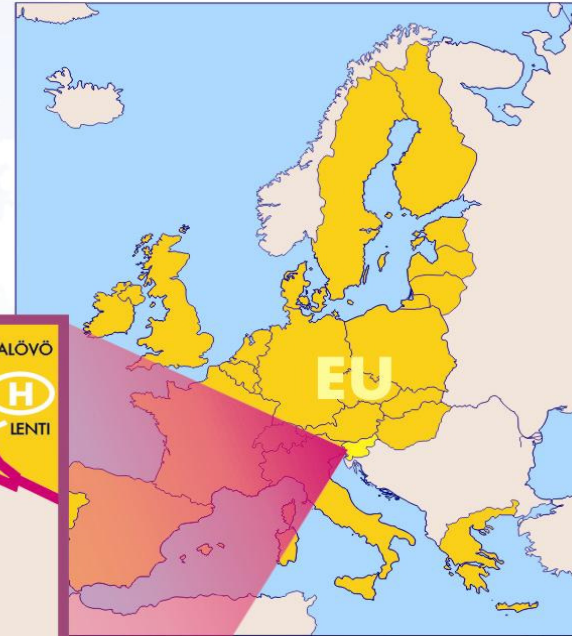
# Integrated approach for noise reduction on vacuum motors

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## Agenda

- Introduction
- Sound – physical background
- Sound pressure and power measurement
- Research methods
  - Vibration control
  - Aero-dynamic noise
  - CFD calculations
  - Noise camera
- Case study (noise control / peak removal)
  - Variation of impeller geometry
  - Helmholtz resonator
- Active noise control
- Conclusions

# DOMEL LOCATION



**2005**



- Domel d.d., Železniki, Slovenia

- Since 1946

- Global motor producer

- <http://www.domel.com>





# PRODUCT GROUPS



**VACUUM CLEANER MOTORS -  
DRY ASPIRATION  
VACUUM CLEANER MOTORS -  
WET & DRY ASPIRATION**

**DC MOTORS**

**UNIVERSAL COMMUTATOR MOTORS**

**BRUSHLESS EC DC BLOWERS/PUMPS  
EC CENTRIFUGAL FANS  
EC EXTERNAL ROTOR MOTORS**

**TOOLS  
COMPONENTS**



information: [www.domel.com](http://www.domel.com)

**2005**

# Sound – Physical background

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## Physical background:

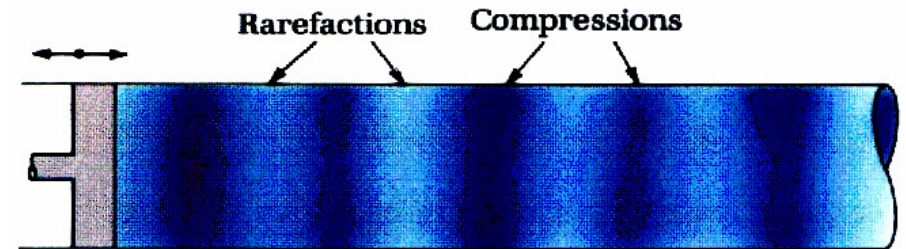
- **Sound sources**
- **Human perception of the sound**
- **How to measure sound ?**

# Sound wave

Bruel&Kjaer

## ■ Sound Source:

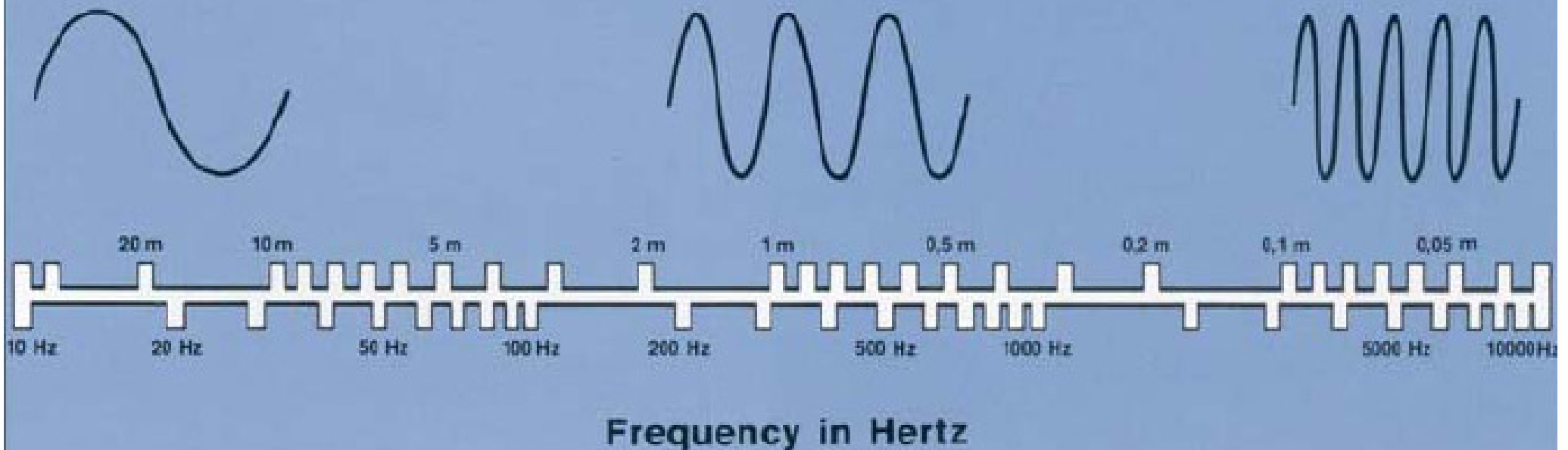
- Structural vibrations
- Aero-dynamic - Fluid flow



Speed of sound at normal  
air conditions: 340 m/s

Wavelength in Meters

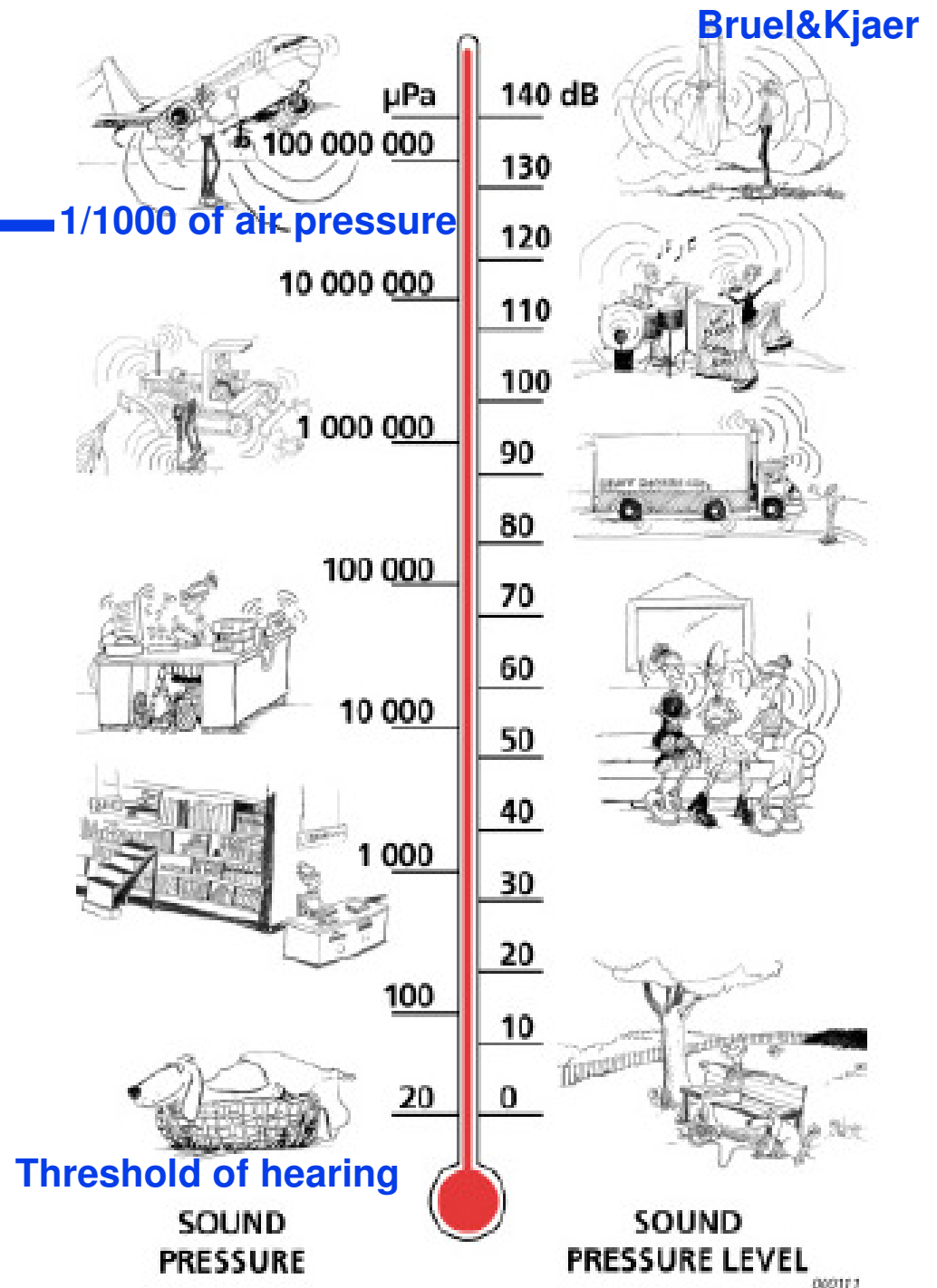
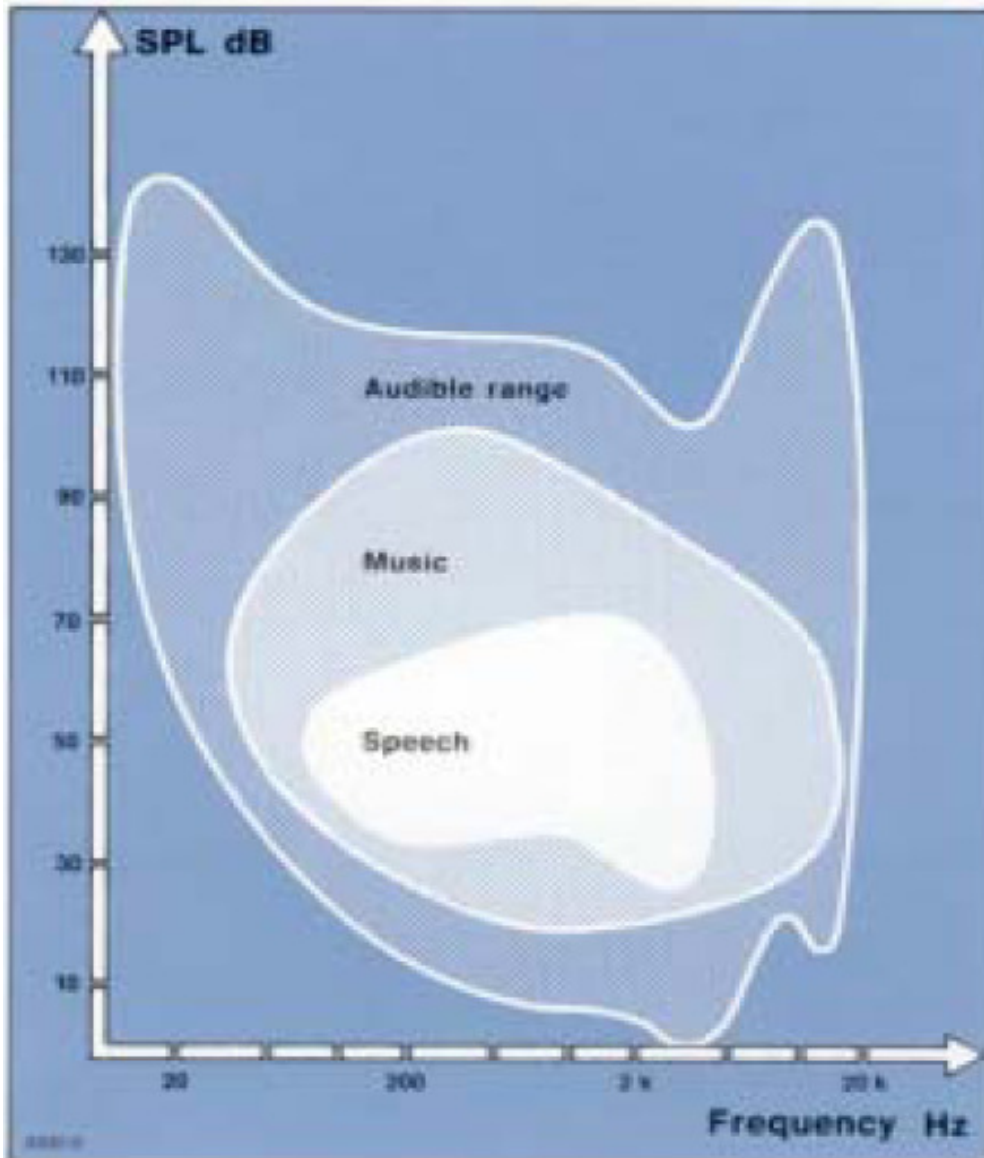
$$\text{Wavelength } (\lambda) = \frac{\text{Speed of sound}}{\text{Frequency}}$$





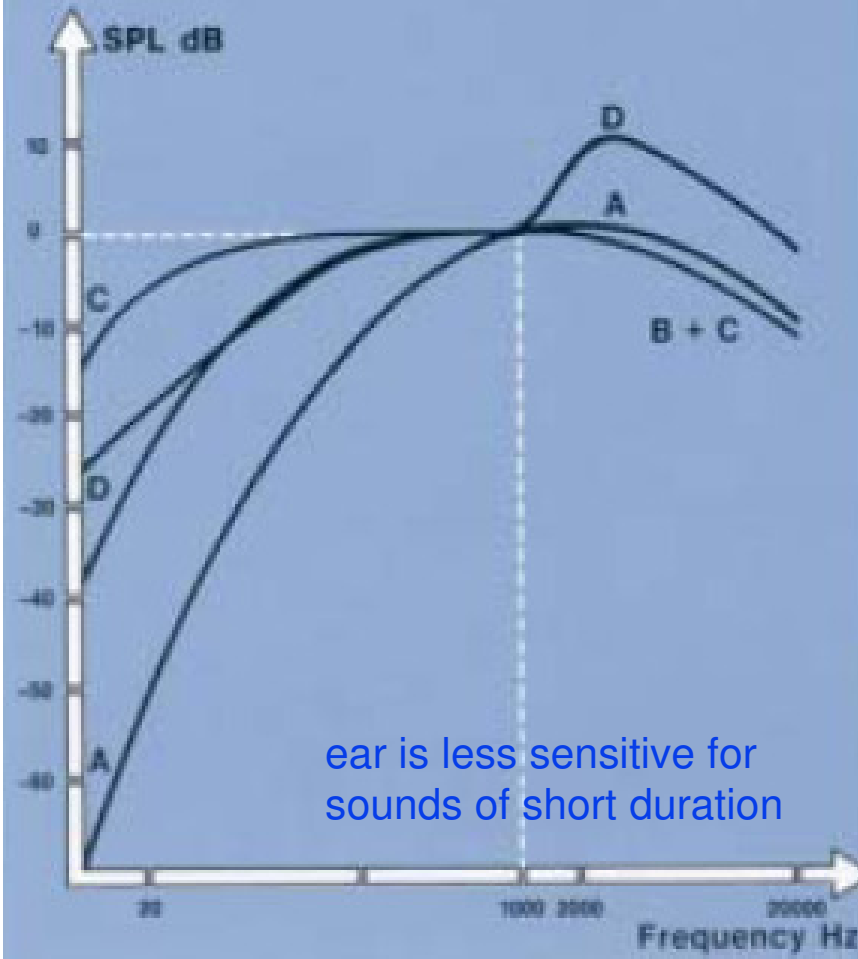
# Sound pressure level

$$L_p = 10 \log_{10} p^2 / p_0^2$$

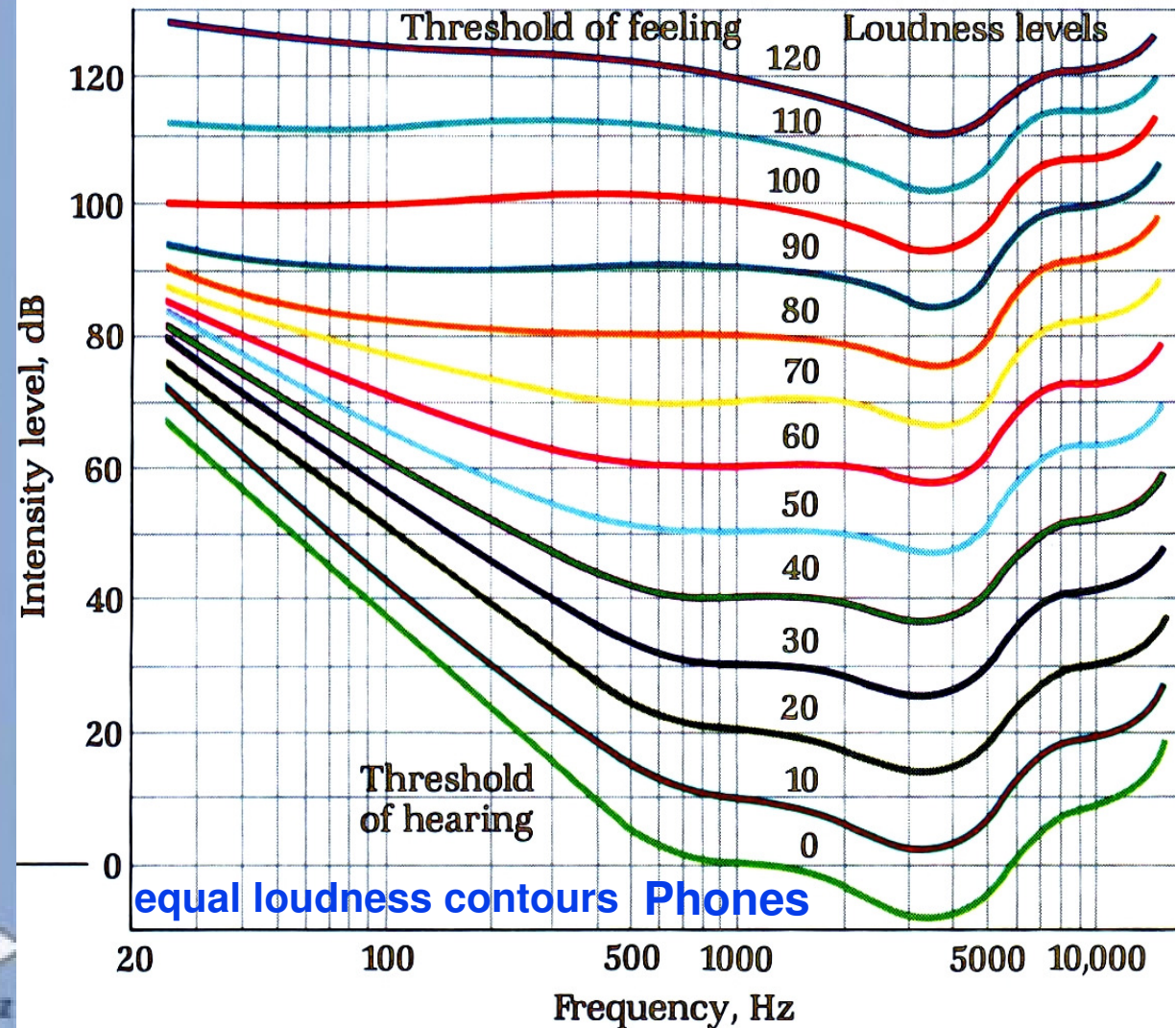


# Human perception of sound

**A** - weighting network – at low sound pressure level – widely used  
**D** – for aircraft noise measurements



Curves of perceived equal loudness Bruel&Kjaer



# Analogy between sound pressure ( $L_p$ ) and temperature (T) and sound power ( $L_w$ ) and electric power

Sound Source :

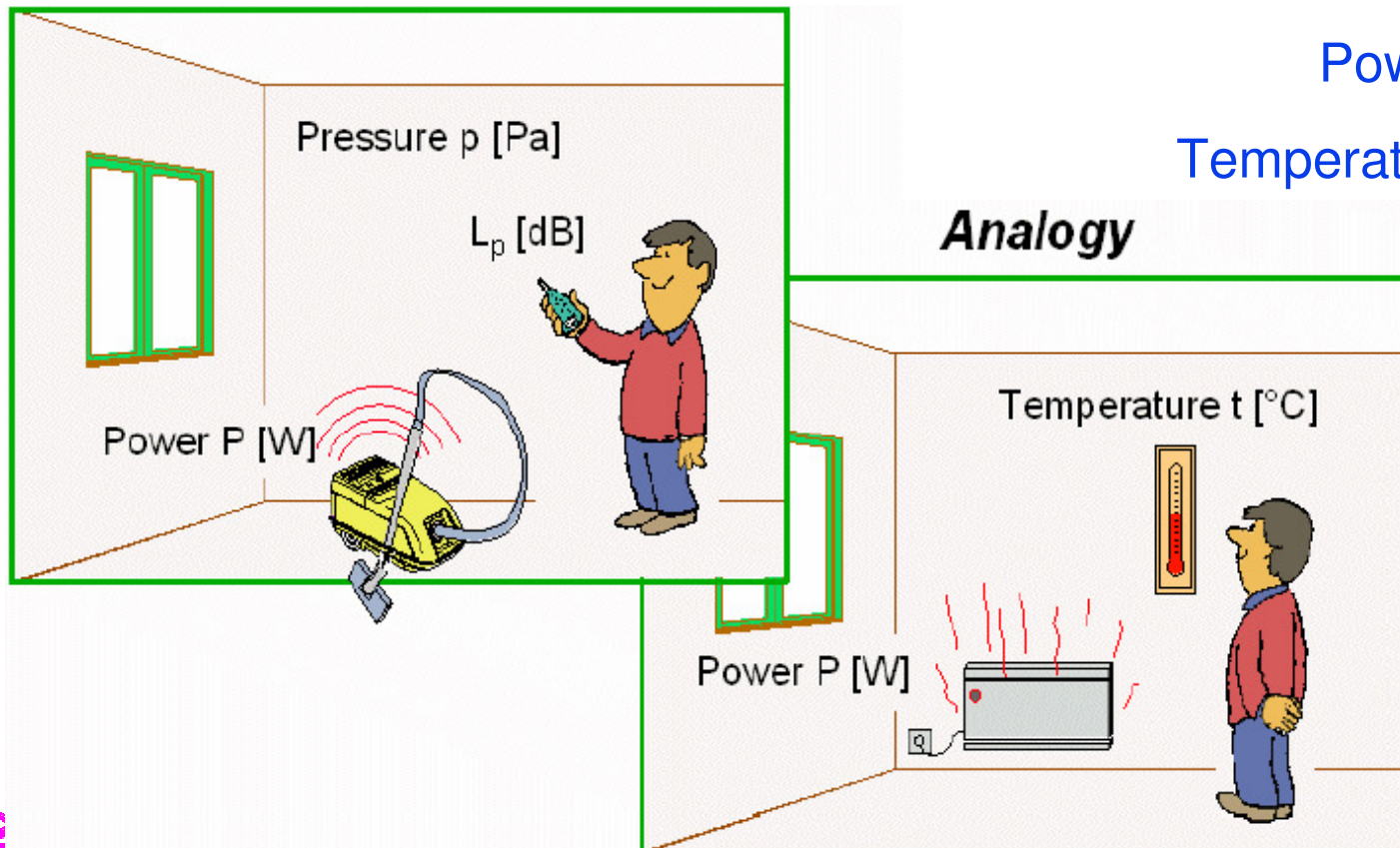
Sound Power P [W]  $L_w$

Sound Pressure p [N/m<sup>2</sup>]  $L_p$

Electrical Heater :

Power P [W]

Temperature t [°C]





# Quantifikation of sound sources

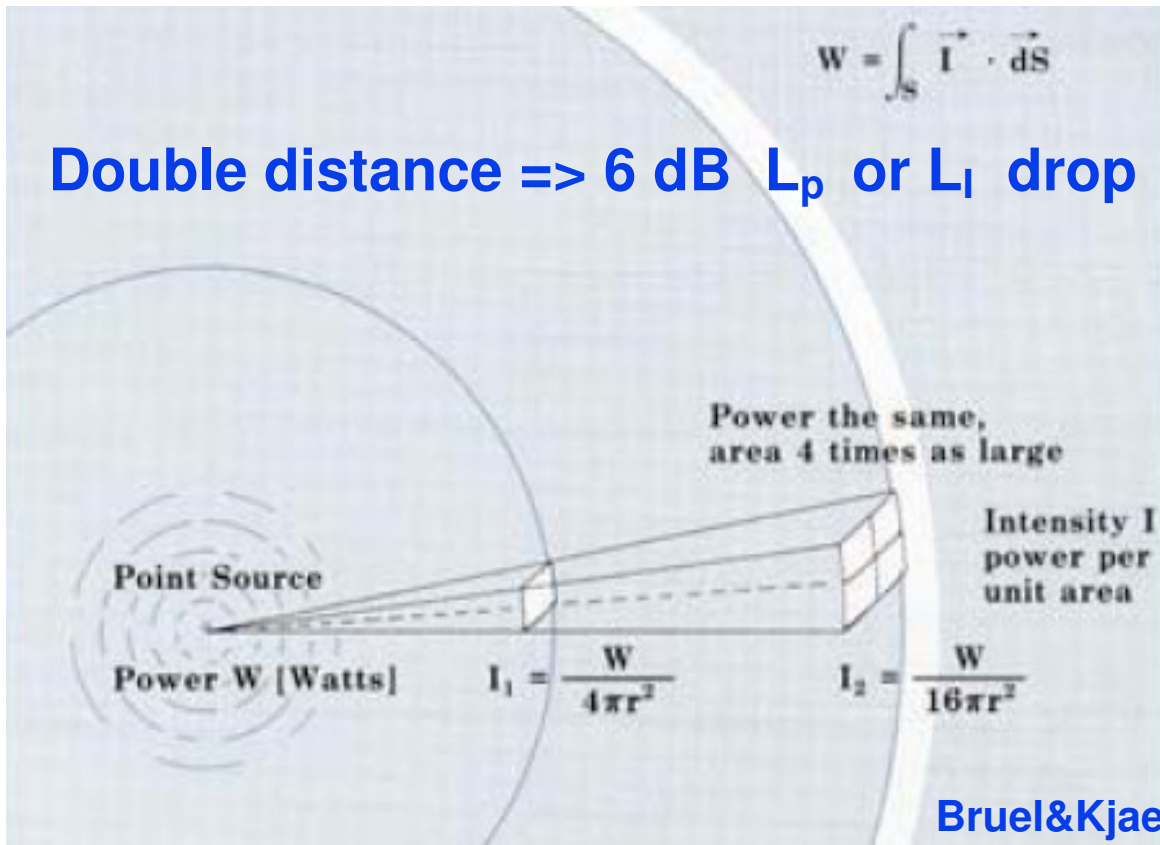
- $L_W$  ... Sound power **94 dB(A)  $L_W$**
- $L_I$  ... Sound intensity
- $L_p$  ... Sound pressure (1 m) **83 dB(A)  $L_p$**

$$W = I \cdot S$$

$$I = \frac{(\Delta p_{\max})^2}{2 \cdot v \cdot \rho}$$

$$W = \int_S \vec{I} \cdot d\vec{S}$$

Double distance => 6 dB  $L_p$  or  $L_I$  drop



Ref. parameter	$W_0$	$I_0$	$p_0$
Unit	W	W/m <sup>2</sup>	Pa
Reference value	10 <sup>-12</sup>	10 <sup>-12</sup>	2·10 <sup>-5</sup>

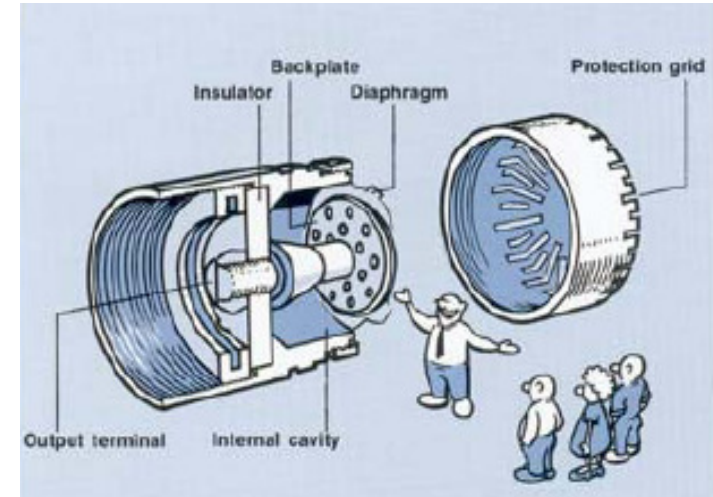
$$L_W = 10 \cdot \log_{10} \left( \frac{W}{W_0} \right) \quad [\text{dB}, \text{dB}_A]$$

$$L_I = 10 \cdot \log_{10} \left( \frac{I}{I_0} \right) \quad [\text{dB}, \text{dB}_A]$$

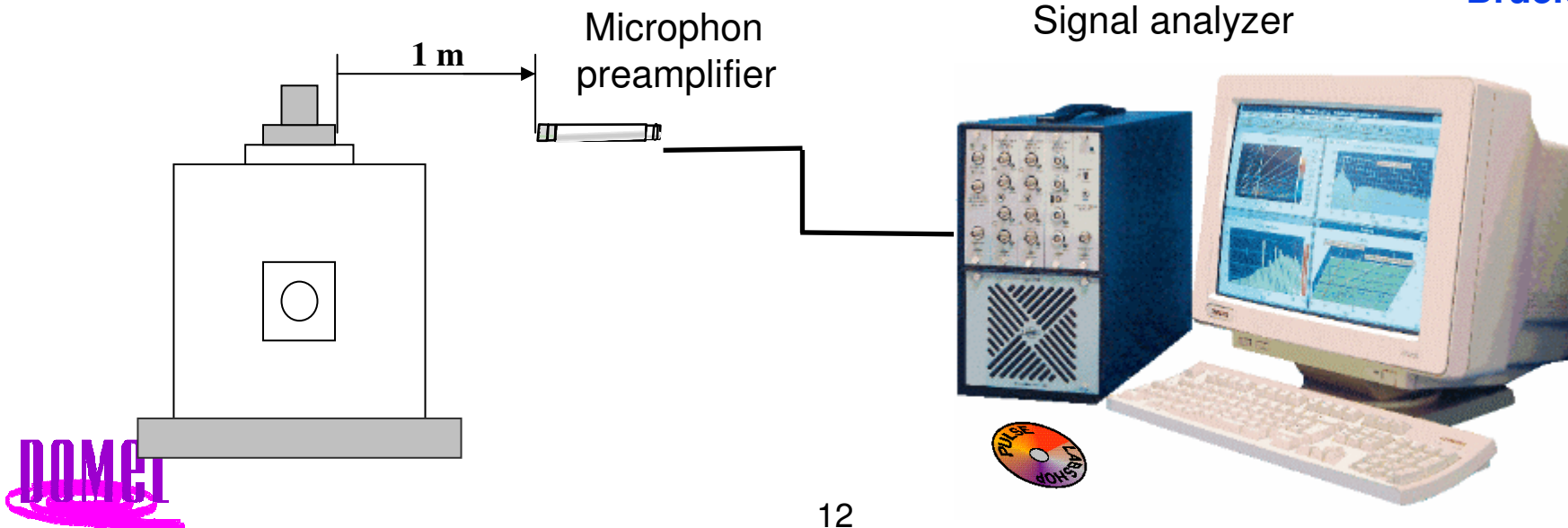
$$L_p = 10 \cdot \log_{10} \left( \frac{p^2}{p_0^2} \right) \quad [\text{dB}, \text{dB}_A]$$

# Measurement equipment – sound pressure ( $L_p$ )

- Microphon  
(condenser, tensioned-metal diaphragm)
- Preamplifier  
(converts output signal into low impedance)
- signal analyser (FFT, CPB)
- **anechoic chamber (free field)**

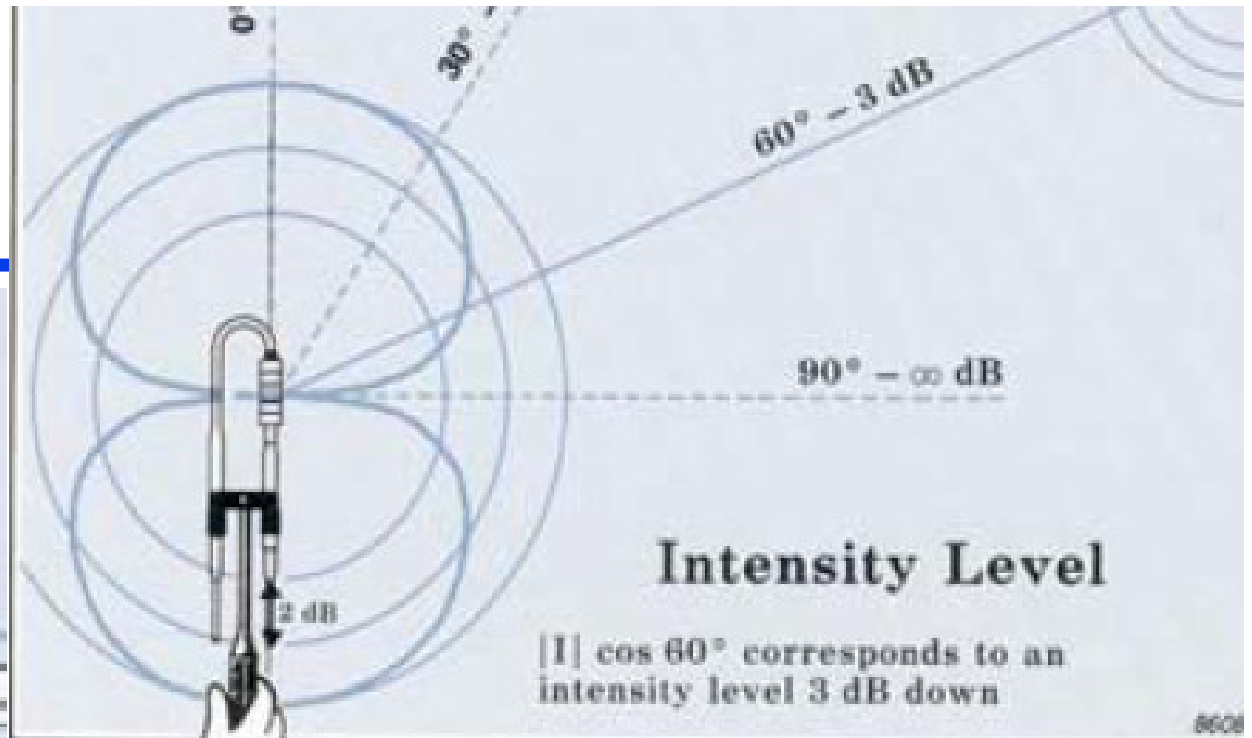
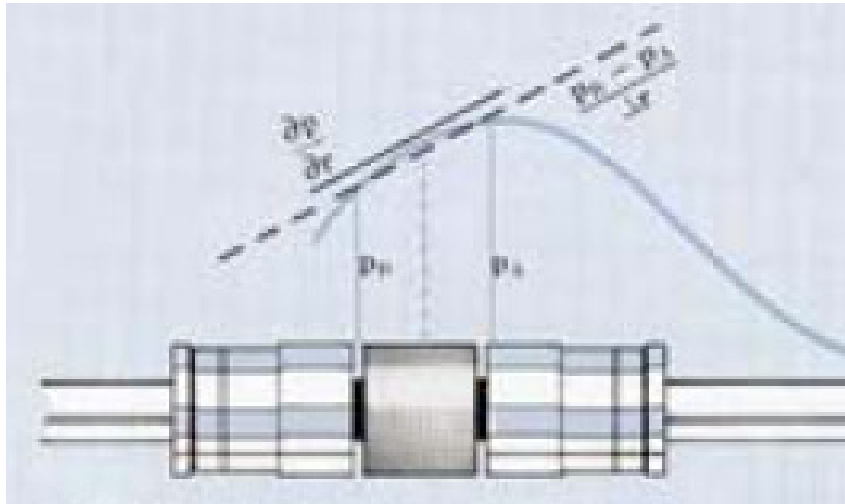


Bruel&Kjaer



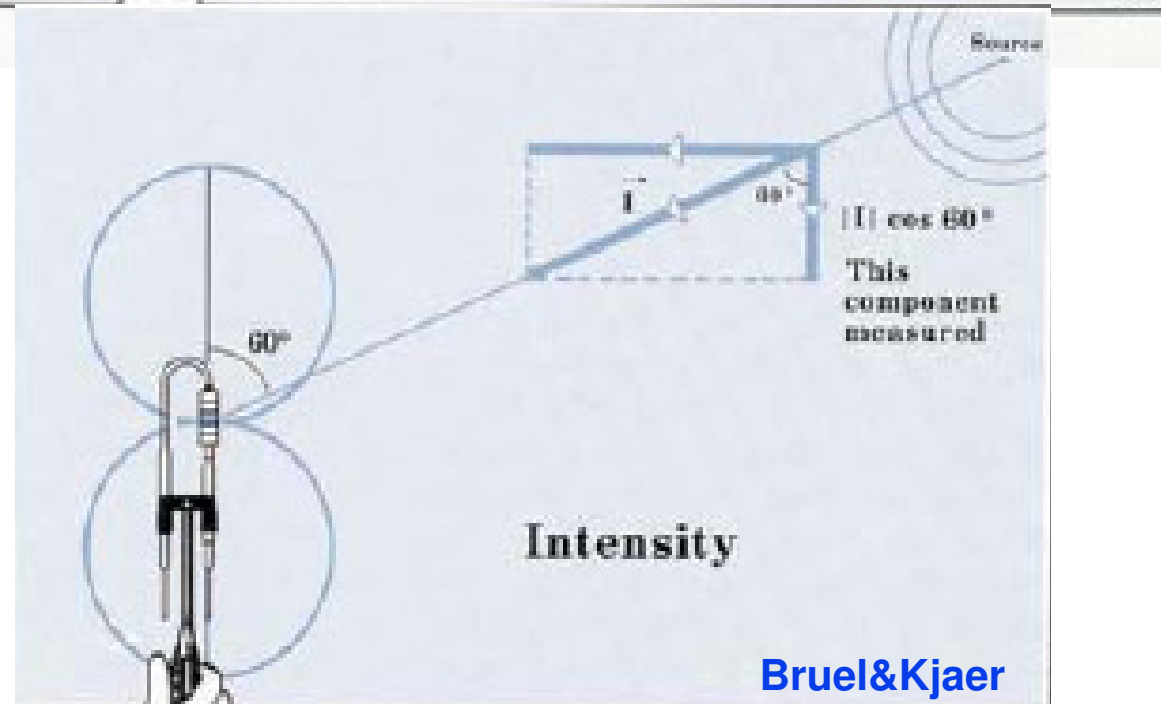
DOMCI

# Sound intensity



Bruel&Kjaer

Sound intensity measure only the component perpendicular to the sound source.

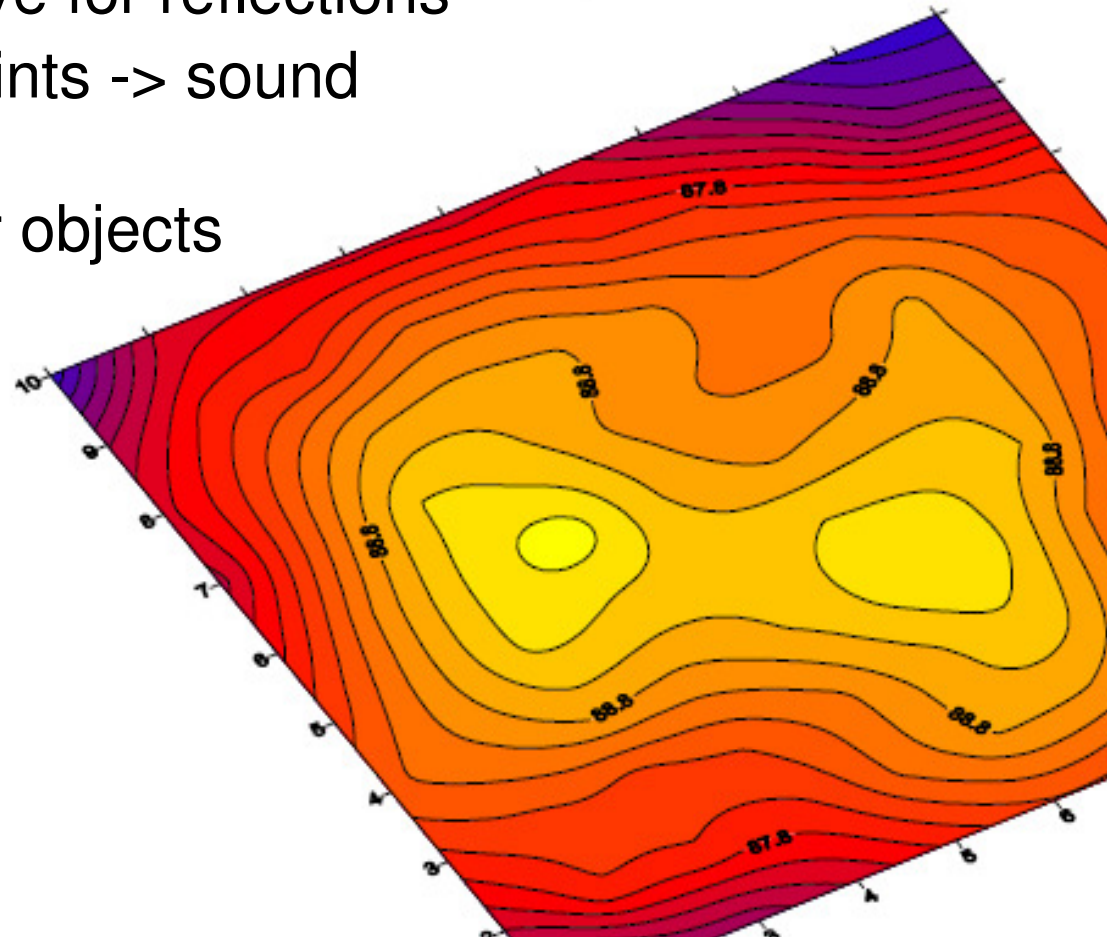
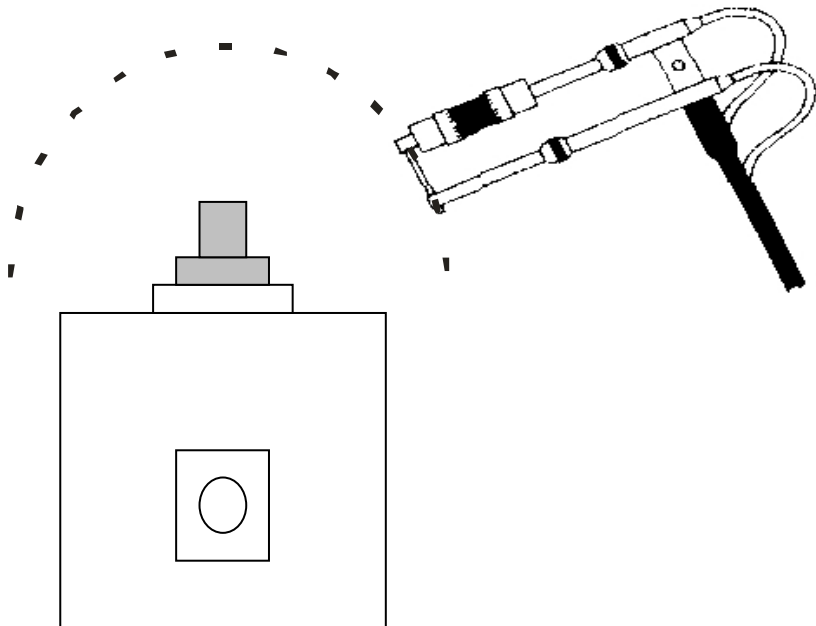


Bruel&Kjaer



# Measurement equipment – sound intensity

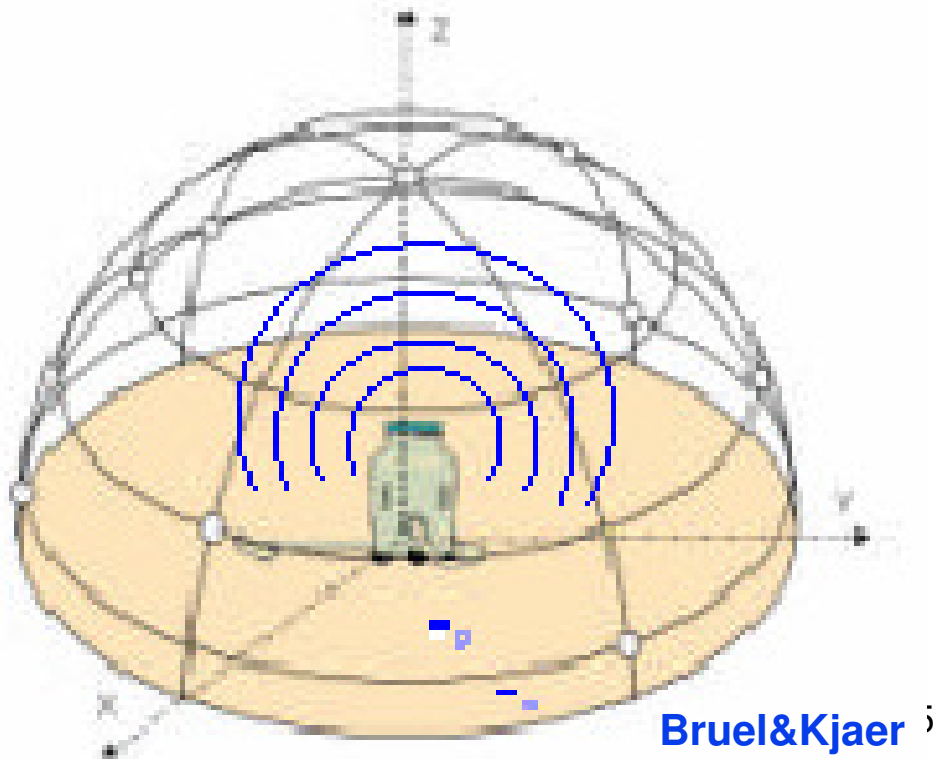
- Equipment to measure sound intensity:
  - Sound sonde – 2 phase microphone
  - Measurement is not sensitive for reflections
  - Measurement at all mesh points -> sound intensity map
  - Sources of sound on bigger objects



# Measurements: noise spectrum in anechoic chamber

- Noise pressure measurement  $L_p$
- Noise power measurement  $L_w$   
Pressure-based, almost free-field,  
ISO 3744 (soft padding on the walls)

$$L_p = 10 \log_{10} p^2/p_o^2 \quad L_w = 10 \log_{10} W/W_o$$

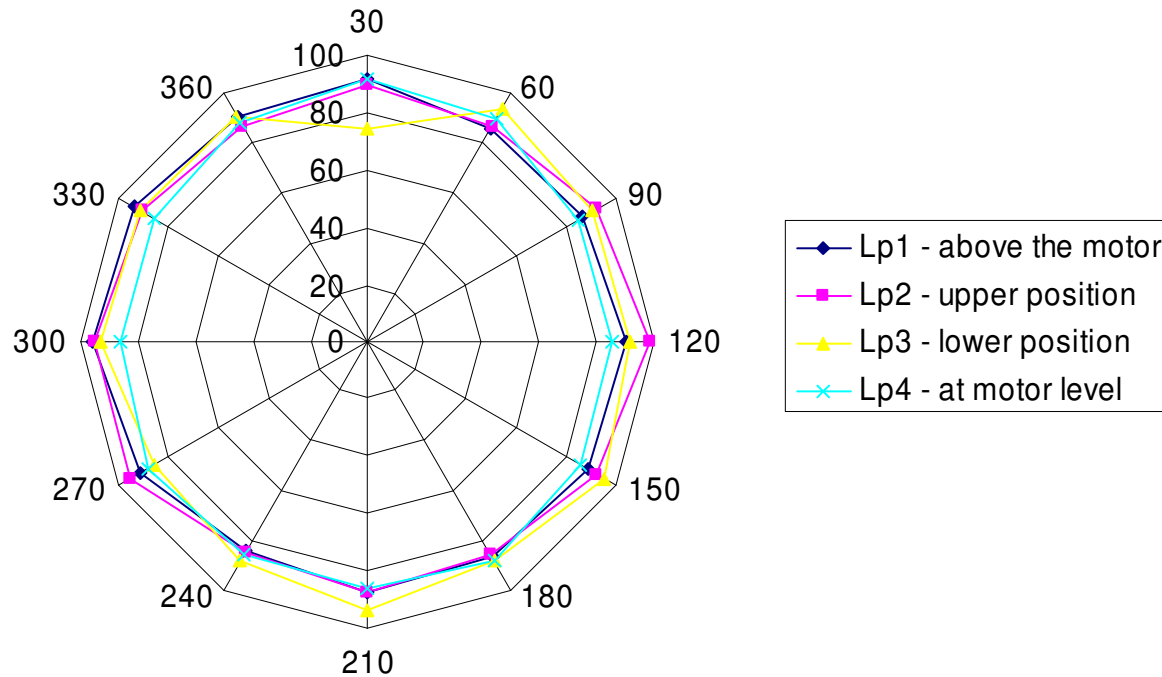




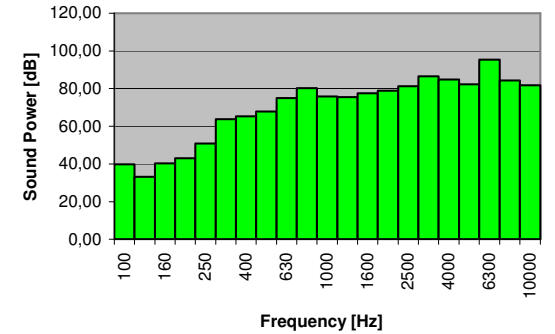
Req. No. 11830905  
 Working ord. No. 98914  
 date: 21th September, 2005  
 measured by: Dragica Bačić  
 BR / J. Tavcar  
 463.3.201 standard  
 226V / 50Hz

# Noise power level (Lw) report

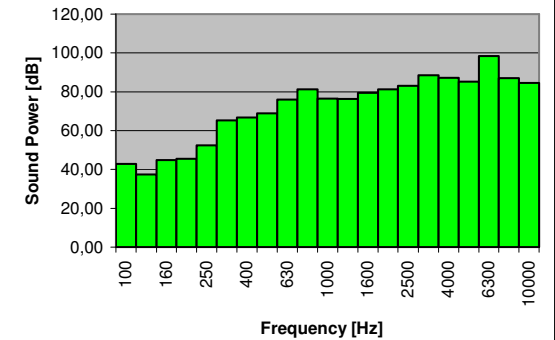
**Sound pressure level Lp [dB]**  
 (around object at 1 m distance)



**Sound power spectrum Lw**

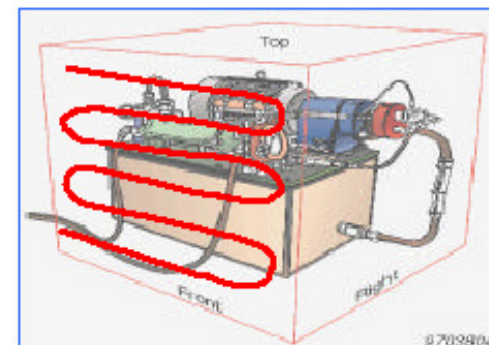
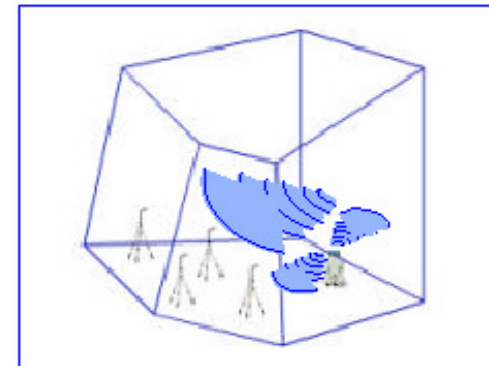
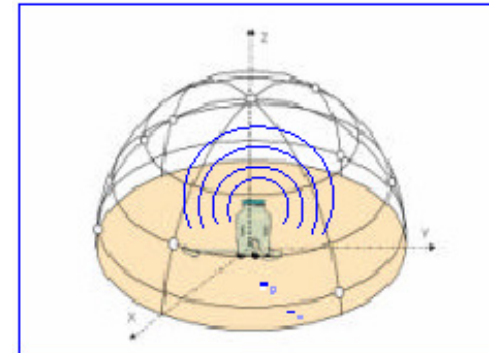


**Sound power spectrum Lw corrected K2**



## Methods of measuring Sound power ( $P_w$ ) level

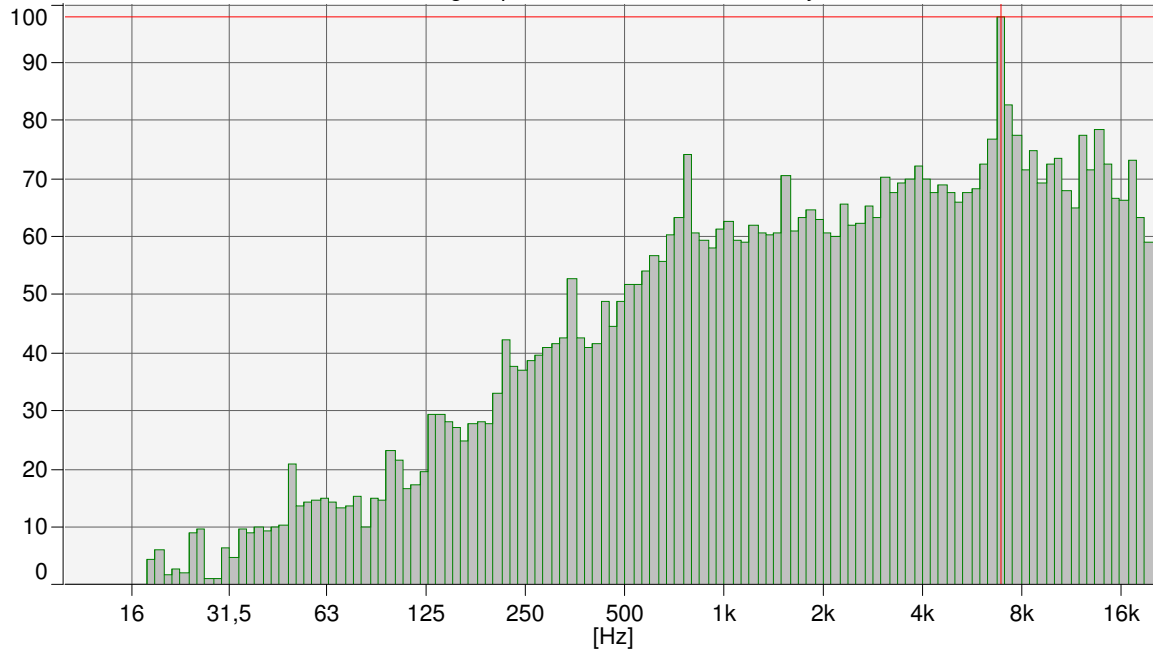
- Pressure-Based, **Free Field**
  - Almost free-field, ISO **3744**
  - Anechoic or Semi-anechoic chamber, ISO 3745
  
- Pressure-based, **Diffuse Field**
  - Reverberation room, ISO **3741**
  - Special reverberation room, ISO 3743  
sound energy is uniformly distributed
  
- **Intensity**
  - Scanned Measurements, ISO **9614 - 2**
  - Point measurements, ISO 9614 - 1





[dB(A)/20,00u Pa]

Autospectrum(noise)\_CPB\_fi13  
Working : Input : Multi-buffer 2 : CPB Analyzer



## FFT and CPB spectrum

CPB – Constant Percentage  
Bandwidth  
1/12 octave / 1/3 octave

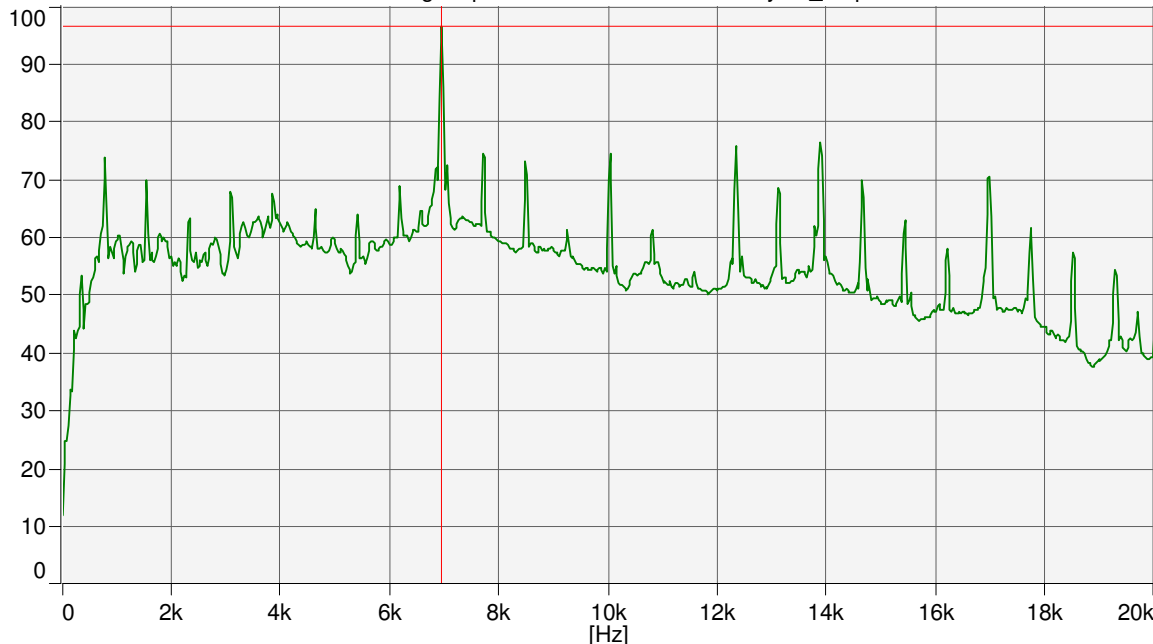
**250 Hz – 500 Hz**      **1 Octave**  
higher frequency = 2 x lower freq.  
1 Octave = **8 tones** in music

A third octave:  
higher freq. = 1,26 times lower freq.

FFT – Fast Fourier Transformation  
linear frequency scale (x-axis)

[dB(A)/20,00u Pa]


Autospectrum\_fi\_13\_noise  
Working : Input : Multi-buffer 2 : FFT Analyzer\_hrup





# Octave

A tonal difference of two pairs of tones is perceived equally if the ratio (and not absolute difference) of the two frequency pairs is equal.

$$\frac{f_{a1}}{f_{a2}} = \frac{f_{b1}}{f_{b2}}$$

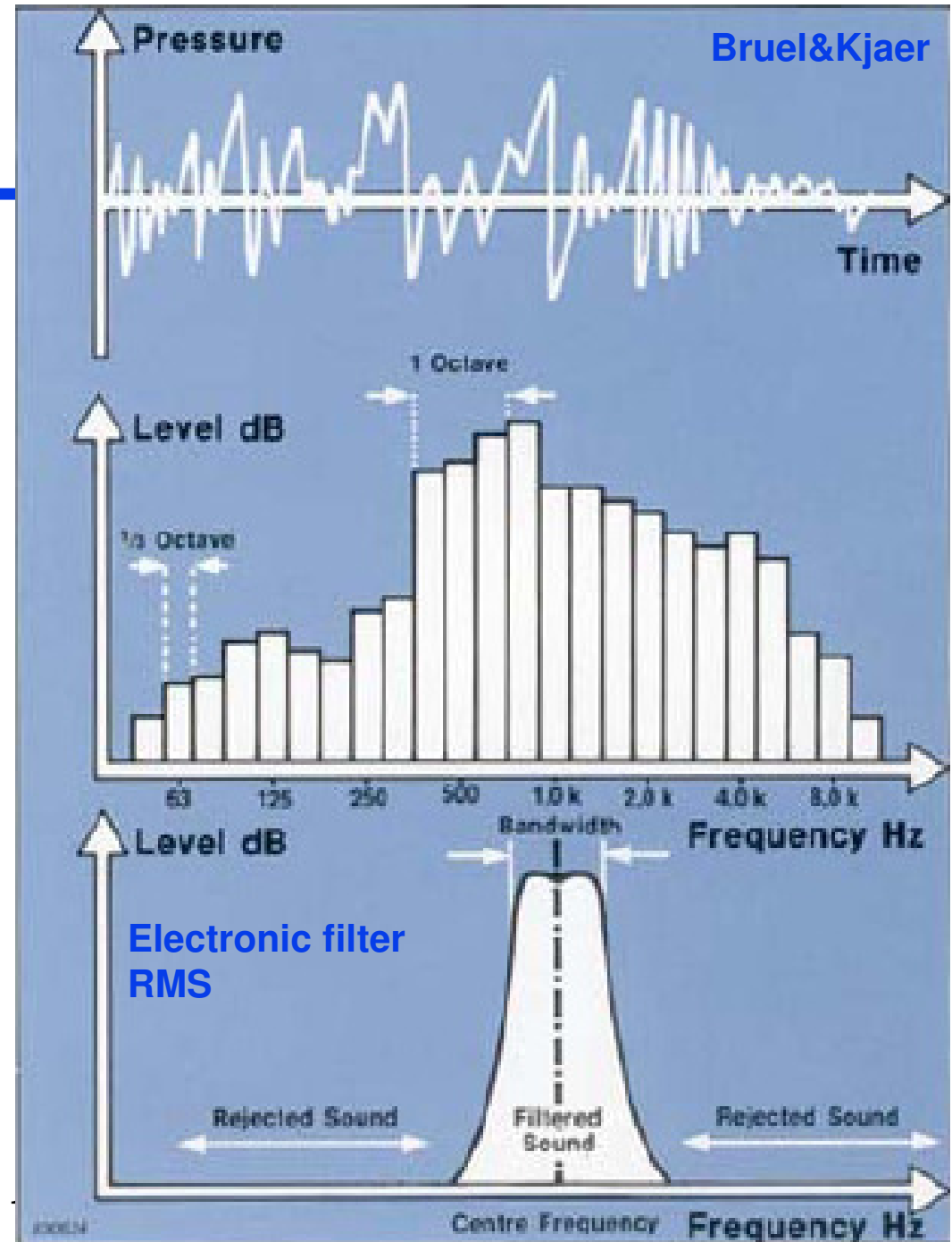
+ 50  
2550 Hz 

500 Hz   
x 1.1

2500 Hz   
X 1.1

550 Hz 

2750 Hz 



# Multiple sound sources

$$L_{p \text{ sum}} = 10 \log_{10} \sum_{i=1}^n (10^{L_{pi}/10})$$

Example:

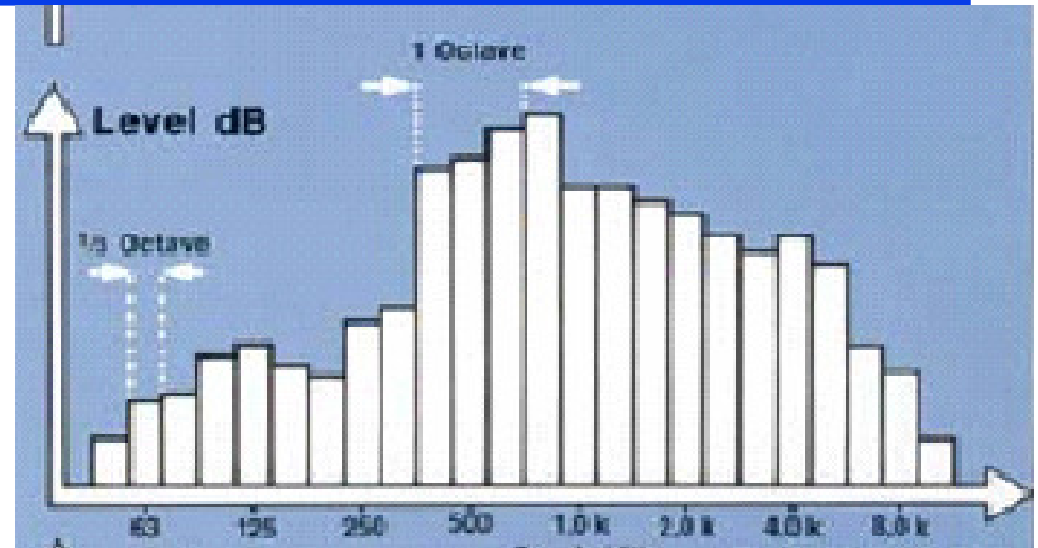
$$65 \text{ dB} + 65 \text{ dB} = 65 + 3 \text{ dB} = 68 \text{ dB}$$

$$10 \times 65 \text{ dB} = 65 + 10 \text{ dB} = 75 \text{ dB}$$

$$90 \text{ dB} + 80 \text{ dB} = 90.4 \text{ dB}$$

$$82 \text{ dB} + 77 \text{ dB} = 83.2 \text{ dB}$$

**Influence of the peaks or wider broadband noise is important**

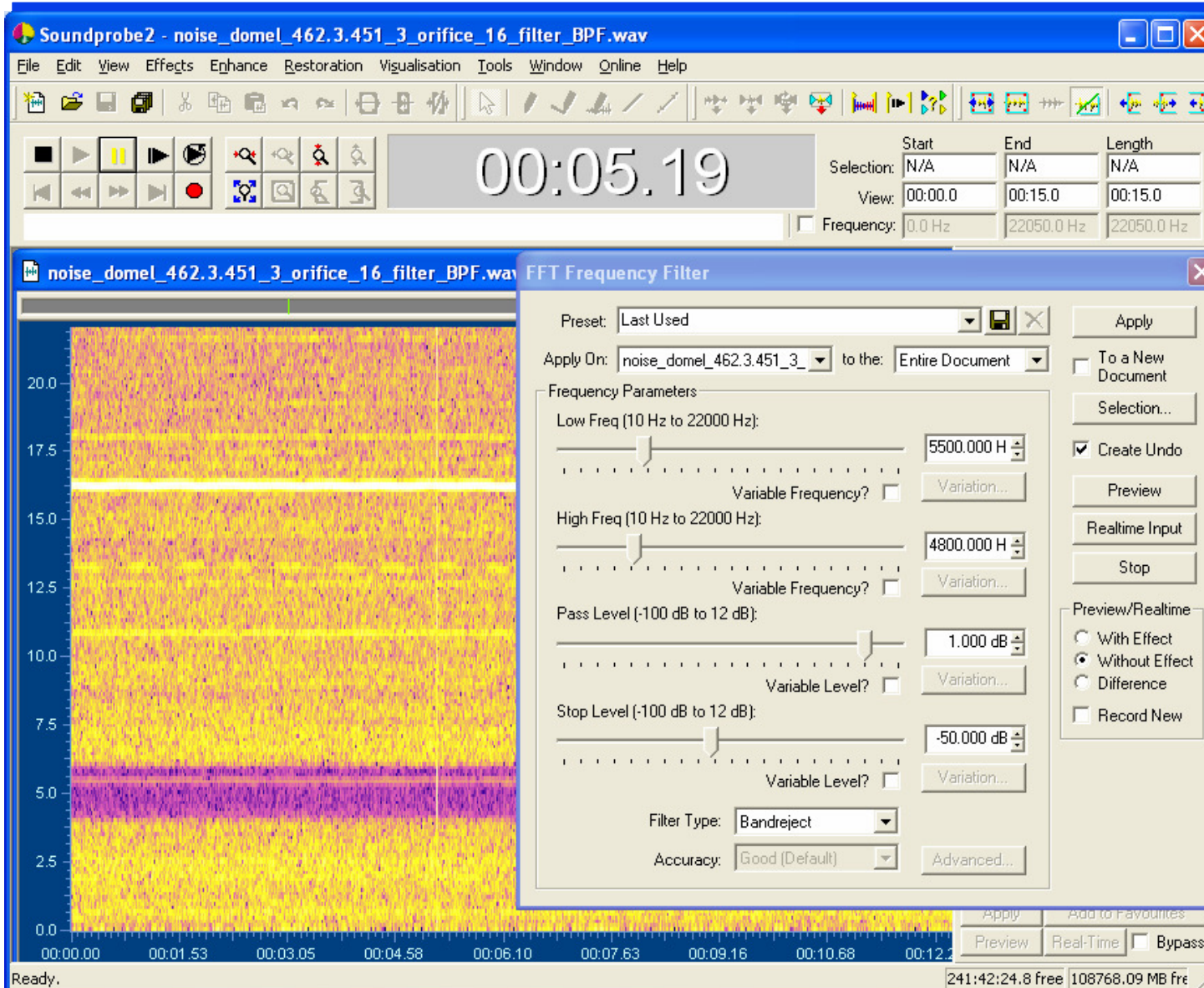


Example:

Noise level	Pressure increase	
20 dB	1000 %	
10 dB	316 %	twice as loud
6 dB	100 %	
3.5 dB	50 %	smallest change we can hear



# Sound quality; editing frequency band filters, special effects



5000 Hz  
Like BPF  
tone



550 Hz



Motor sound



Motor sound  
+ BPF filter



Vacuum cleaner  
(broadband sound)



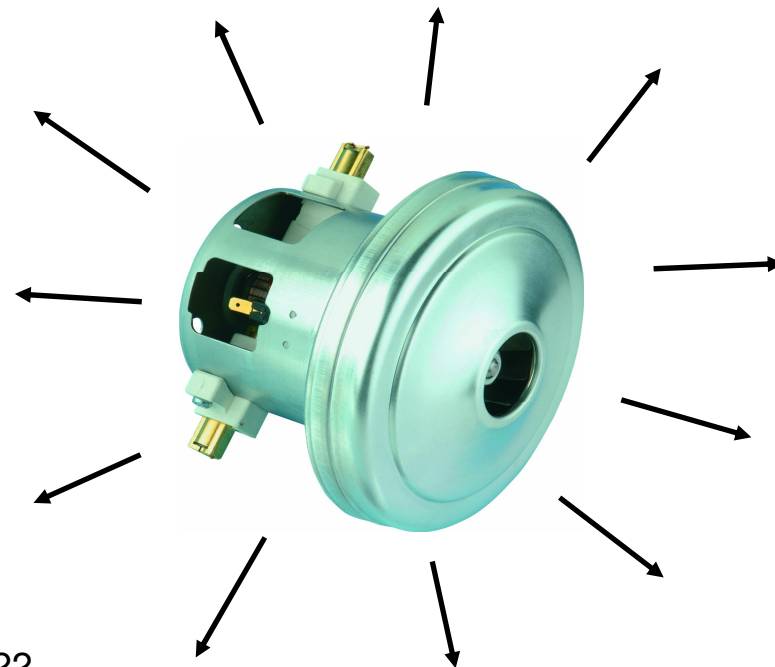
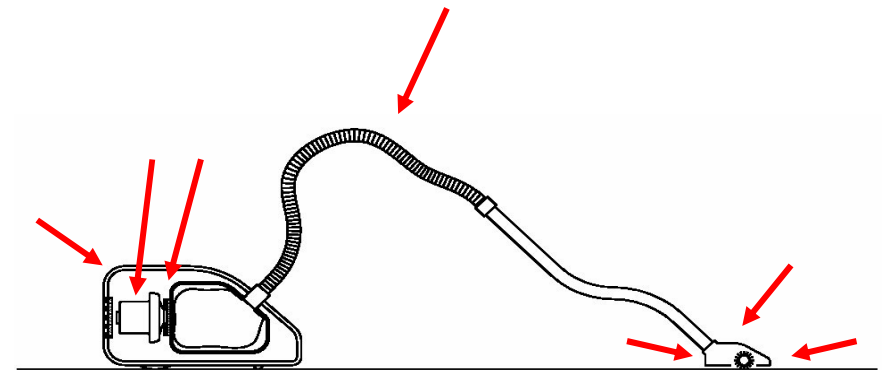


# Noise sources on Vacuum Cleaner

- vacuum cleaner motor
- vibrations of the vacuum cleaner housing
- not optimized flow channels, flow distortion
- motorized power nozzle
- high velocities of air at the intake

## *VC Motor noise sources:*

- *Aero-acoustic reasons,*
- *vibrations of the VCM structure,*
- *mechanical reasons (sliding contact between brush and commutator, bearings...)*
- *electromagnetic reasons,...*

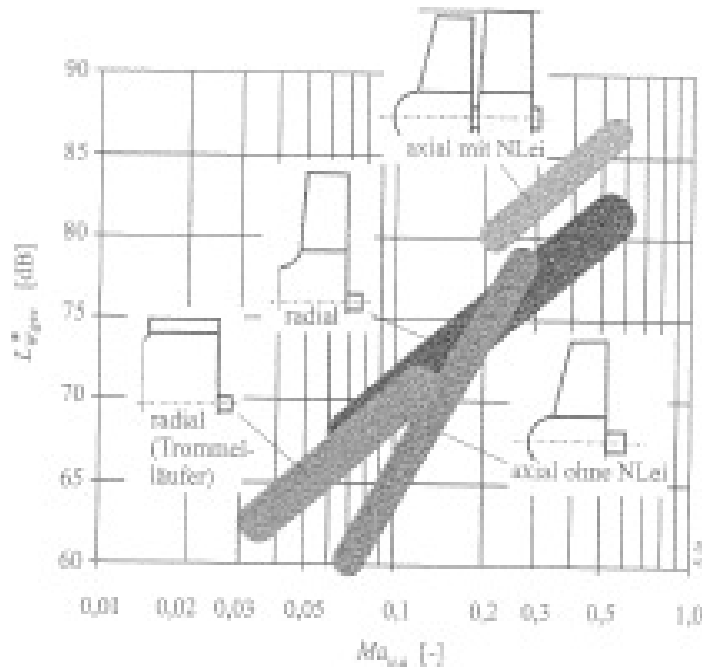


# $L_w$ – Noise power level

$$L_w = f \left( V/t * dp * M^m (Pi * D * n / c_o) \right) \text{ [dB]}$$

$$P = V/t * dp \quad \text{airflow power [W]}$$

$V/t$  - Airflow,  
 $dp$  - Pressure difference  
 $M$  – Mach number (speed)  
 $m$  - Fan type

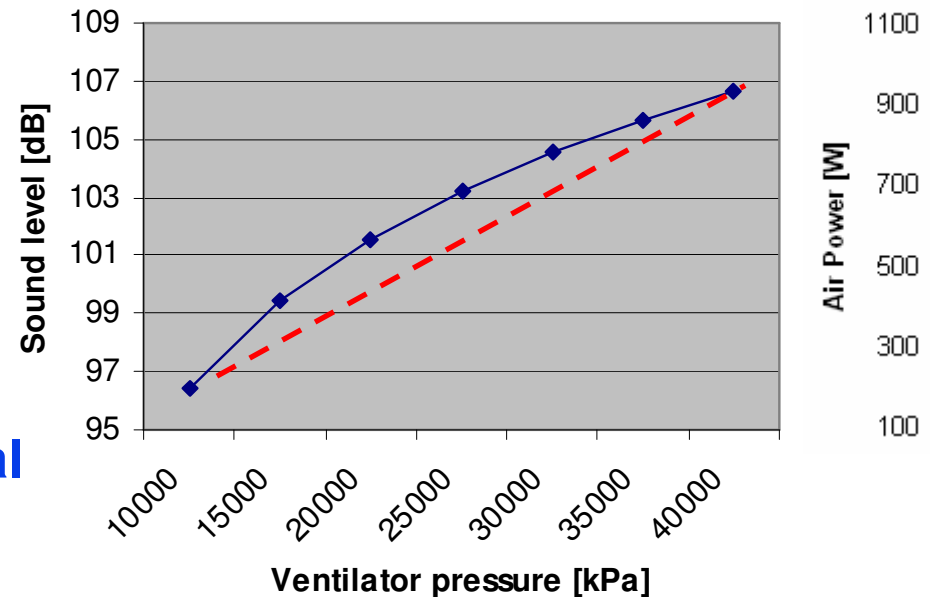


—●— Noise level [dB]

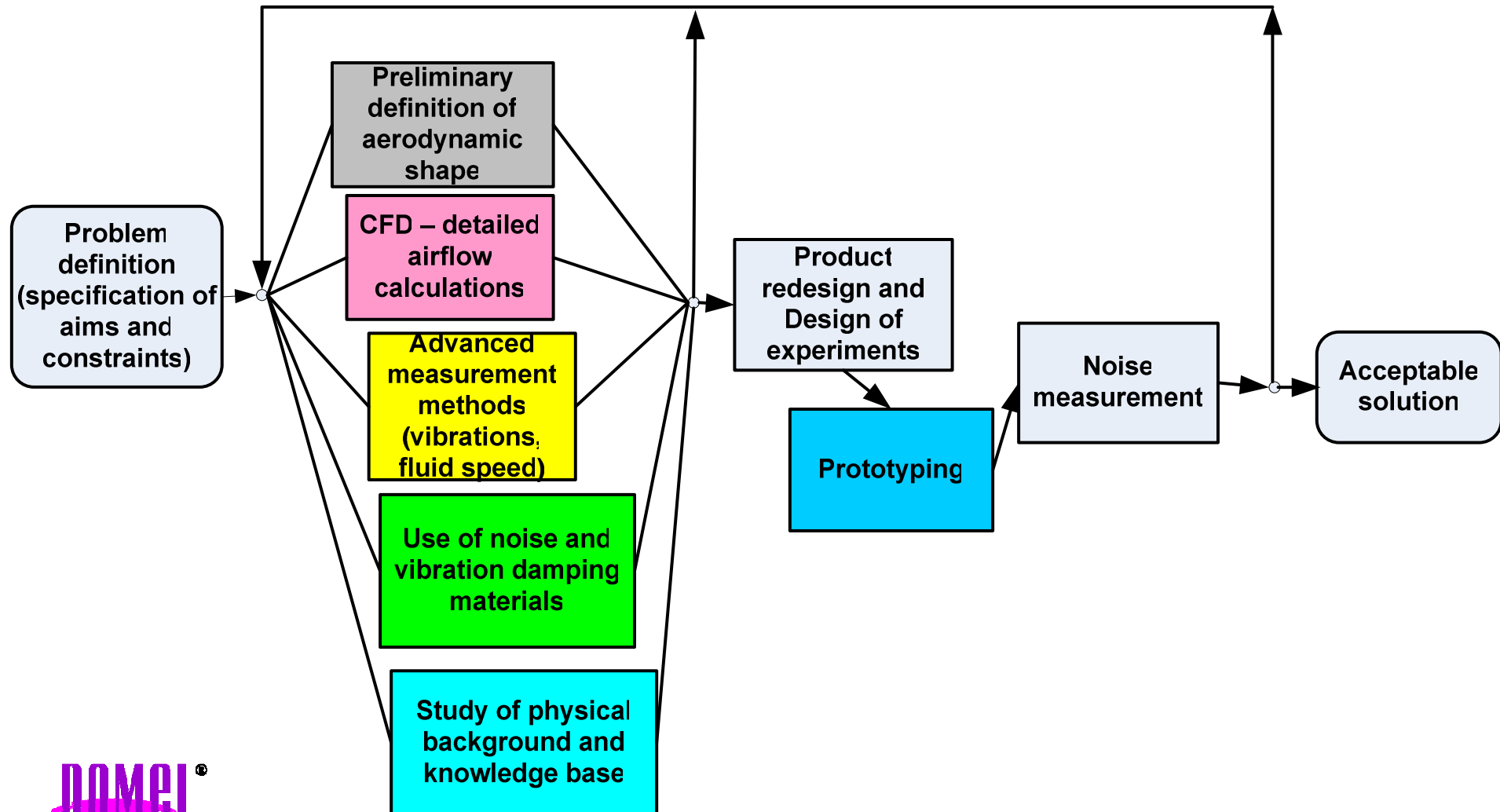
--- Air Power

Centrifugal  
blower

How sound depend on ventilator pressure  
at  $q=25$  l/s and  $n=40000$  RPM



# Integrated approach to noise reduction



# Noise sources

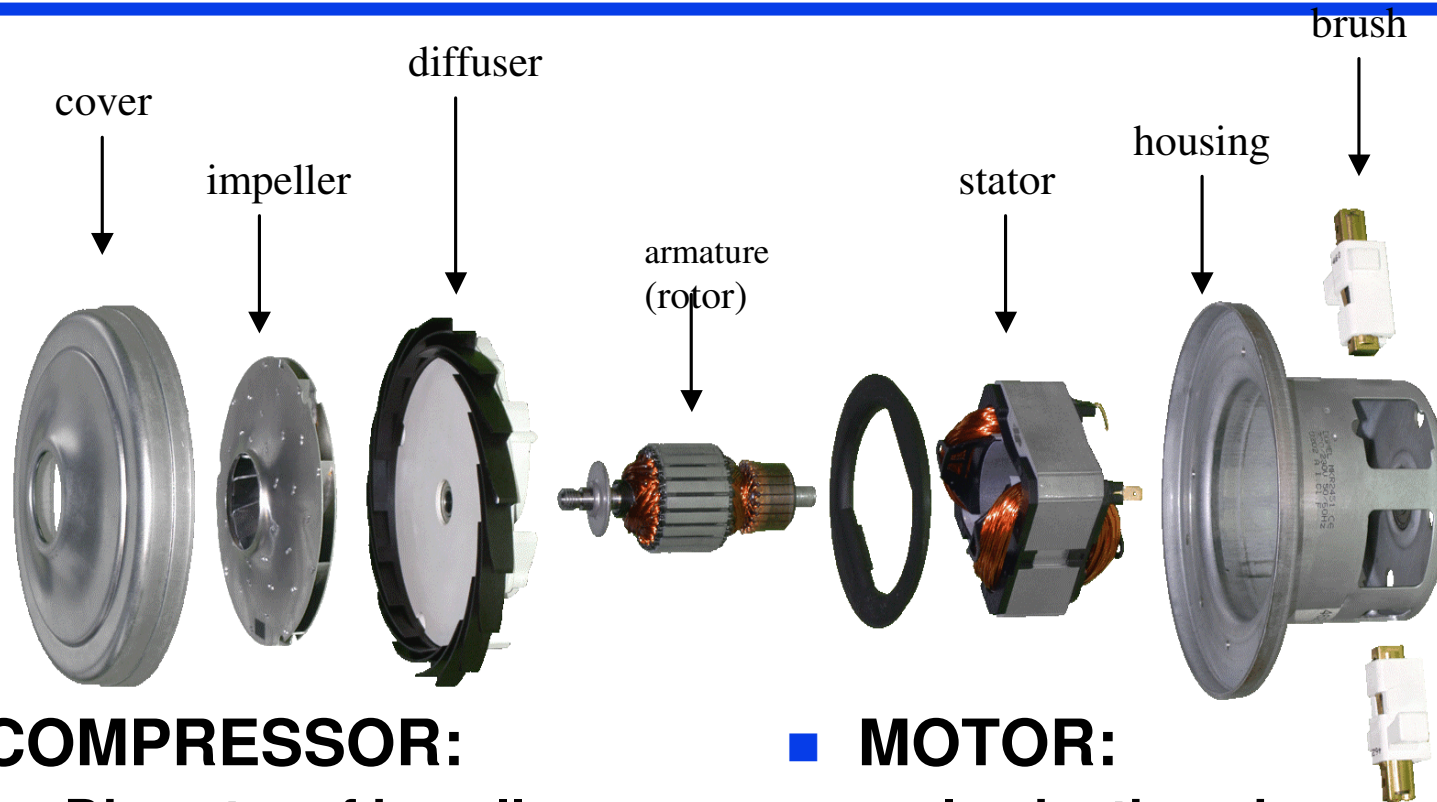
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## Structural born noise:

- **Case study: vibrations of the vacuum cleaner cover**
- **Run up analyses**
- **Modal analyses**
- **Vibrations damping**



# Parts of Vacuum Motor



## ■ COMPRESSOR:

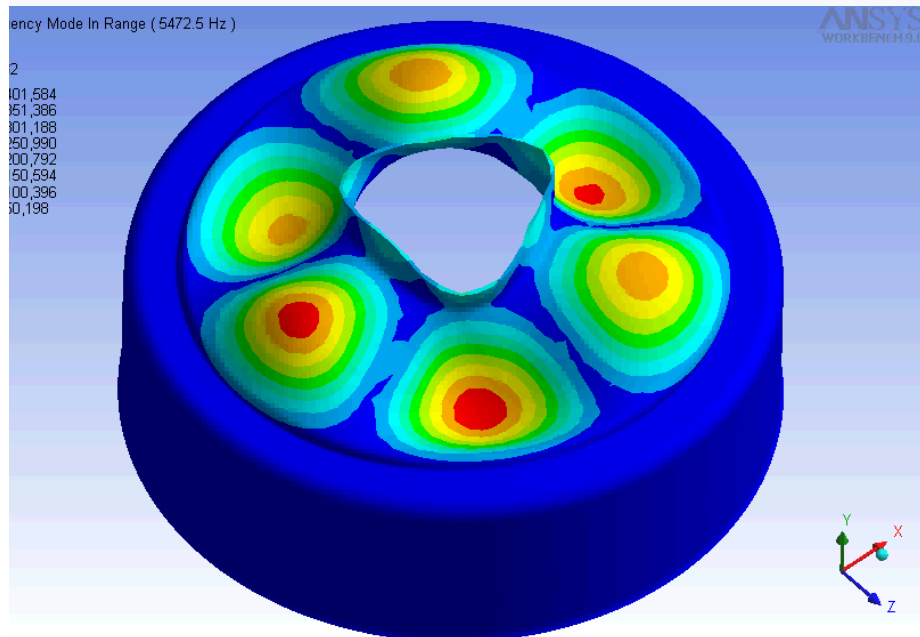
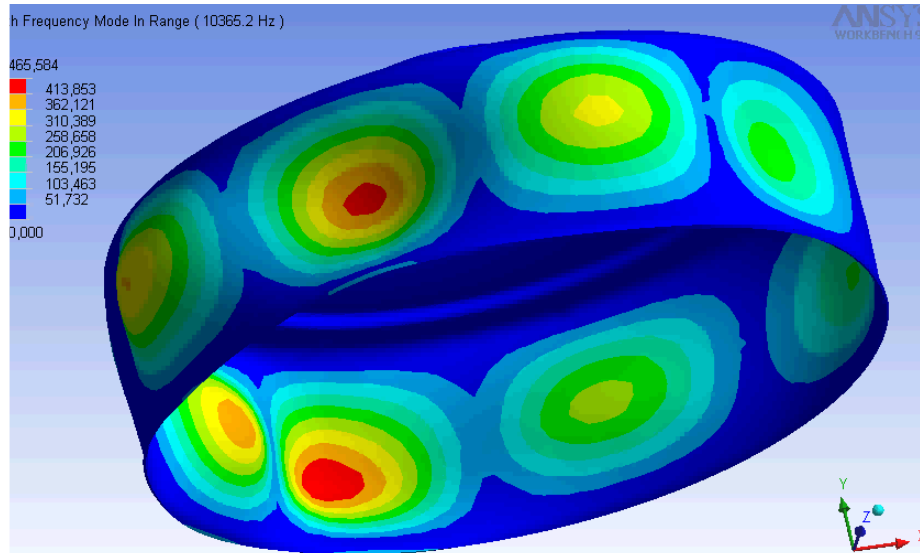
- Diameter of impeller
- number of stages
- impeller outlet width
- with/without diffuser

## ■ MOTOR:

- lamination size
- height of the stack
- winding

**50.000 RPM – concentrated power**

# Sound power calculation of structural borne noise from vibration level and surface size (ISO 7849)



$$W(f) = \rho c v^2(f) S \sigma(f)$$

$$L_W = 10 \log \frac{W}{W_0} \quad \sigma = 1 / \left( \left( 1 + 0.1 \frac{c^2}{(fd)^2} \right) \right)$$

$$d = \sqrt{\frac{S}{\pi}}$$

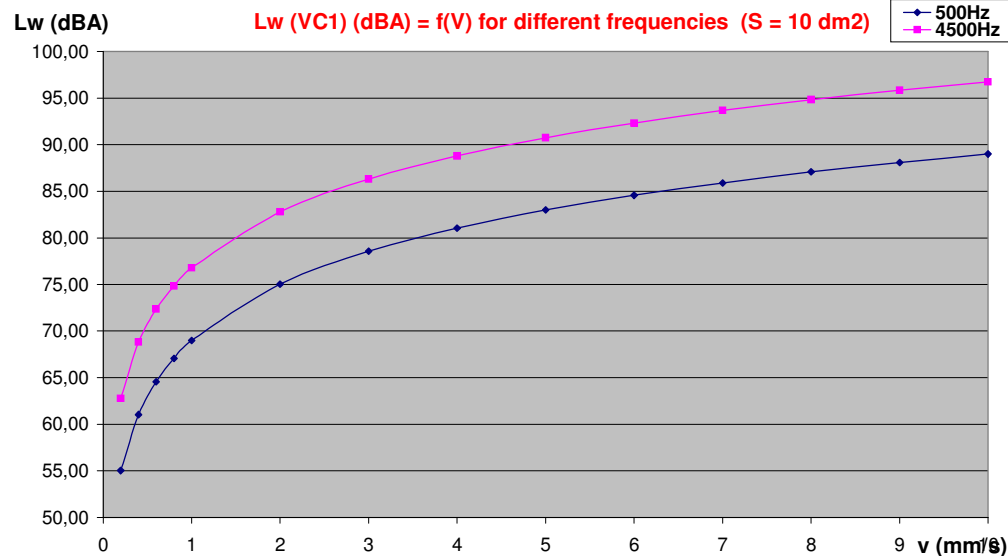
- W(f) - sound power at specific frequency (W)
- $\rho$  - air density (1,2 kg/m<sup>3</sup>)
- c - speed of the sound (340 m/s)
- $v^2(f)$  - vibration level at particular frequency (m/s)
- S - surface size (m<sup>2</sup>)
- f - frequency (Hz)
- $\sigma$  - surface dissemination factor
- L<sub>w</sub> - sound power level in dB
- W<sub>0</sub> - reference sound power (1 pW)

- Resonance on the motors cover at BPF
- FEM calculation (Boundary conditions)

# Sound power Lw calculation Influence of the surface size - S

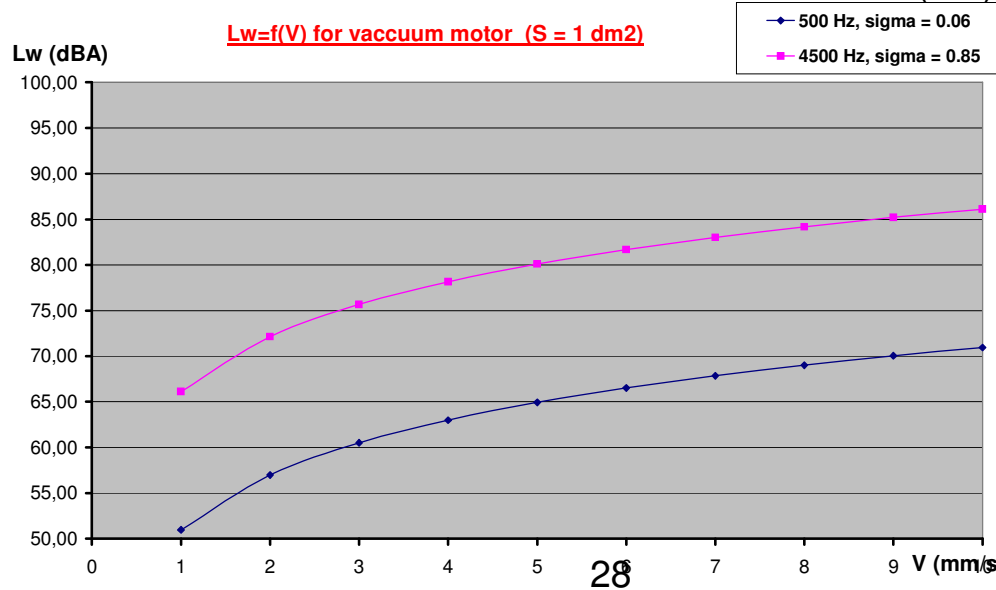
BPF  
4500 Hz

Rotation  
speed  
500 Hz



S = 10 dm<sup>2</sup>

Vacuum  
cleaner

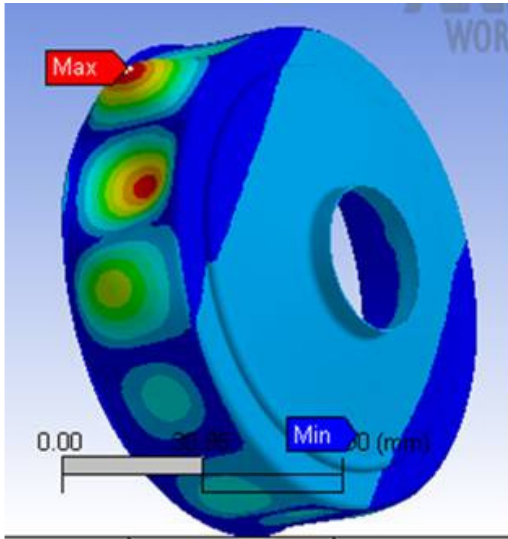


S = 1 dm<sup>2</sup>

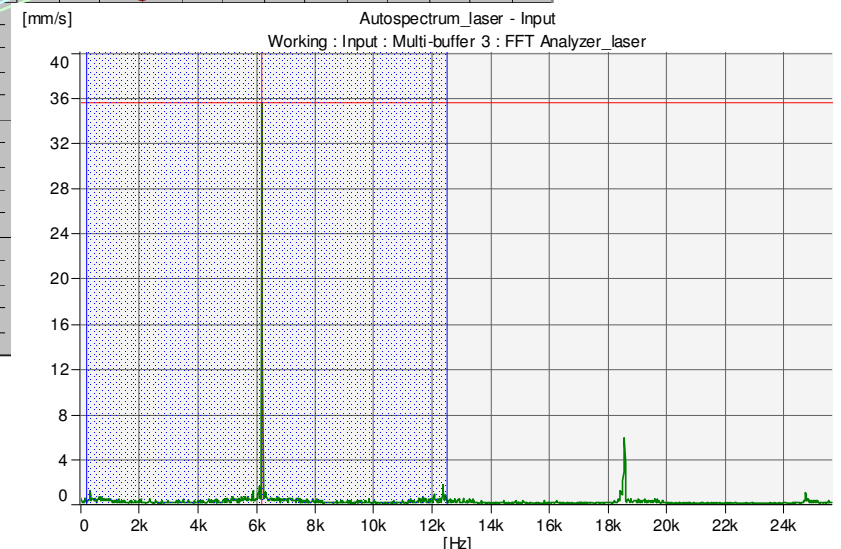
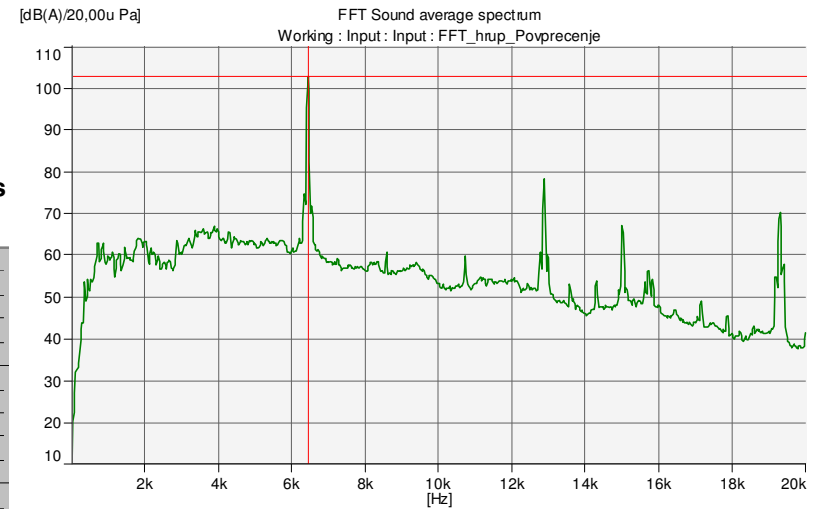
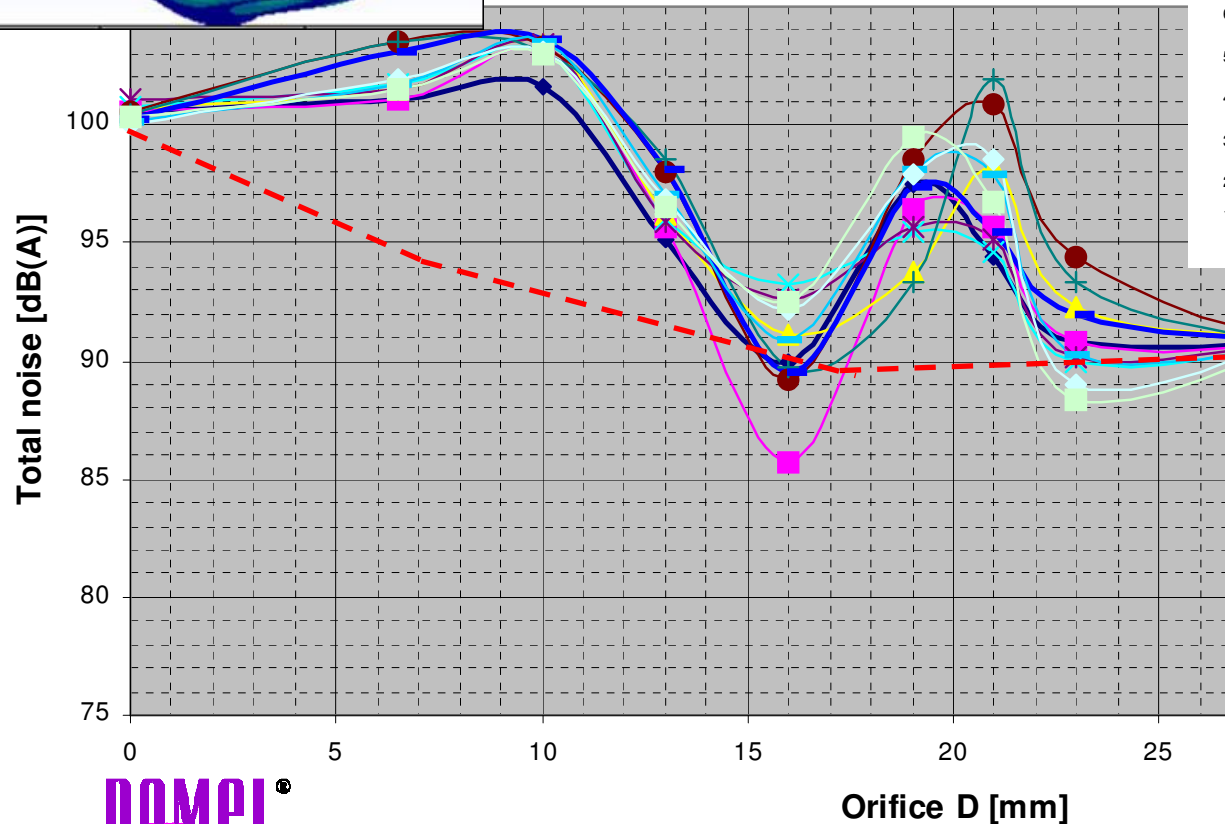
motor



# Total noise level in the relation to the airflow – typical example of the motor with a resonance



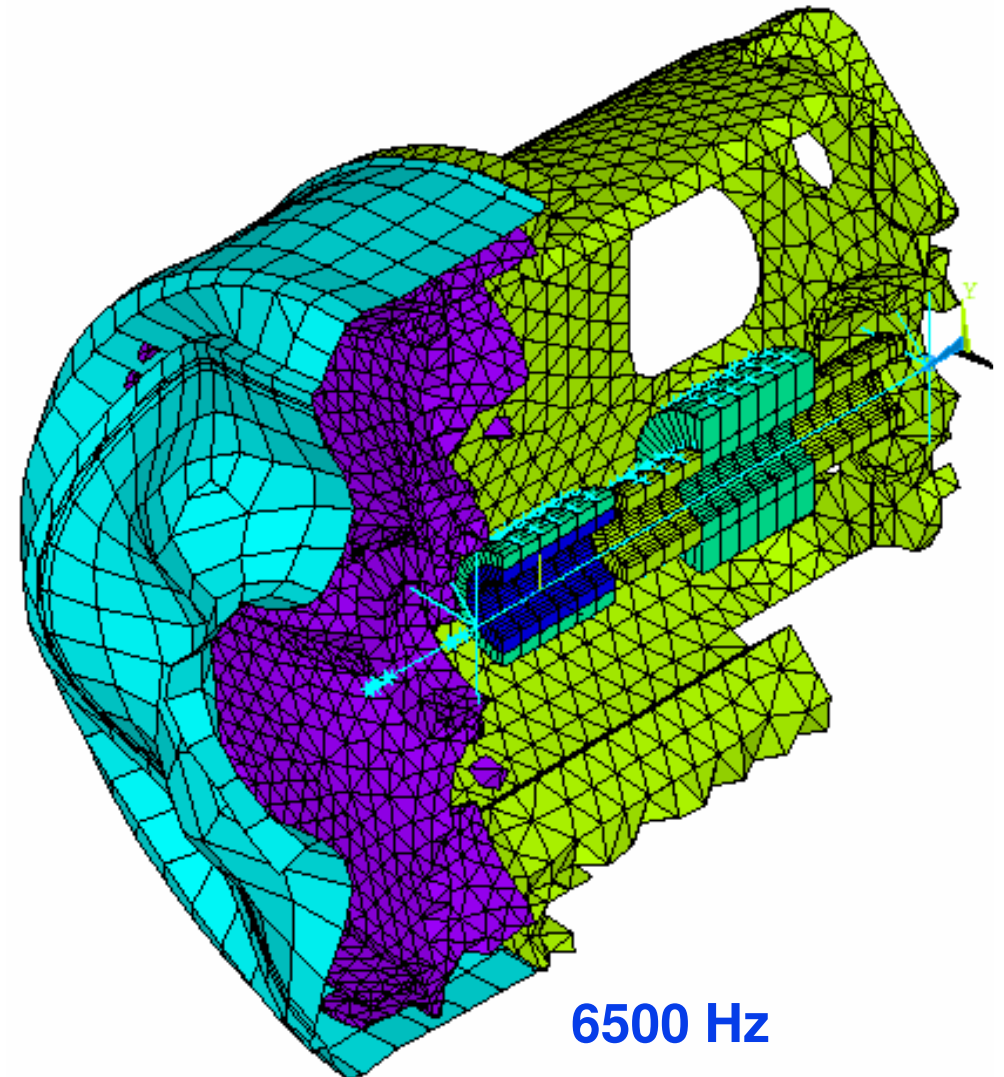
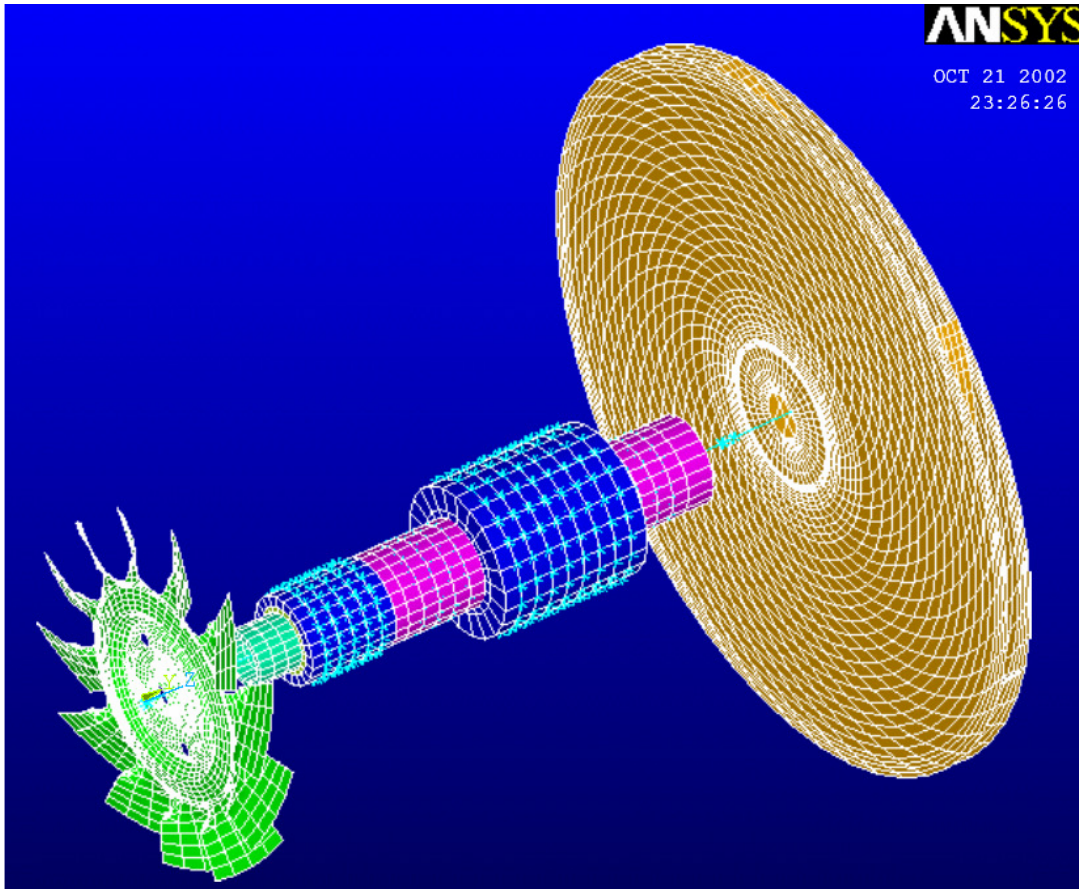
Total noise \_463.3.201\_serija 500 kos





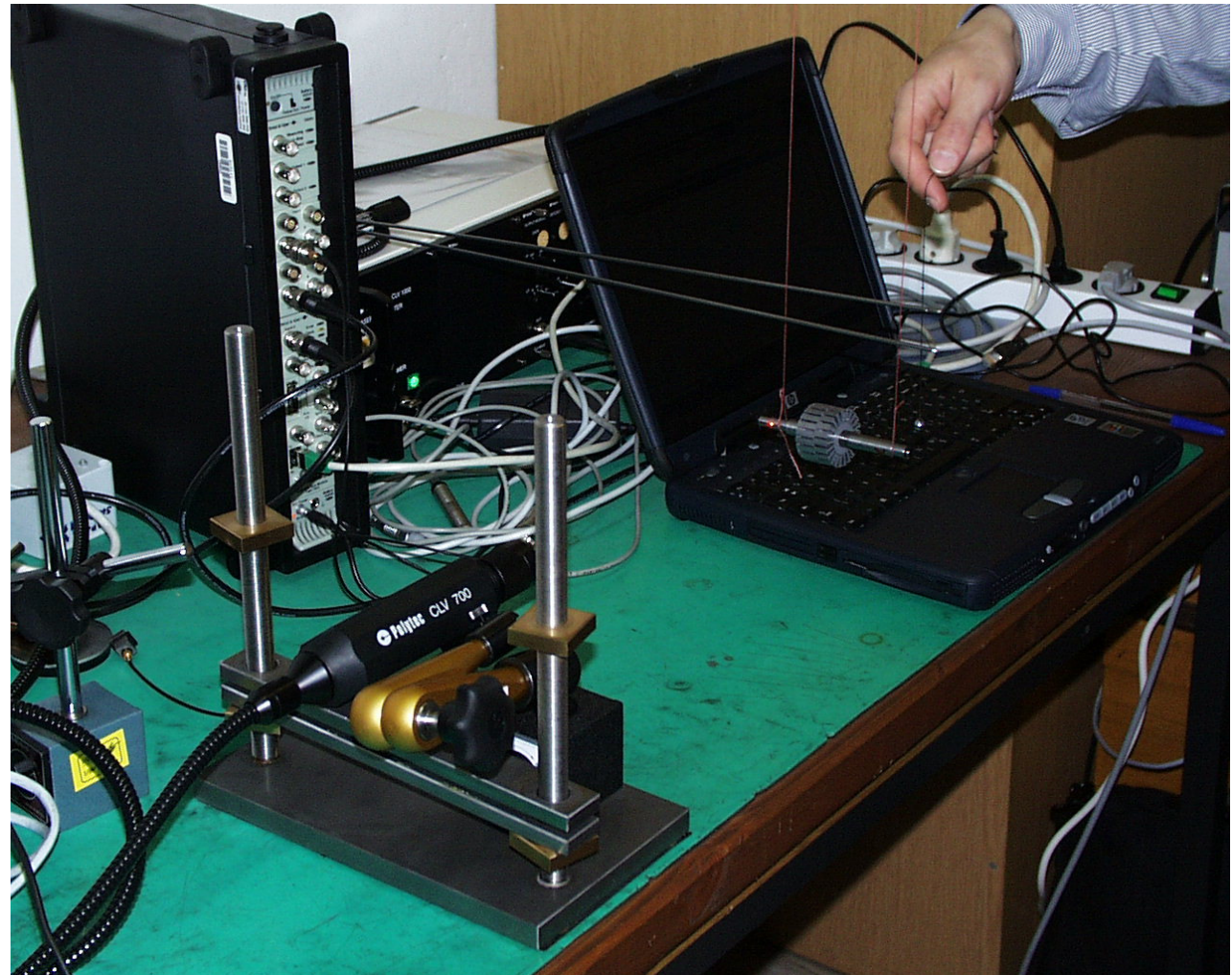
# Numerical Simulations

## Mechanics (LADISK, FS)



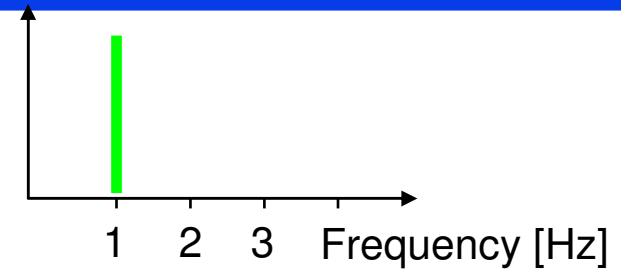
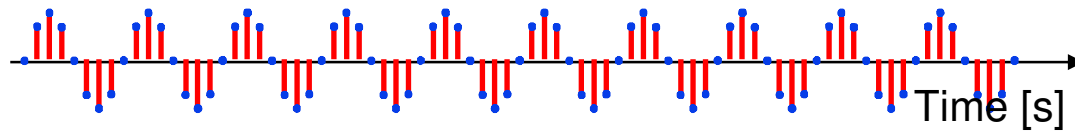
# Measurements: Laser vibrometer

- Bruel&Kaer Pulse system
- Contact less laser measurements of vibrations
  - Small parts
  - During rotation



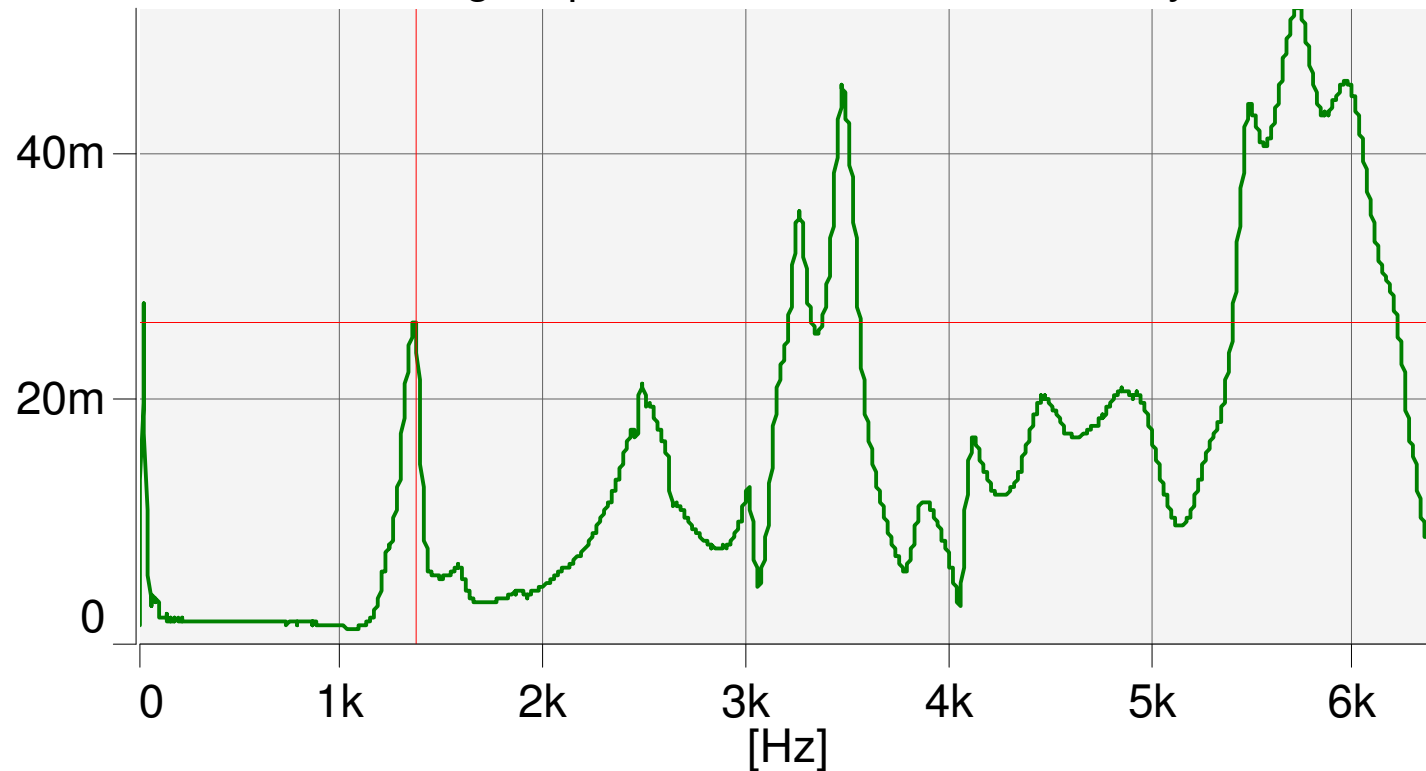
# Frequency spectrum - FFT

Response in time domain.

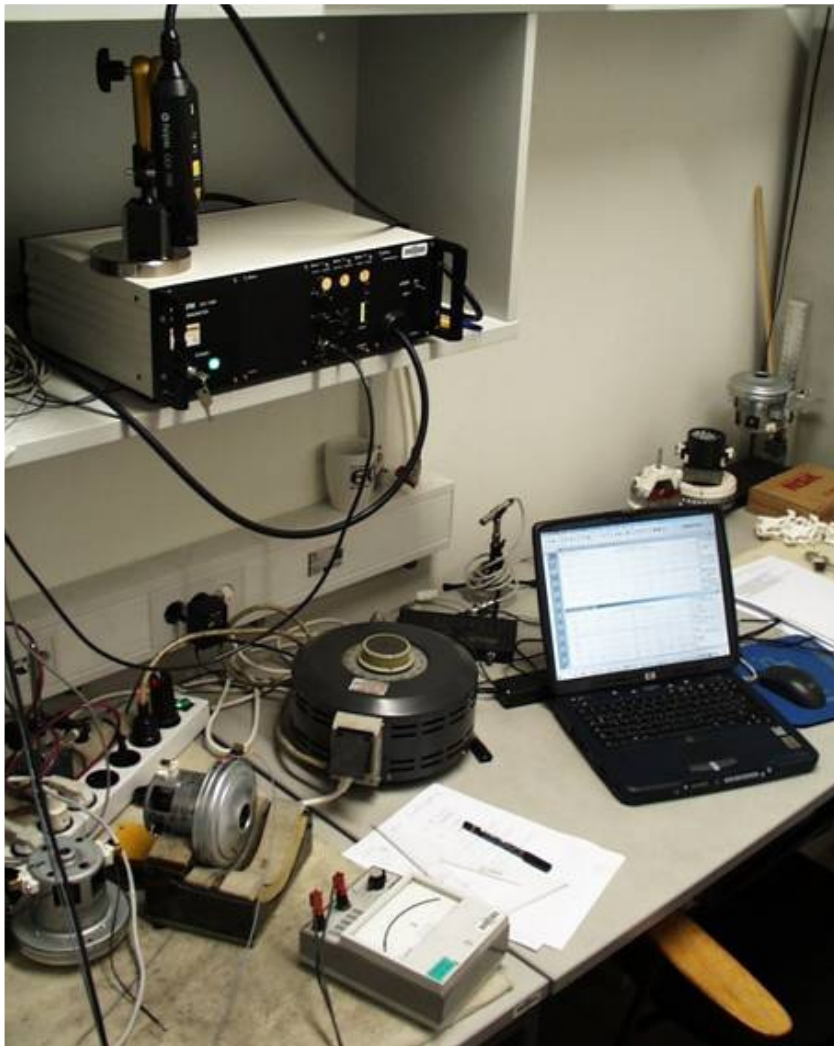


[m/s<sup>2</sup>]

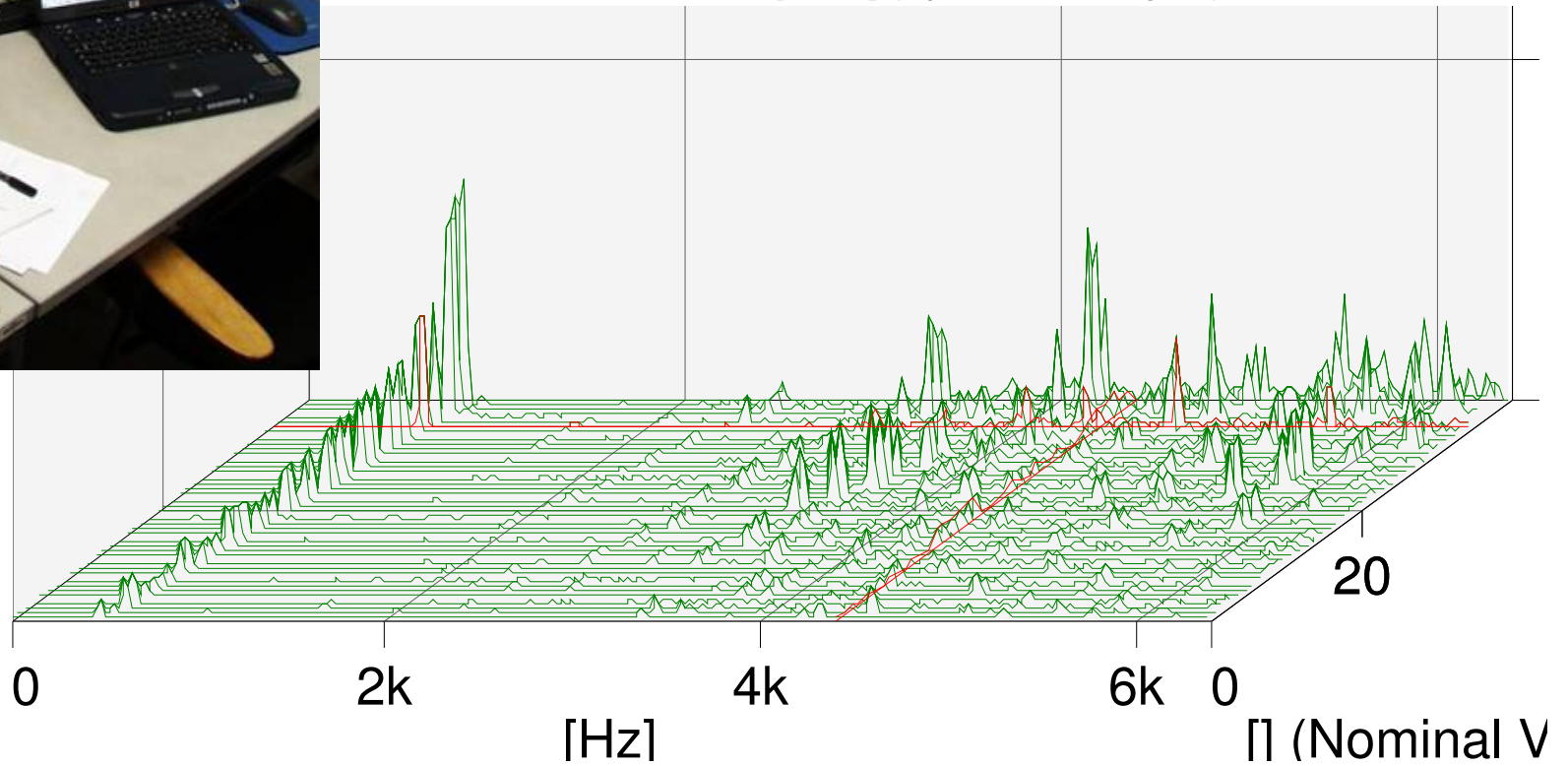
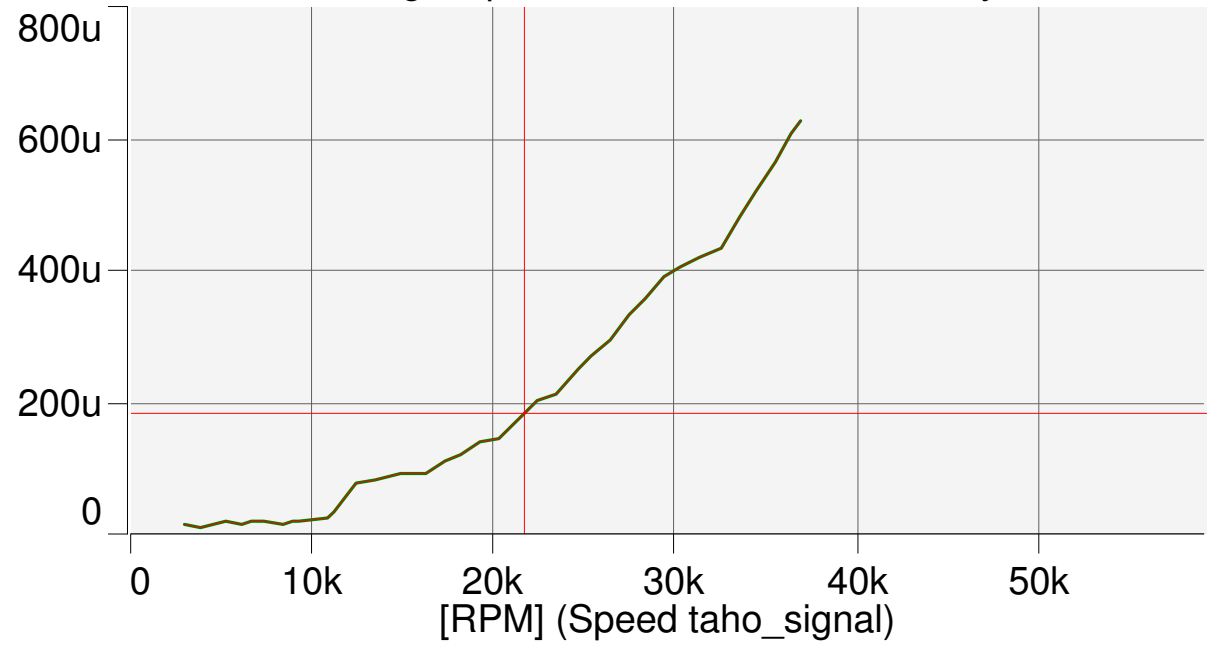
Autospectrum(vibracije\_1)-Multy\_buffer  
Working : Input : Multi-buffer 1 : FFT Analyzer







working : Input : Multi-butter 1 : FFT Analyzer

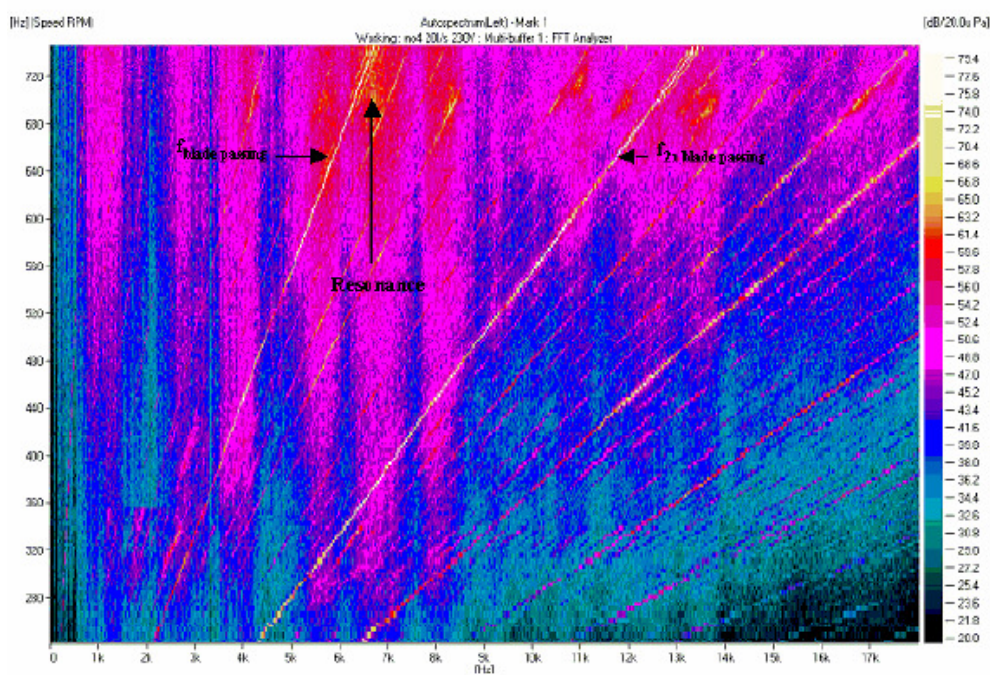


Run up  
analyses

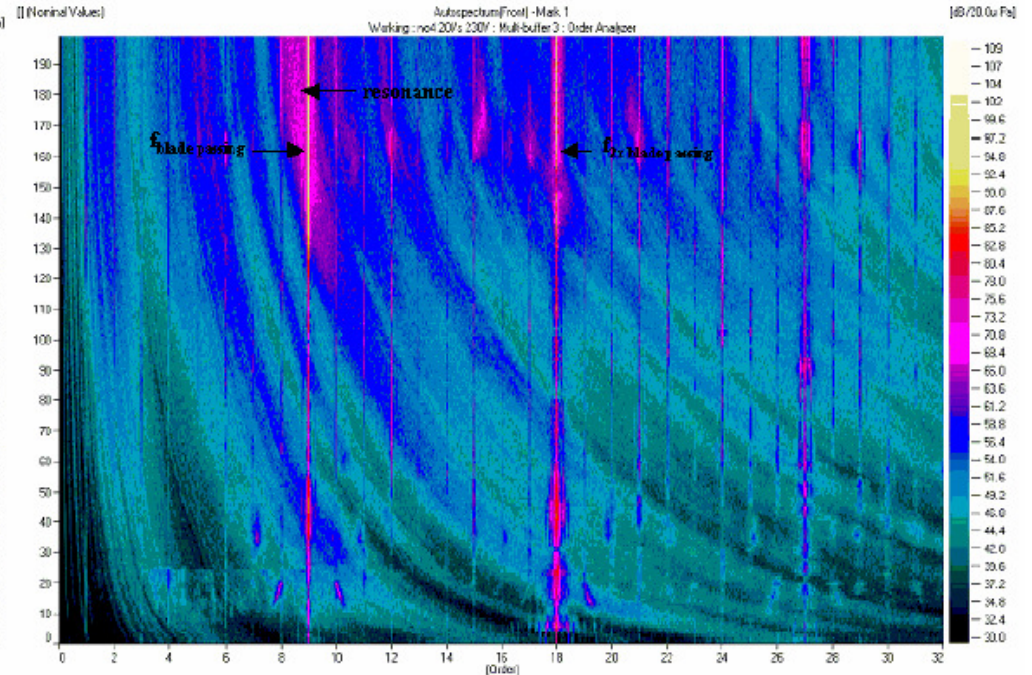


# Run up analysis to determine possible resonances

Sound pressure spectrum as  
a function of frequency (x-axis) and  
speed (y-axis)

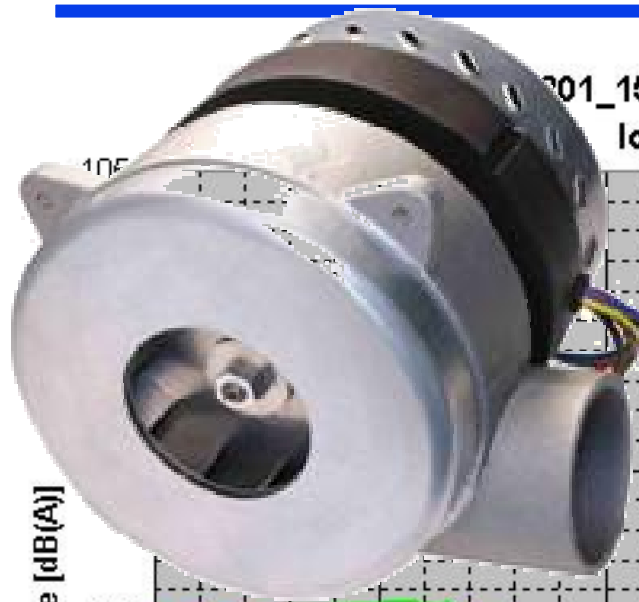


Order tracking analysis  
Harmonics – x axis

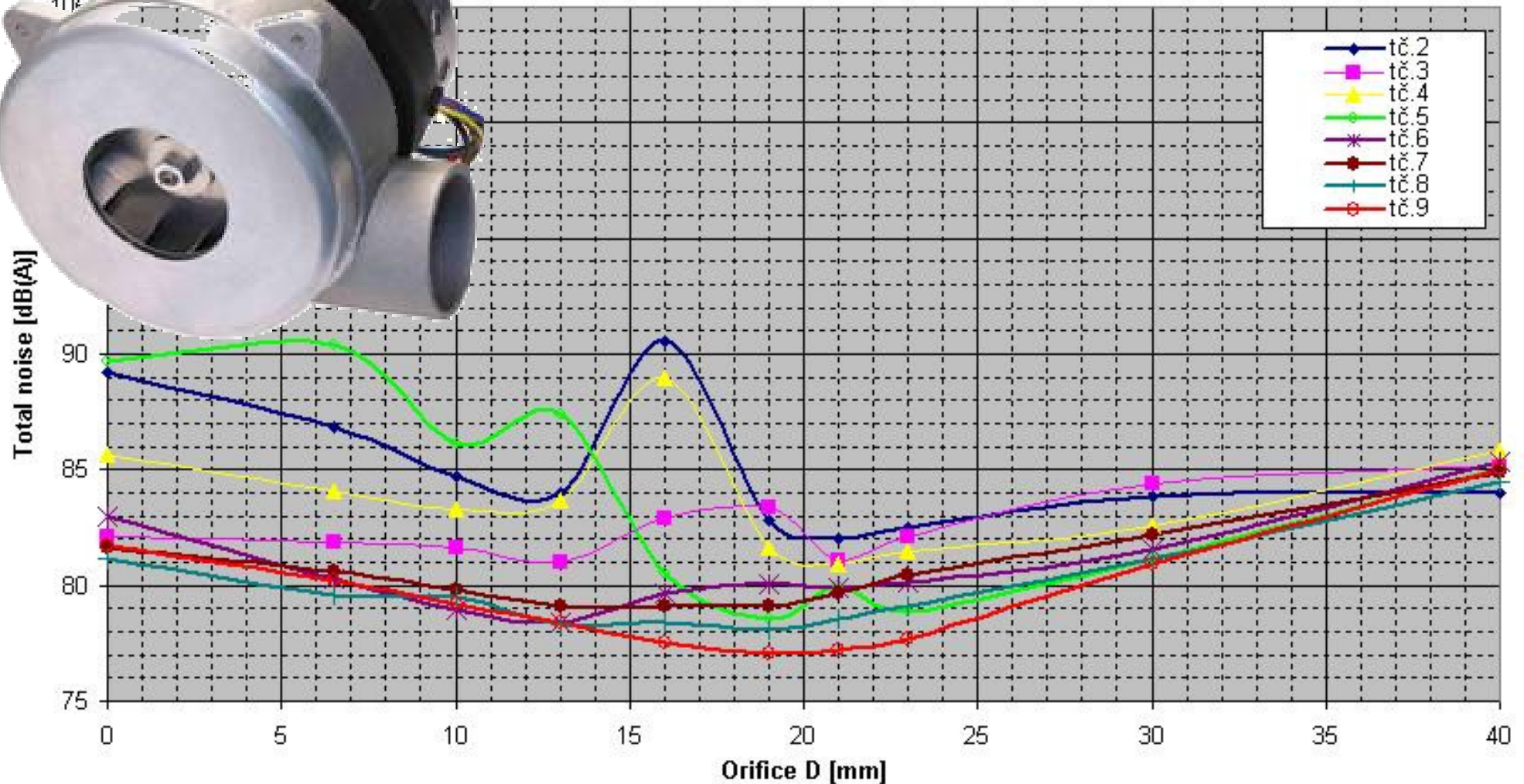




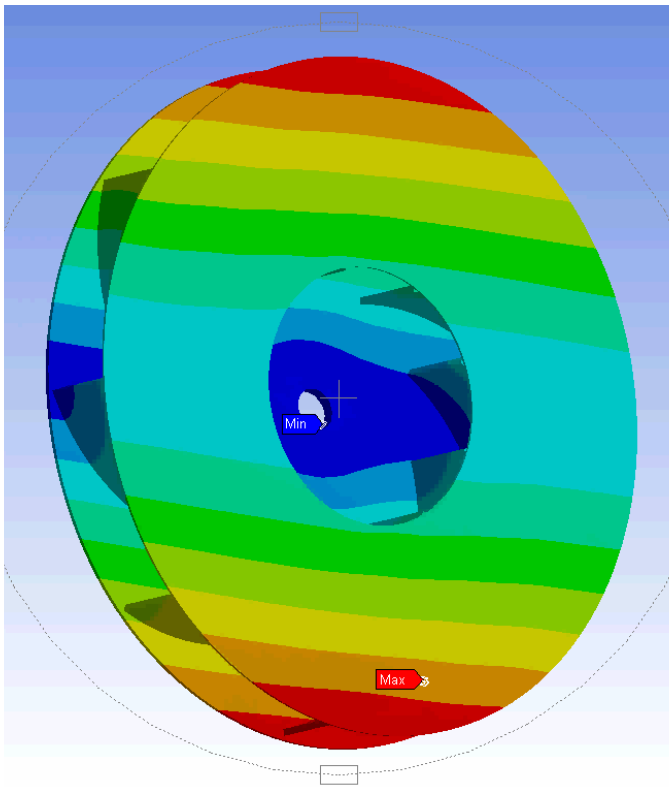
# Case study: impeller resonance



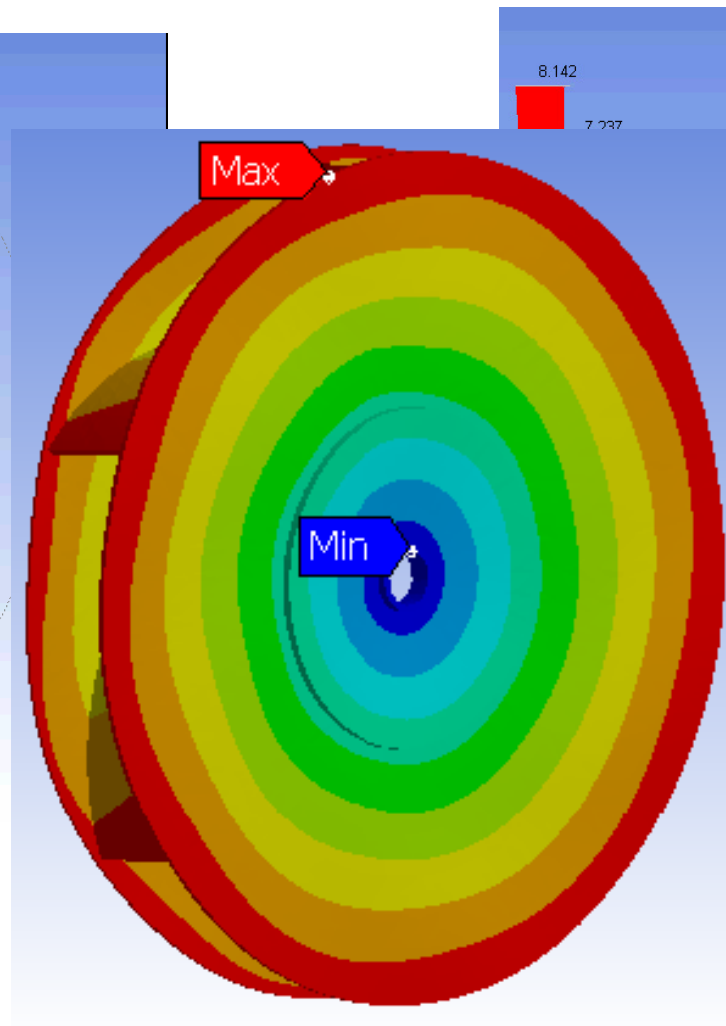
001\_150V\_CEV PROTI MIKROFONU\_tč.9\_kolo 6 in 6 lopatic,povratni vod\_10  
lopatic\_vmesna tulka in podložke+ silikon črni



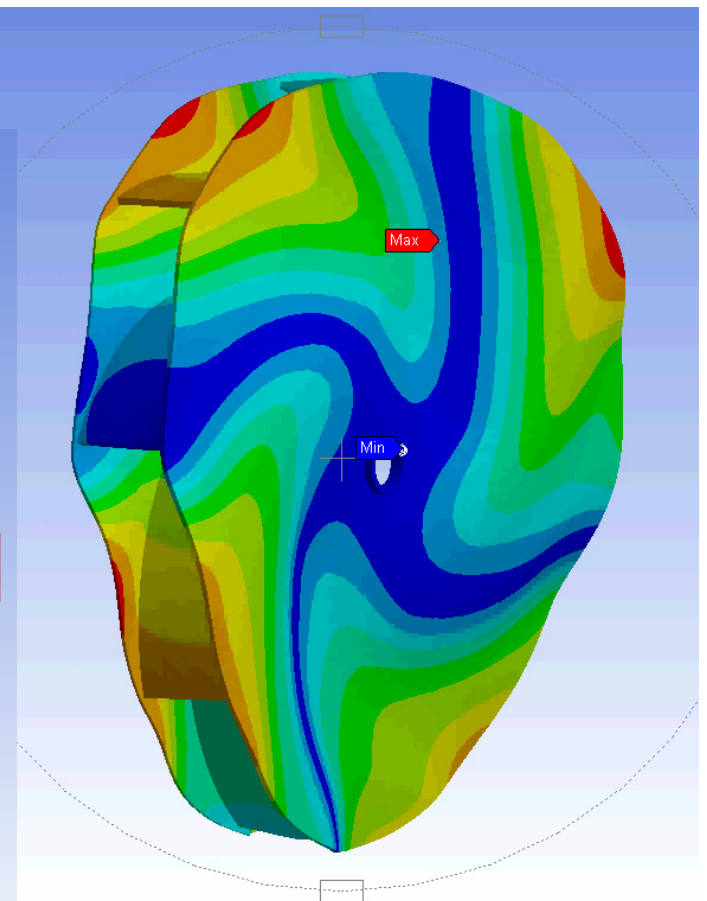
# Impeller natural modes of vibrations



1. mode: 350 Hz

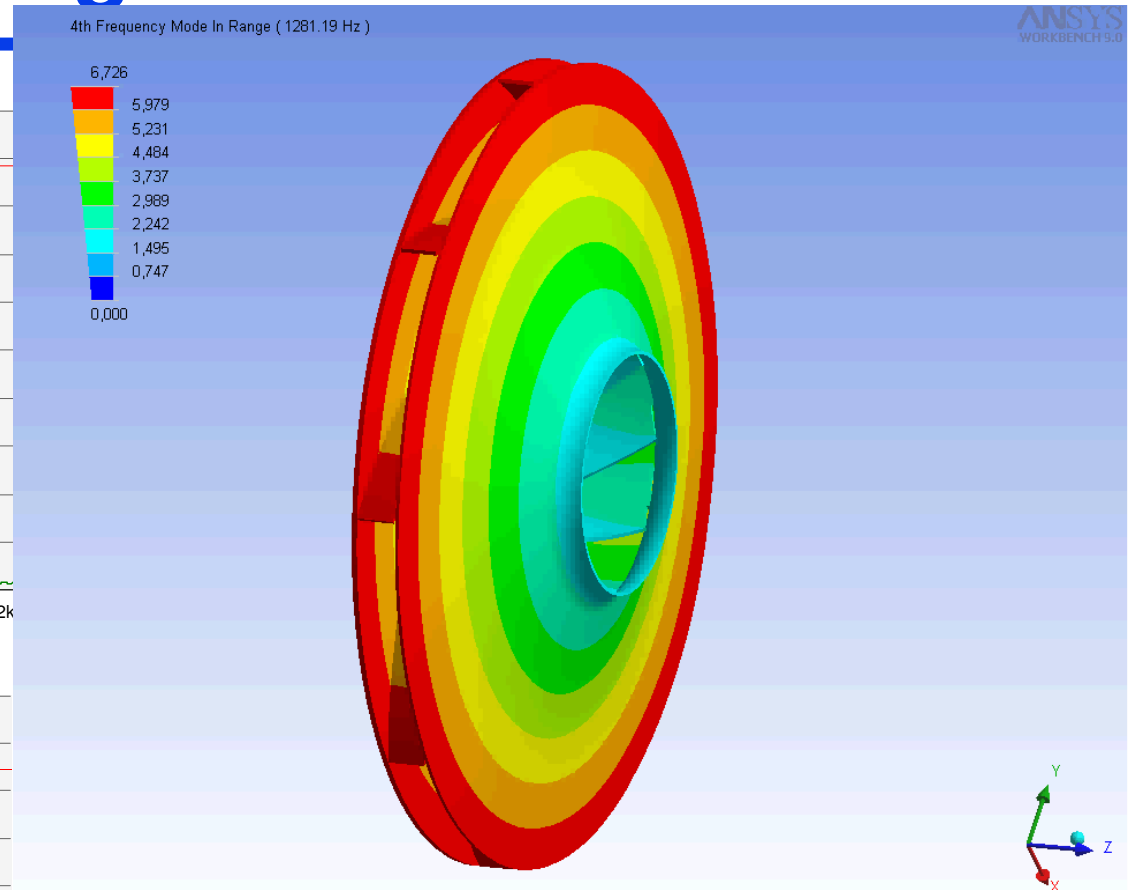
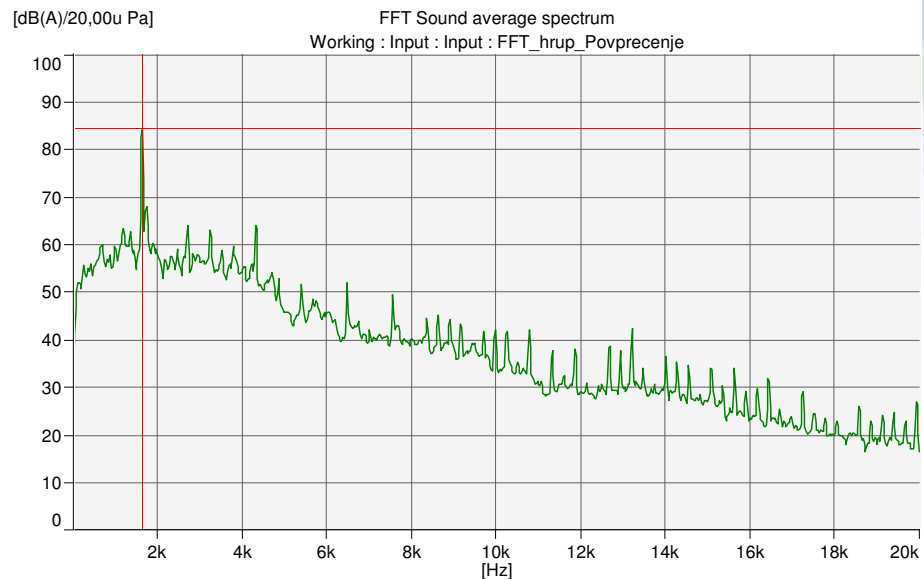
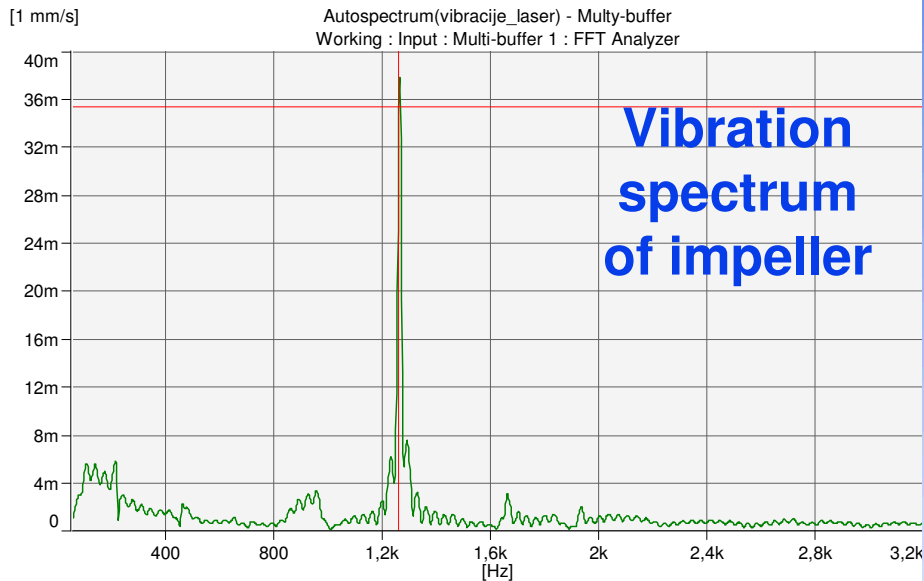


3. mode: 1280 Hz



5. mode: 2670 Hz

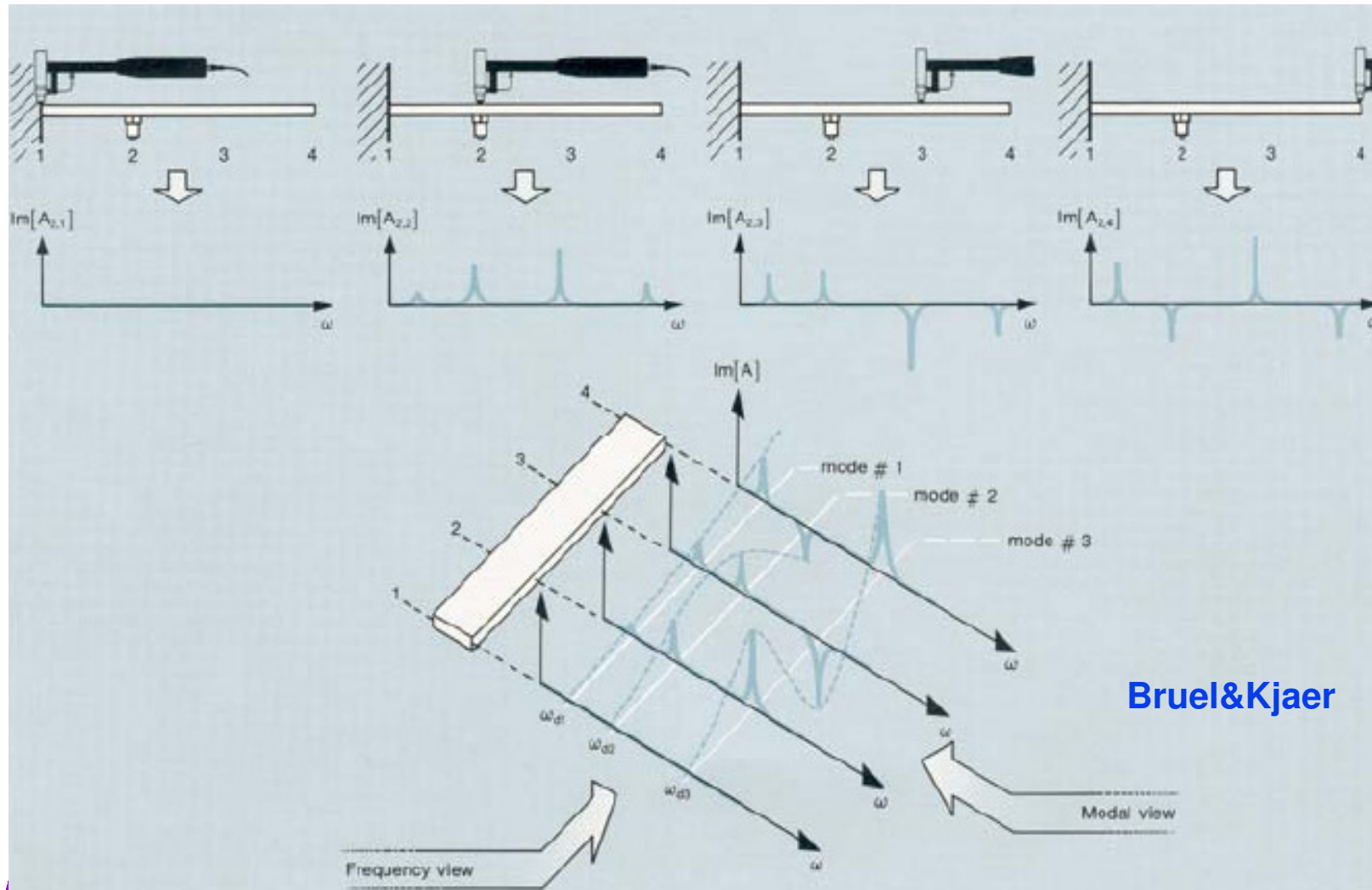
# Vibrations spectrum of impulse excitation in tangential direction



**Sound Spectrum of the EC motor**

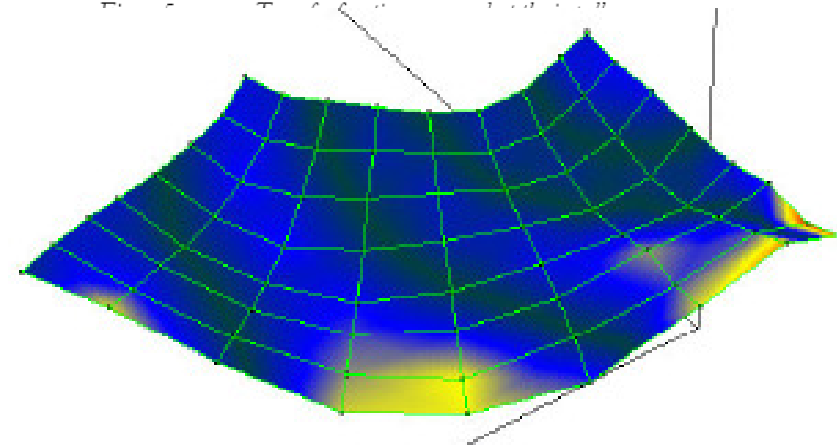
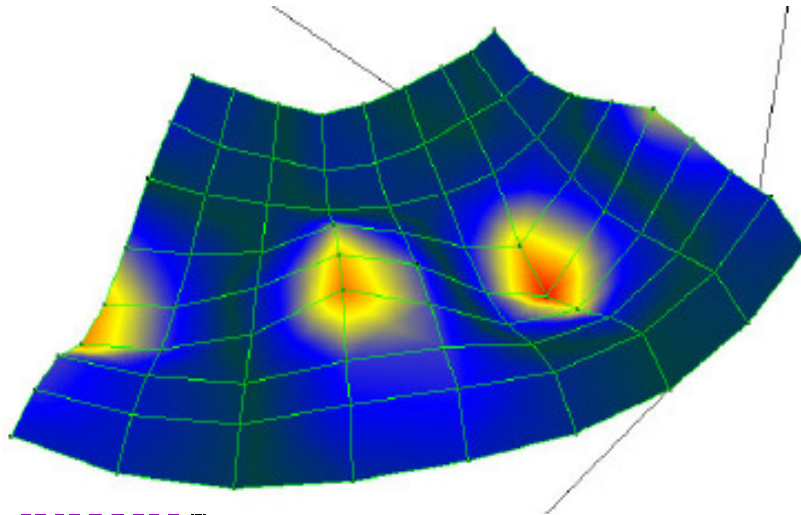
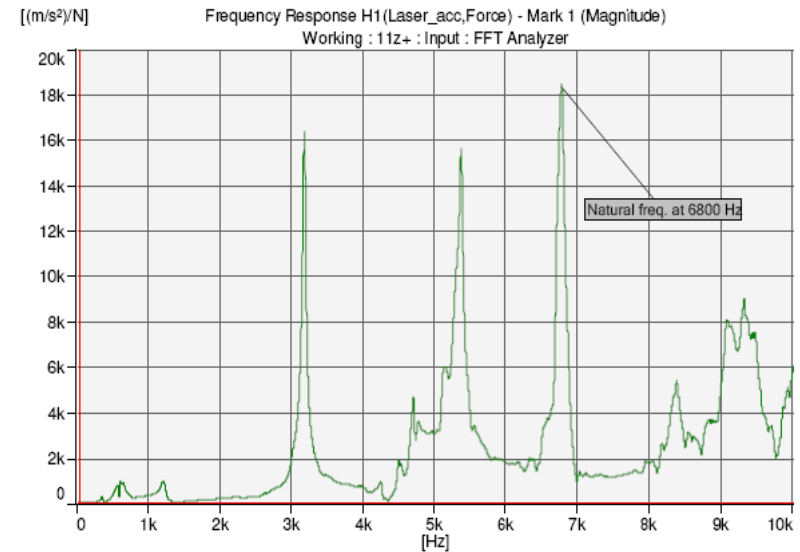
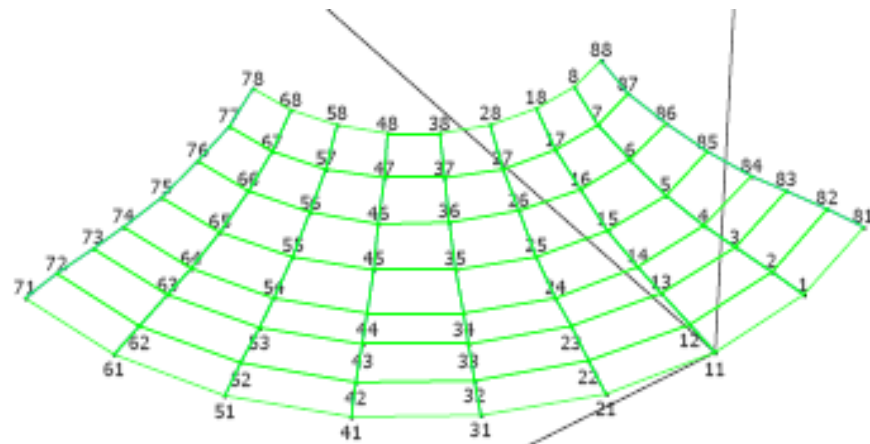
**Brushless or EC motor has six moment pulses per one revolution  
It is an excitation force**

# Modal analyses I



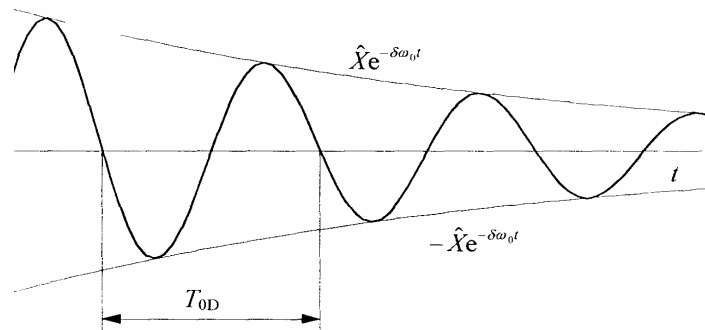
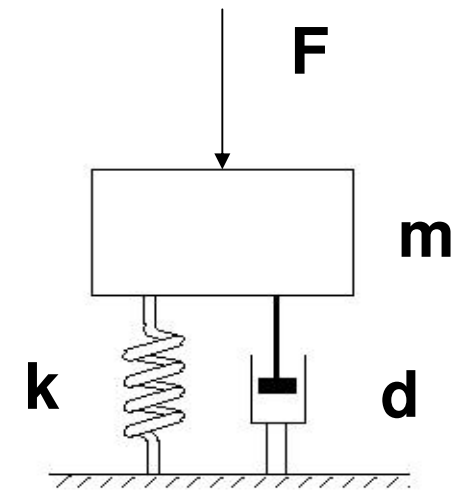
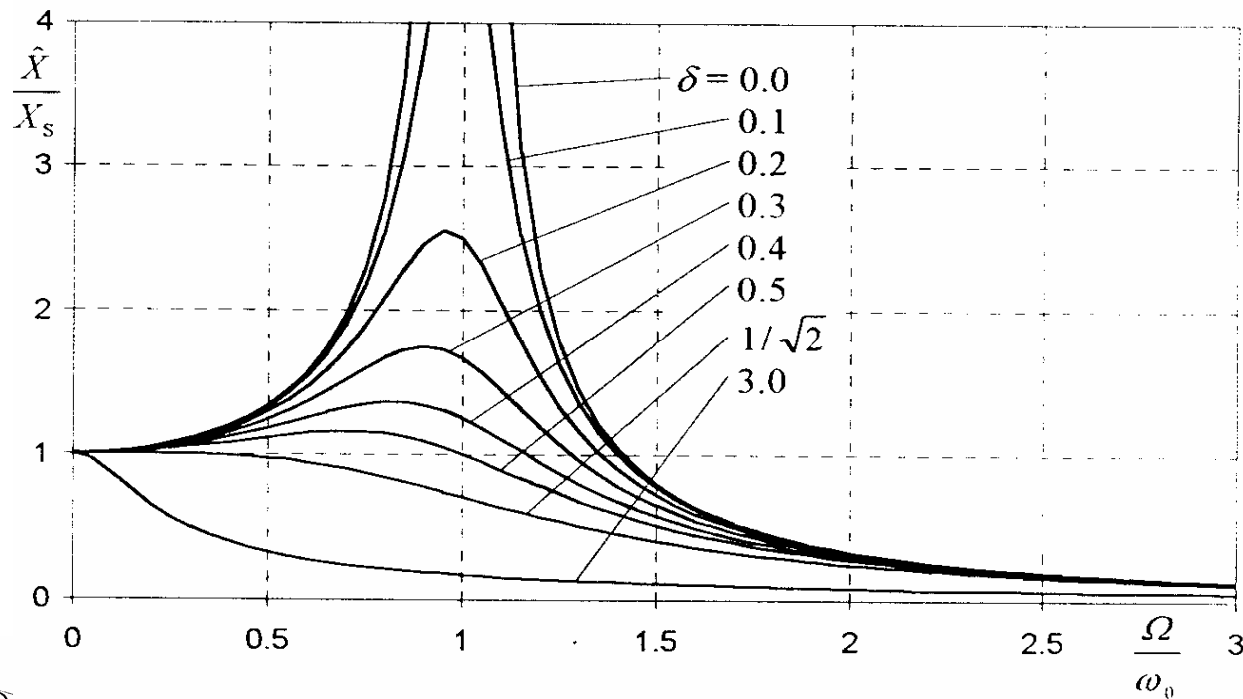


# Modal analyses II (ATC, Drachten)





# Damping of vibration



$$\omega_n = \sqrt{k / m}$$

$$\omega_{nd} = \omega_n \sqrt{1 - d^2}$$

$k$  – stiffness

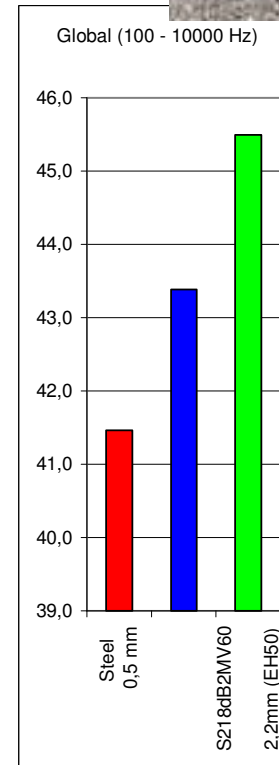
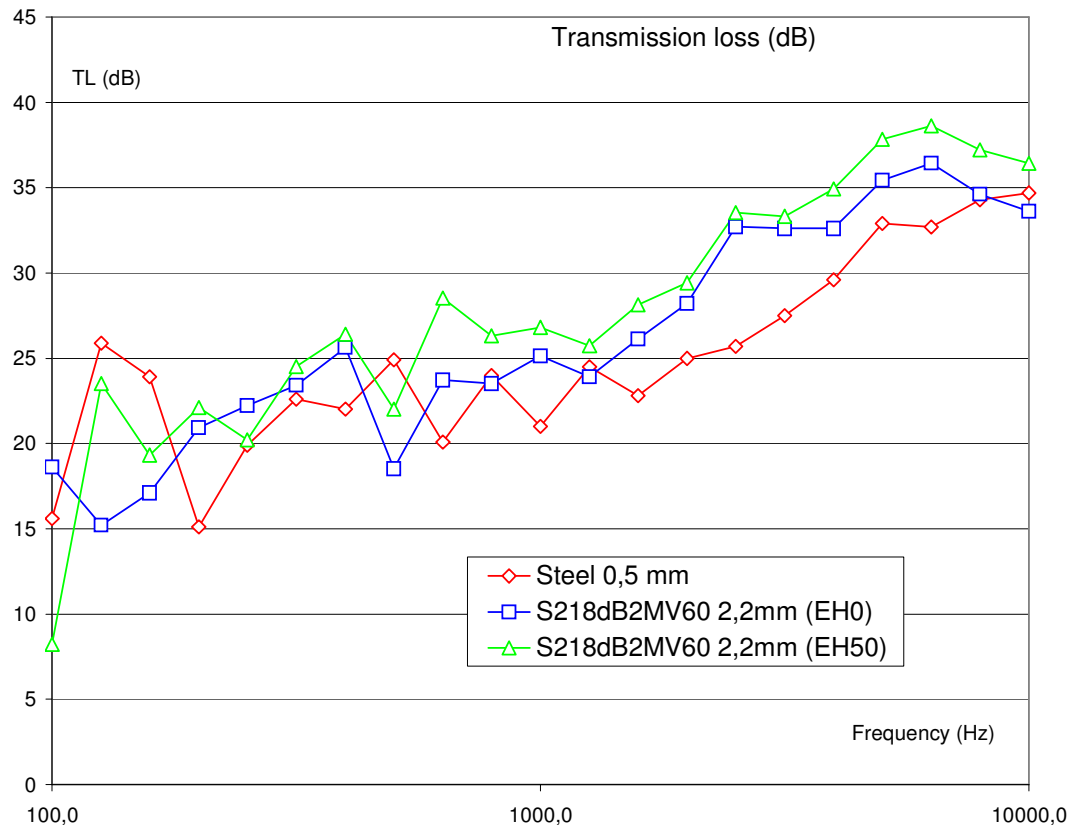
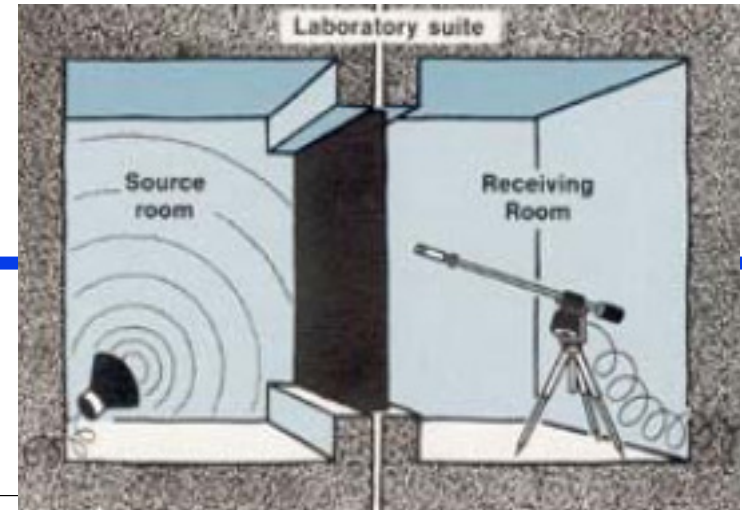
$m$  – mass

$\omega_n$  – natural  
frequency

$d$  – damping factor

# Damping materials

Cover made from accoustic polyamide



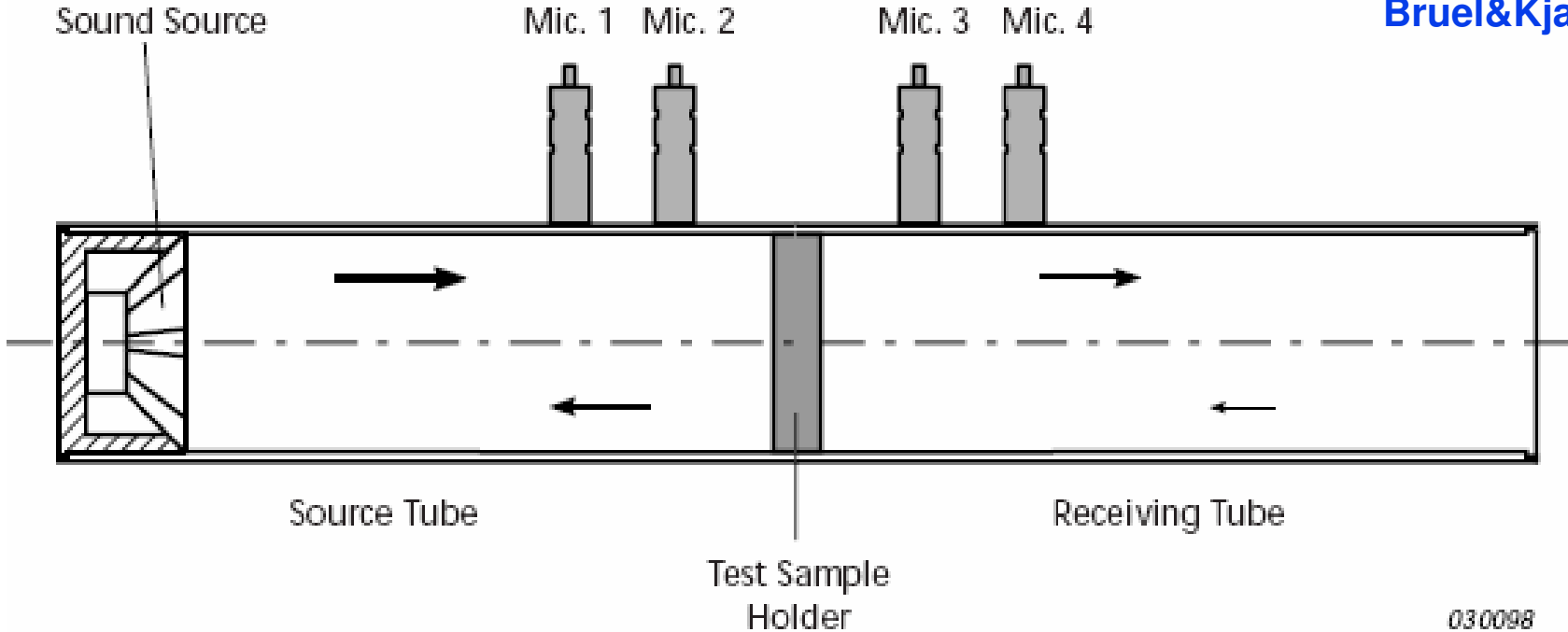
Steel 0.5mm Vs polyamide

With an high insulation grade as the the cover :  
Improves by 3dB  
 the acoustic insulation in comparison with the steel cover

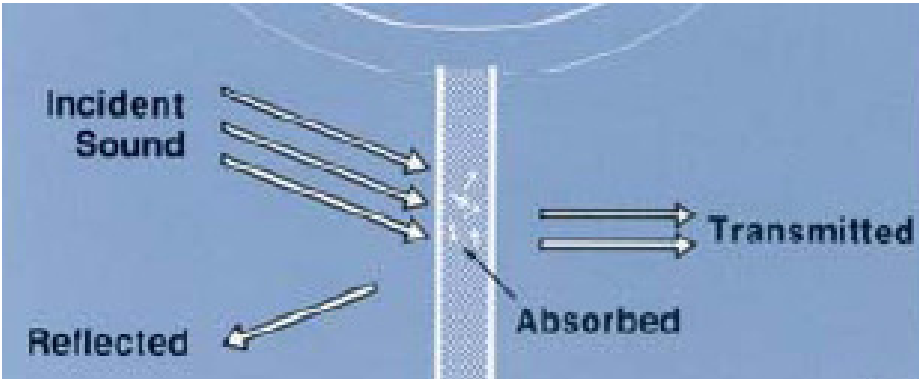
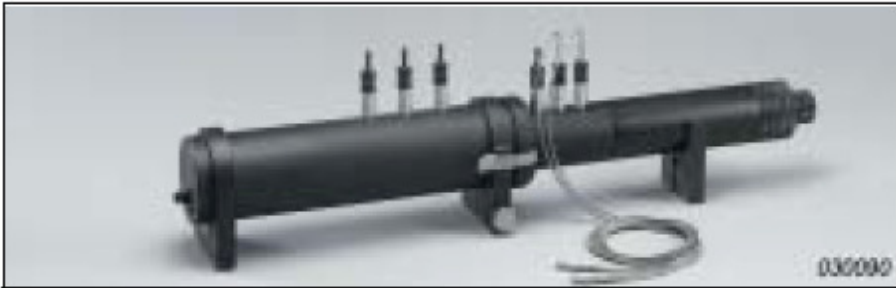


# Transmission loss measurements

Bruel&Kjaer



030098



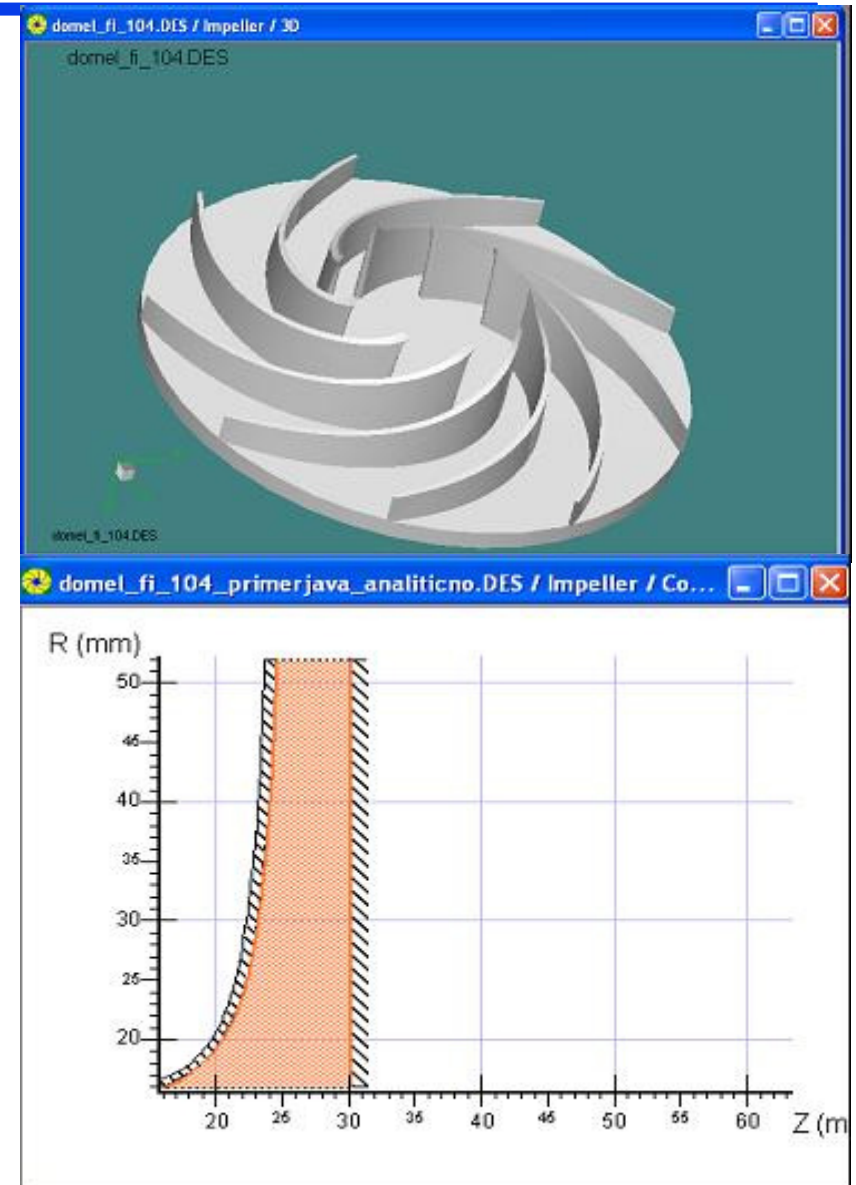
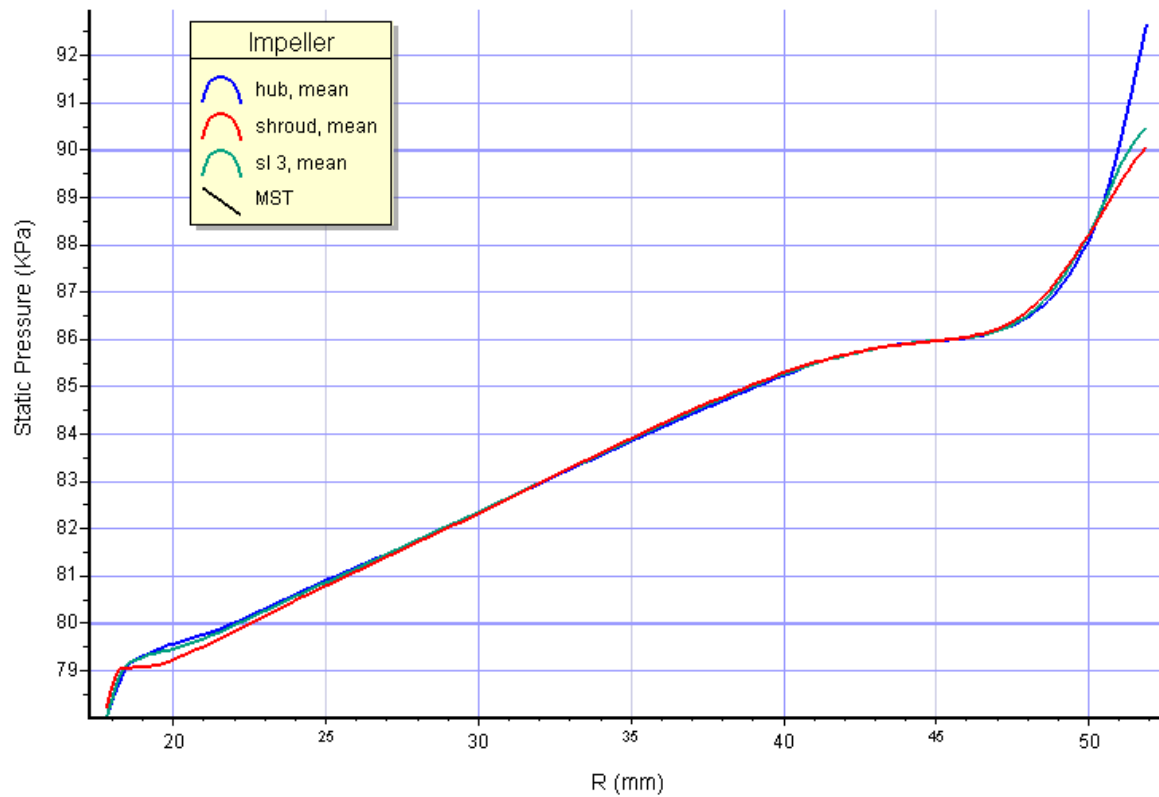
# Noise sources

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## **Aero-dynamic noise:**

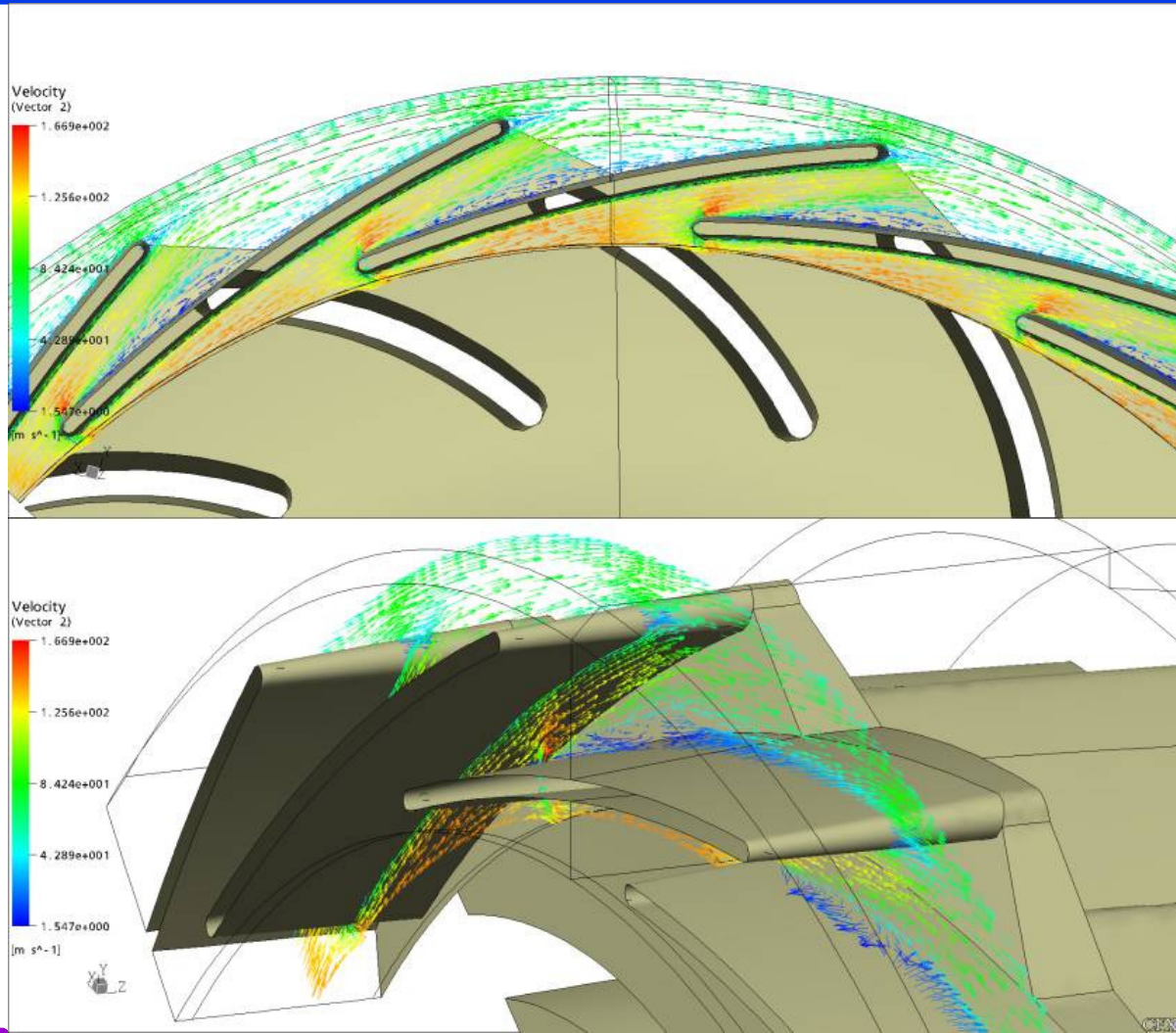
- **blade passing frequency noise  
(fan and diffuser blade interaction)**
- **CFD calculation**
- **flow visualisation**
- **acoustic camera**

# Aerodynamic calculations of impeller and diffuser geometry





# CFD analyses of Global motor, CFX software LECAD, Faculty of Mechanical Engineering Ljubljana



Matjaž Šubelj,  
LECAD

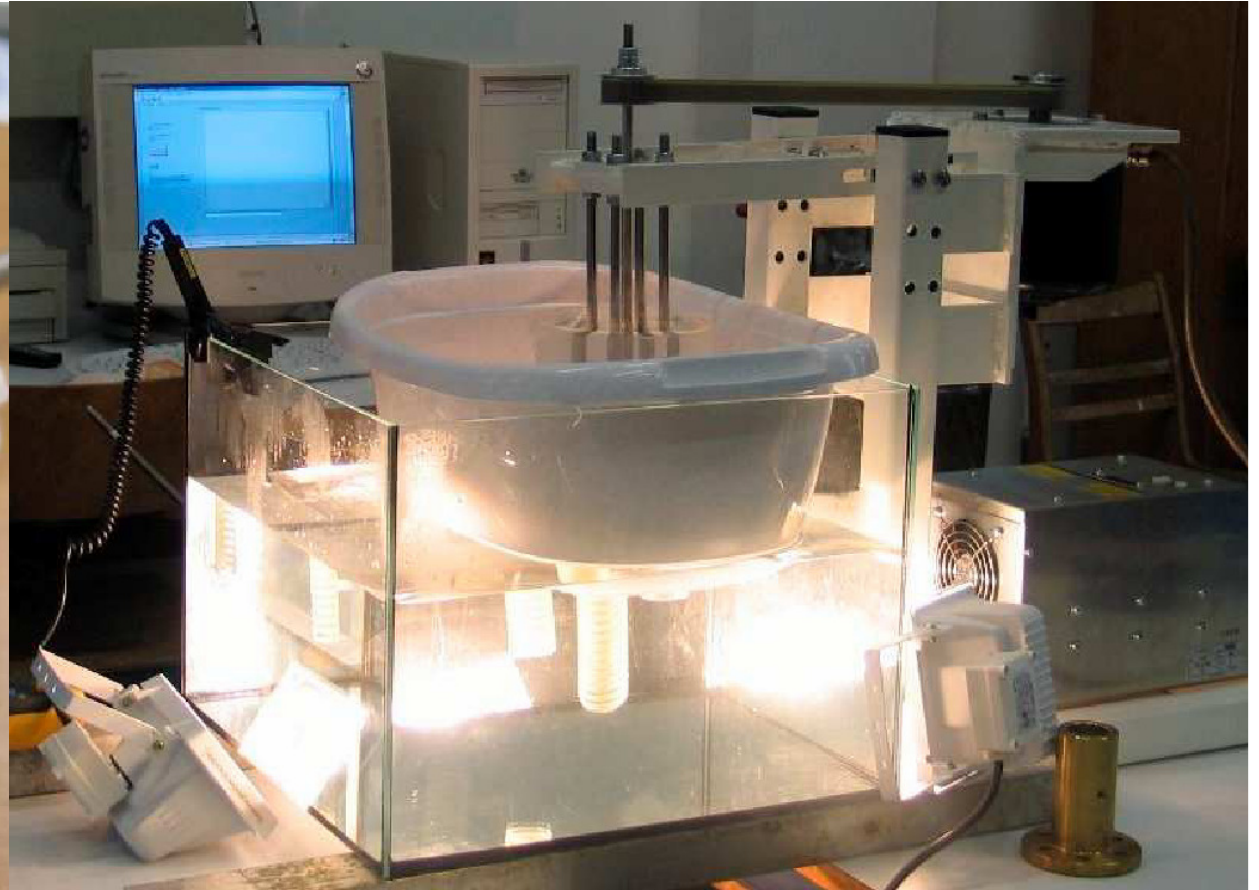
K-ε turbulence  
Model

Airflow 29 l/s  
(orifice fi19)

# Visualization of the airflow

Janez Rihtarsic, LECAD, FME Ljubljana

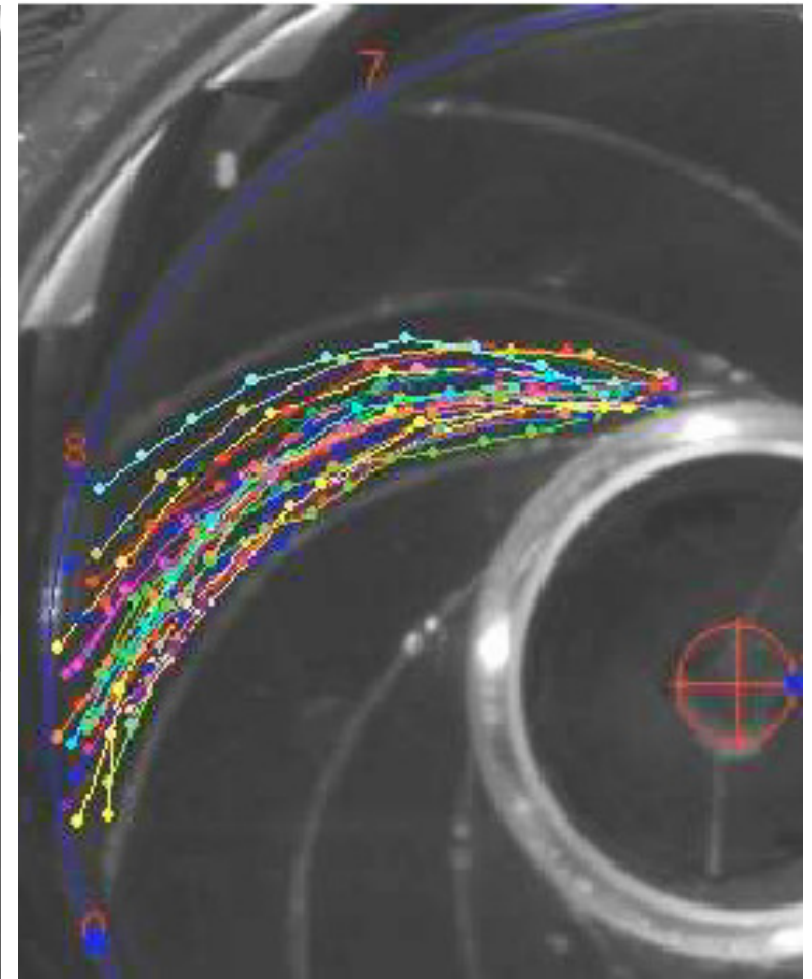
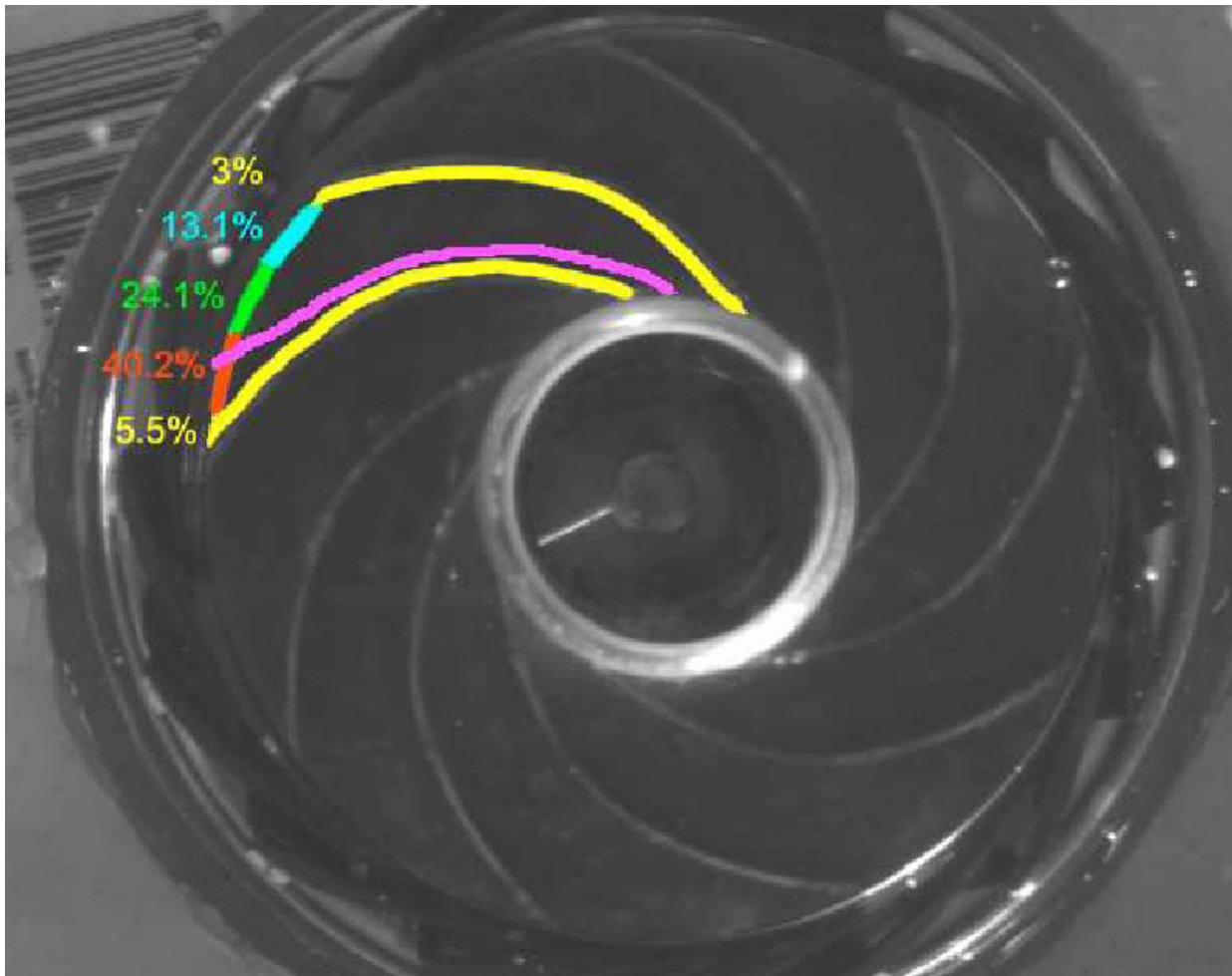
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# Visualization of the airflow

Janez Rihtarsic, LECAD, FME Ljubljana

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# Results of powder applying

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Improved inlet of the motor



# Measurements:

## Test-rig for rapid examinations of VCM's

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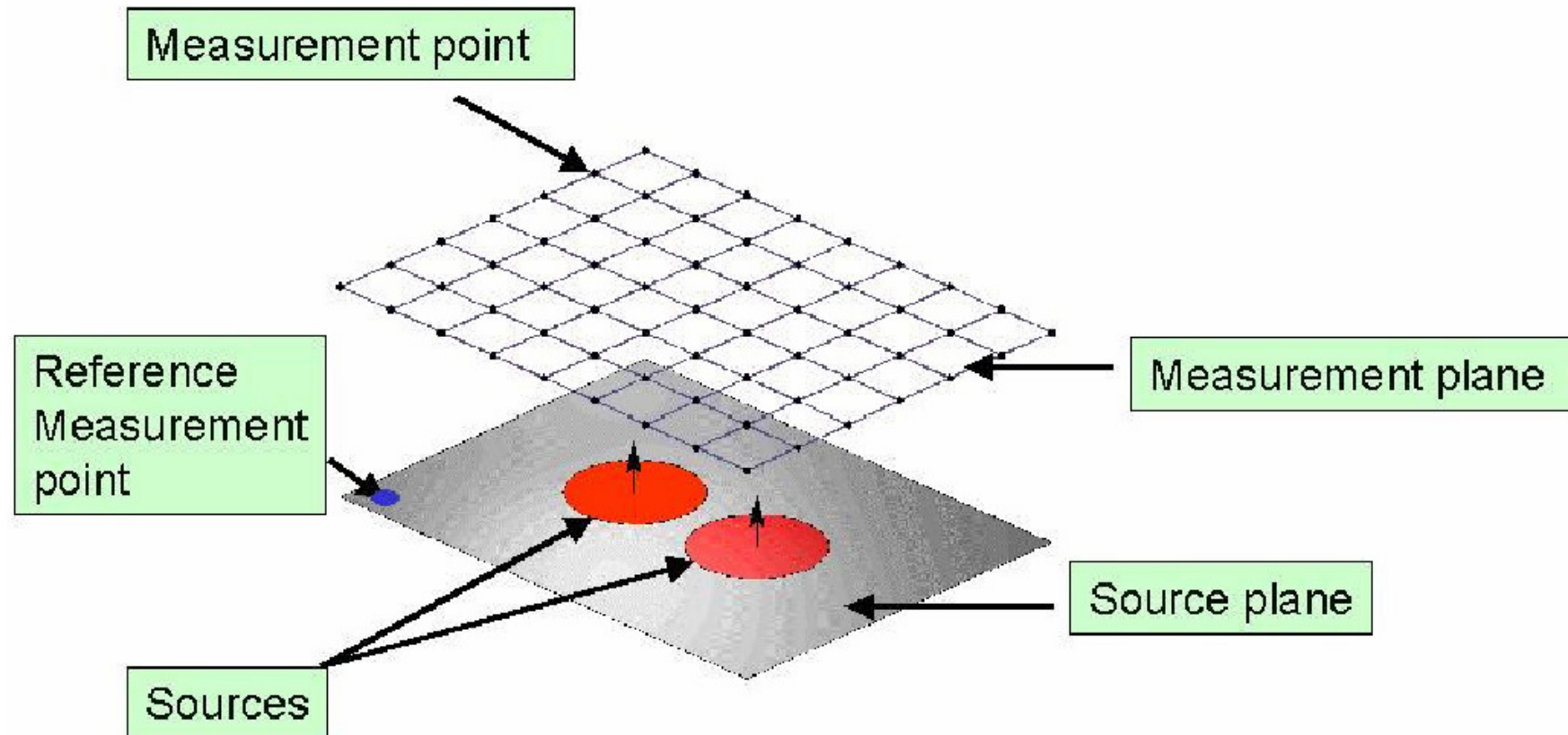
- on-line monitoring of motors or impellers only
- rapid examination
- high flexibility
- according to several standards





# Acoustic camera principles of measurements (ATC)

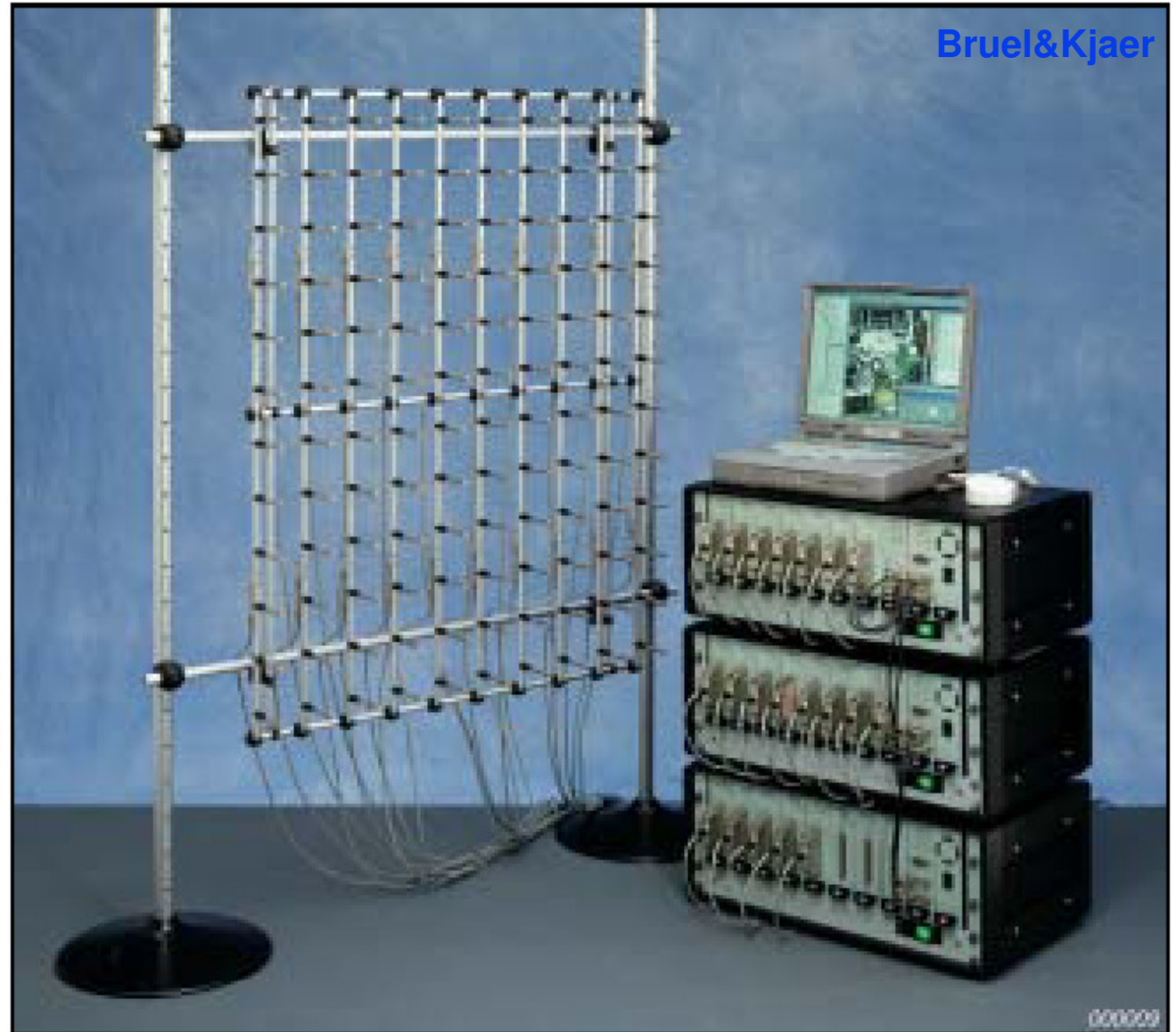
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# Array of microphones / sound camera



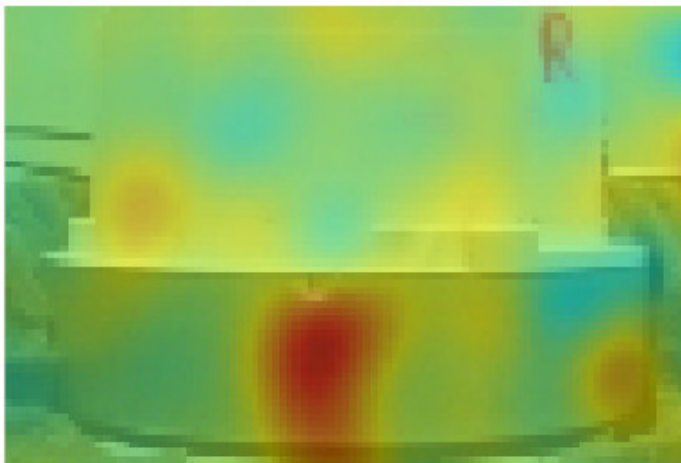
**DOMEL**<sup>®</sup>



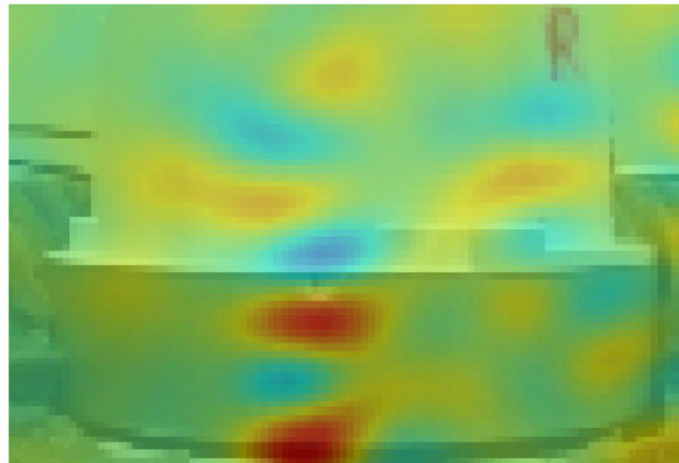
Bruel&Kjaer

## Acoustic camera 3 (Philips, ATC) left side, blade passing frequency, airflow 20 l/sec

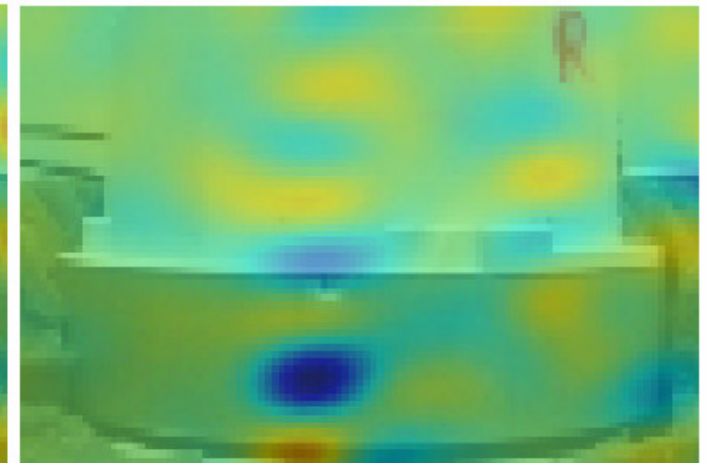
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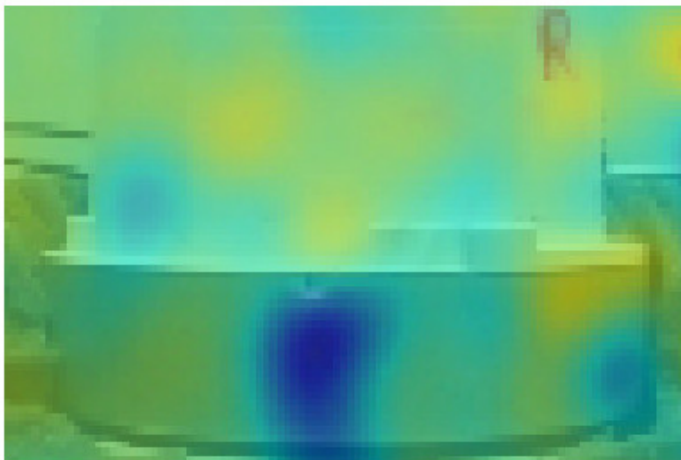
*0 degrees*



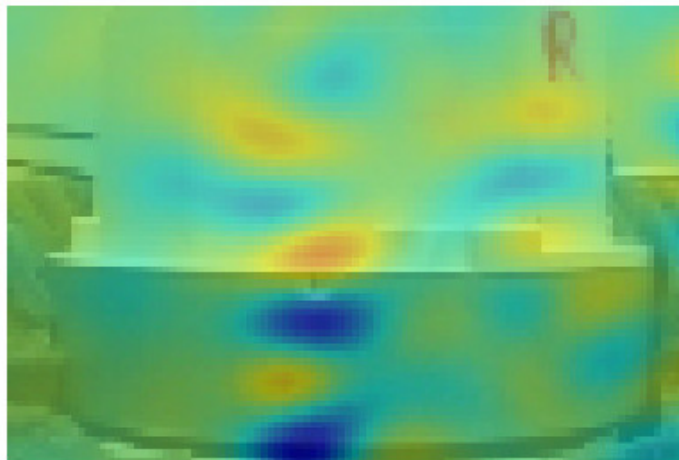
*60 degrees*



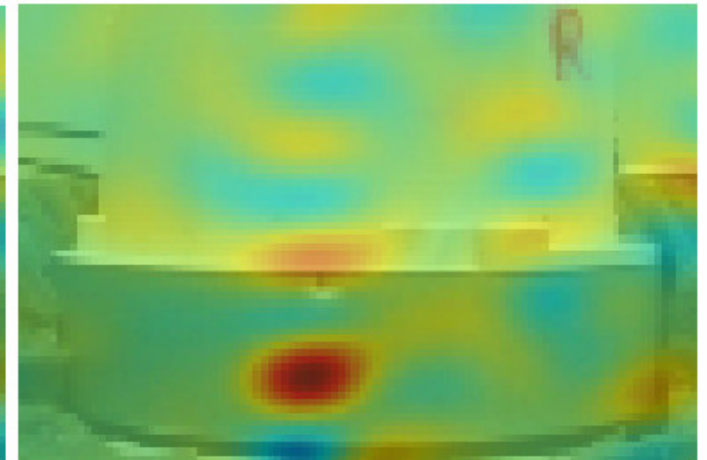
*120 degrees*



*180 degrees*



*240 degrees*



*300 degrees*



# Standing wave experiment setup

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Signal  
generator  
(sweep sinus or  
random  
broadband noise)

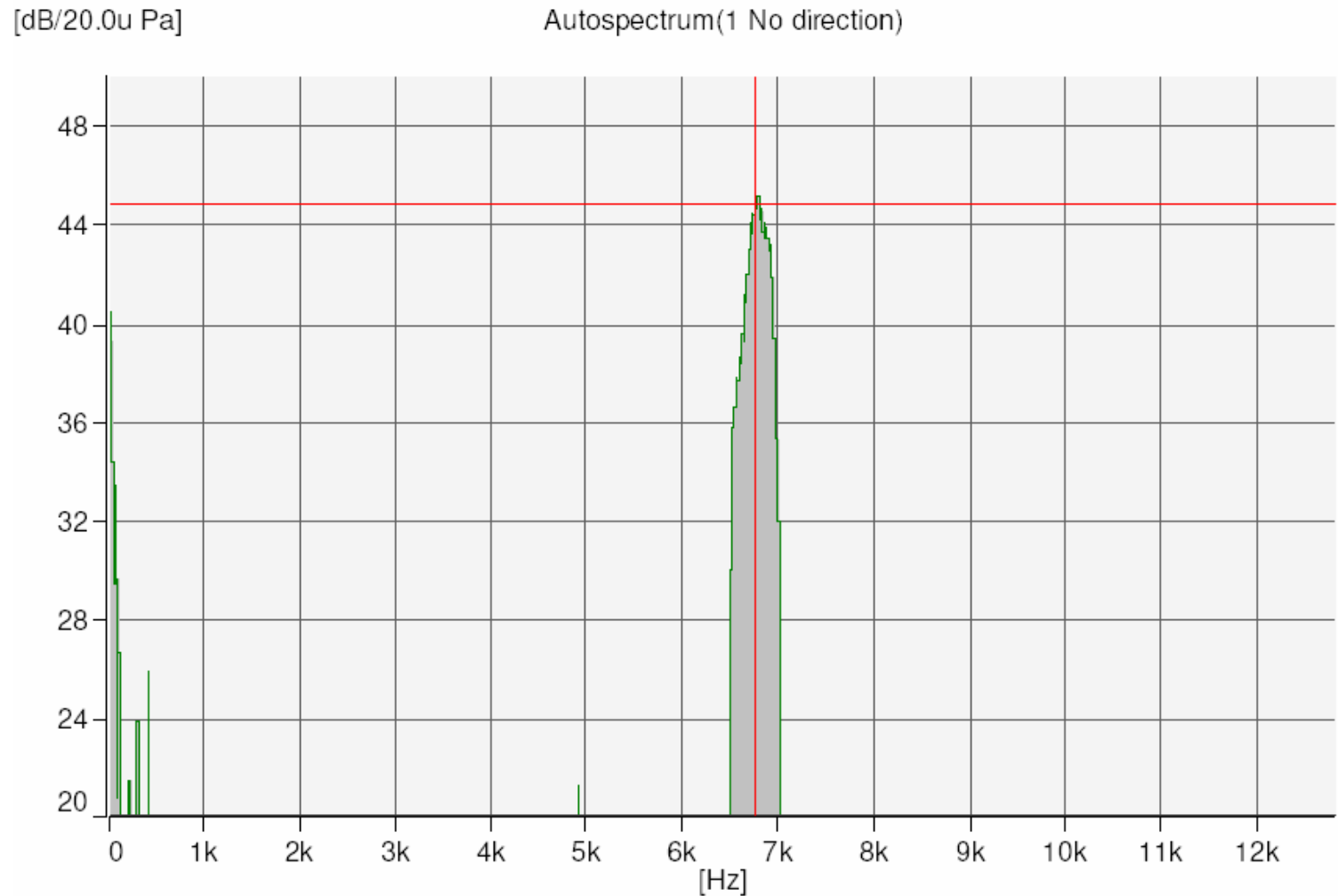


microphone

Speaker

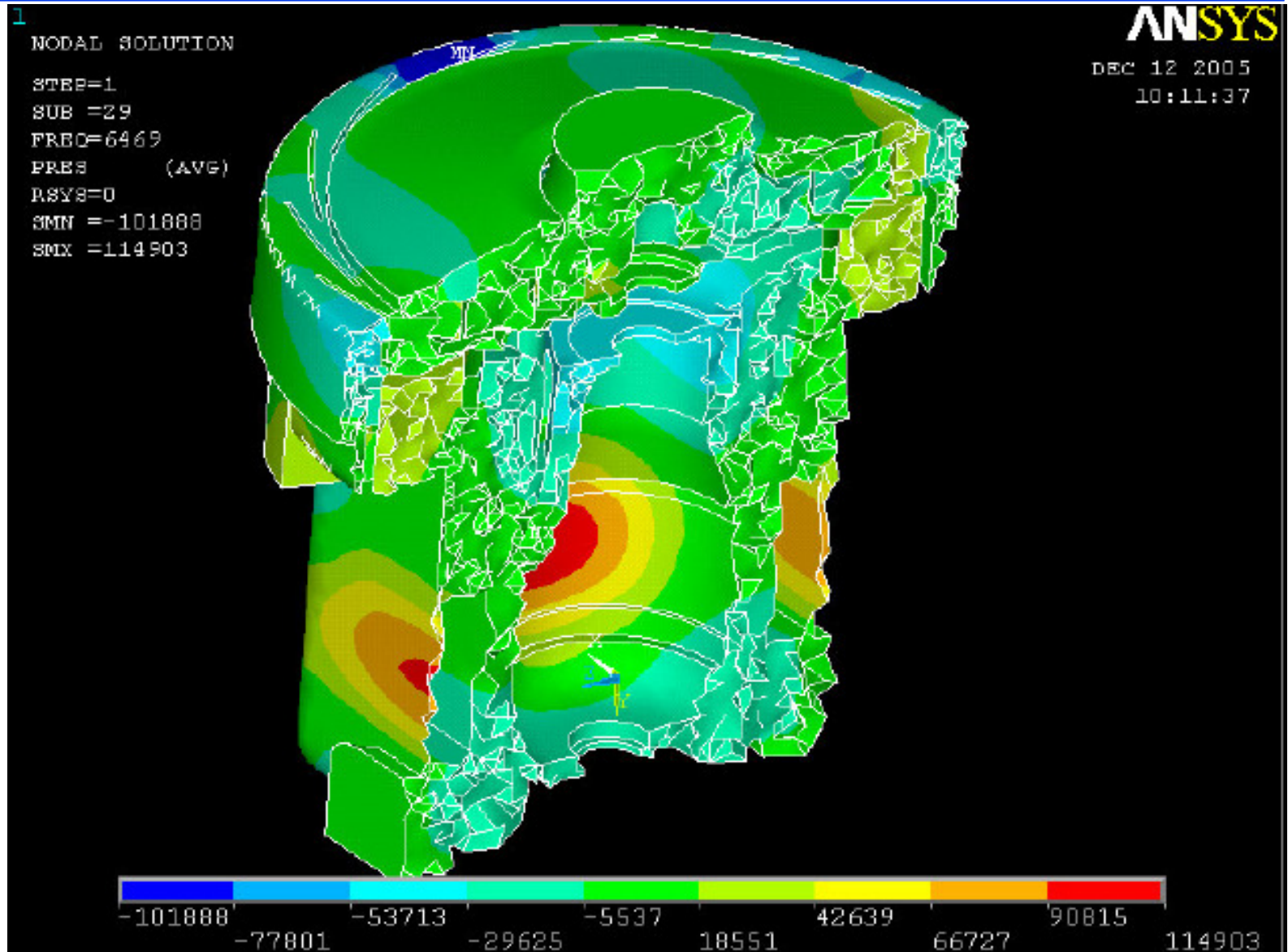
# Standing wave Sound measurement

Peak hold  
measurement  
(peak overlap)





# Standing wave FEM calculation (ATC, Drachten)



# Noise level reduction

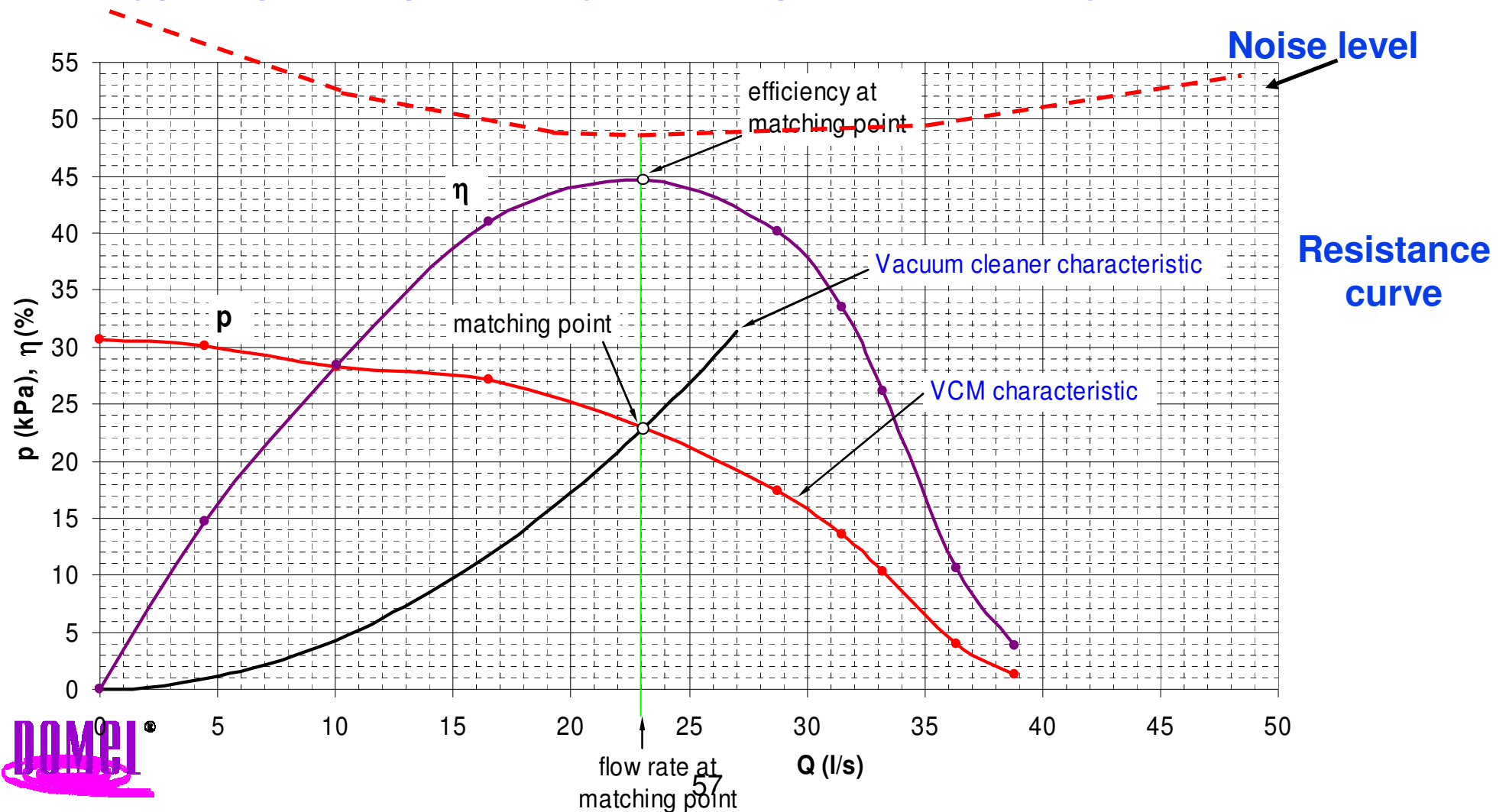
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## Case study:

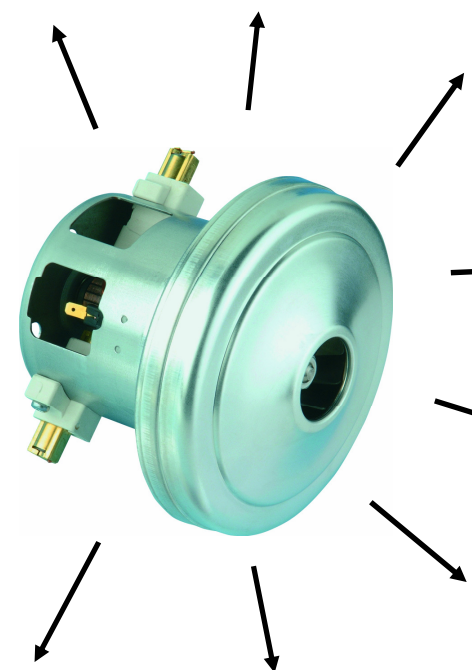
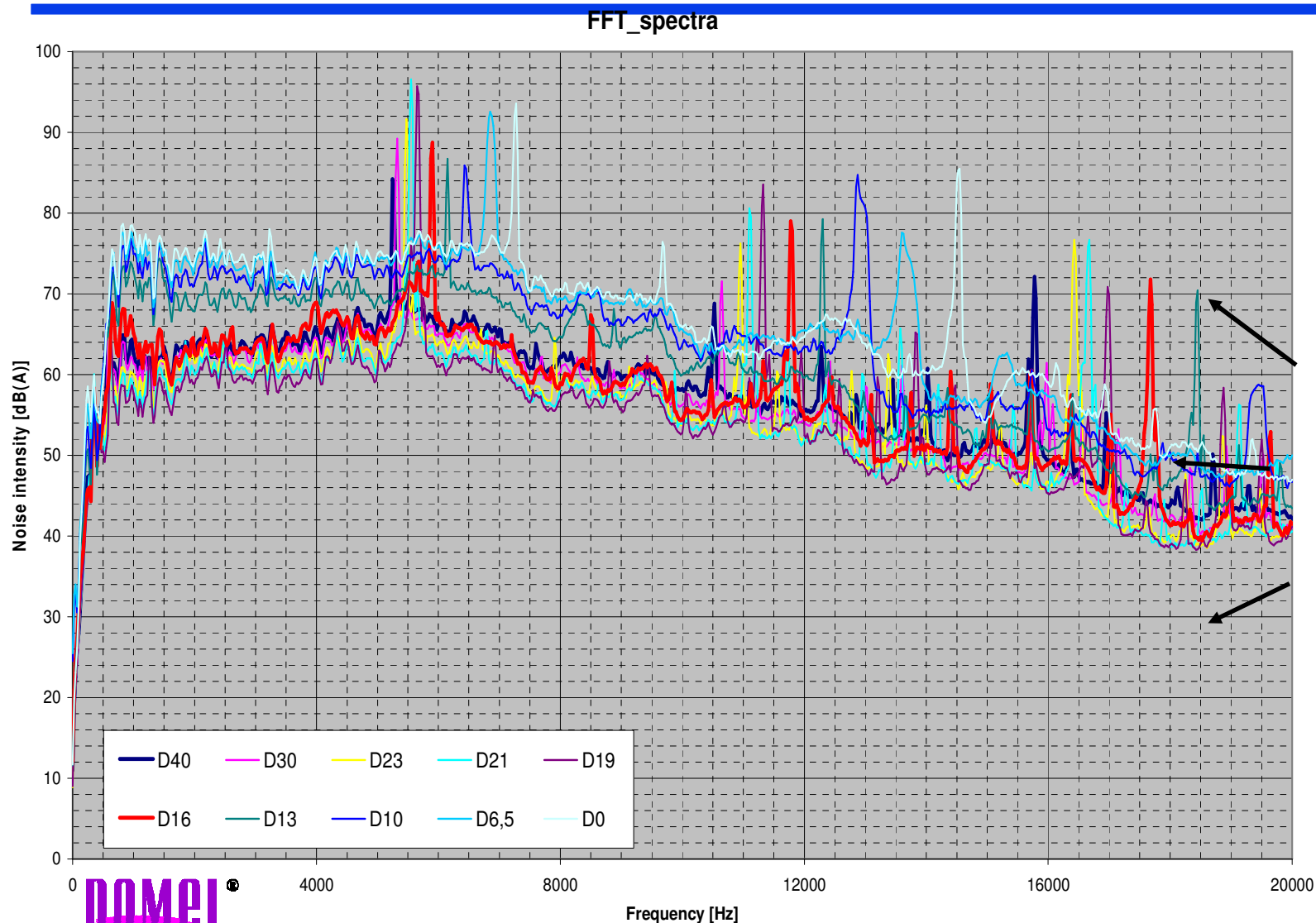
- Good matching between vacuum cleaner and motor
- Impeller design
- Helmholtz resonator

# Good Matching between vacuum cleaner and Motor reduces noise level

- Matching point: pressure produced by the VCM = pressure loss through the vacuum cleaner

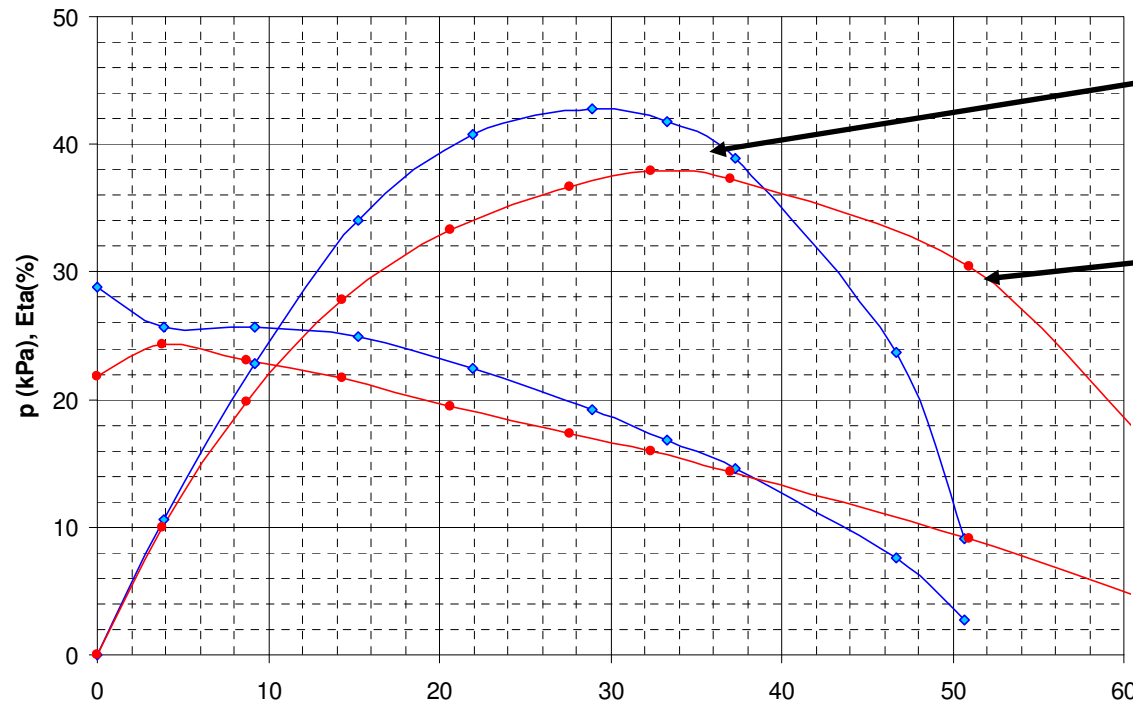


# Sound spectrum / total level / annoying peaks





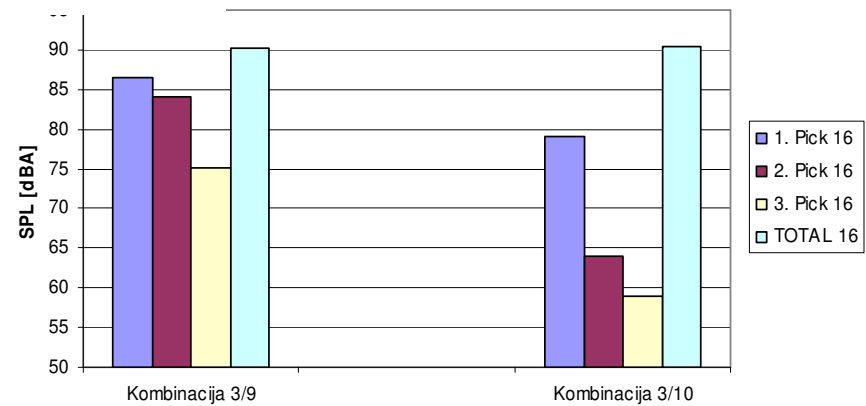
# Diffuser removal - 2



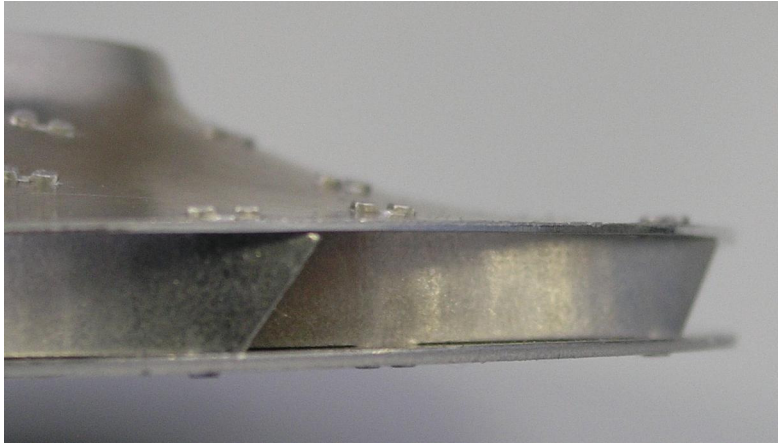
Original VCM with diffuser

VCM without vaned diffuser

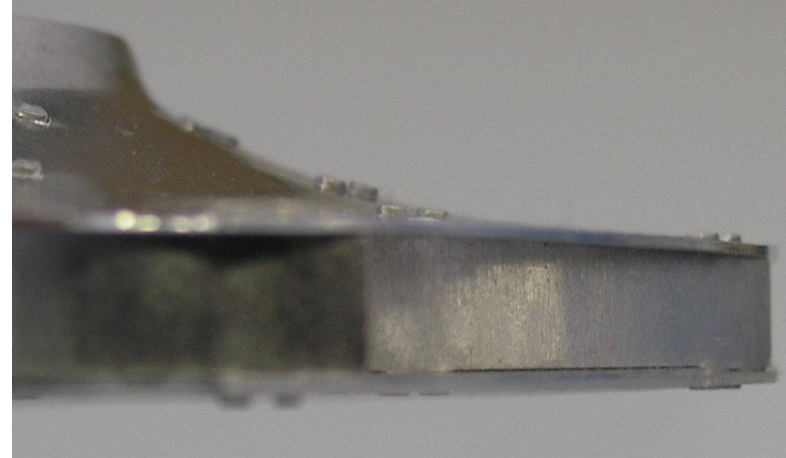
Broadband noise increase



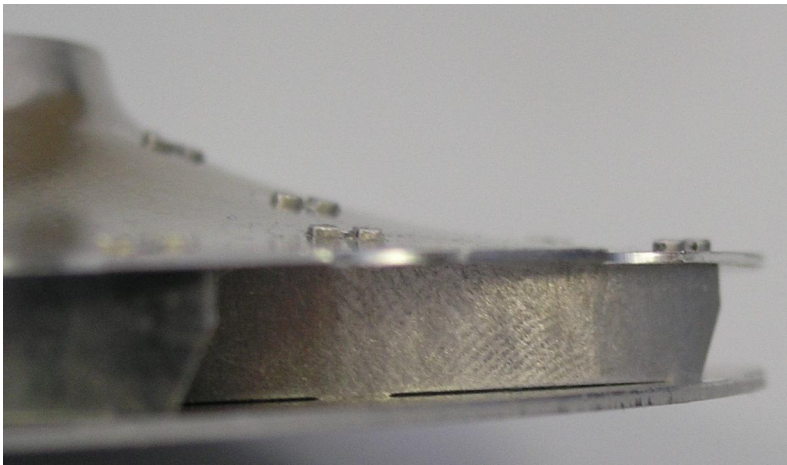
# Impeller blade cut (462)



Inclination down



Standard blade



Step - Inclination down



Improved performance at low airflow  
with blade cut **Inclination down**

Small influence on noise

# Impeller geometry variation

## Taguchi experiment

### 1 – shorter blade (cut)

- A – 0.0 mm (current)
- B – 2.0 mm
- C – 4.0 mm

### 2 – impeller exit width

- A – 6.3 mm - (current impeller fi 90)
- B – 5.7 mm (input width (6.3 mm))
- C – 5.0 mm ((input width (6.3 mm))

### 3 – shape of exit blade

- A – blade cut with inclination 30 degrees
- B – straight cut (current)

### 4 – impeller input width

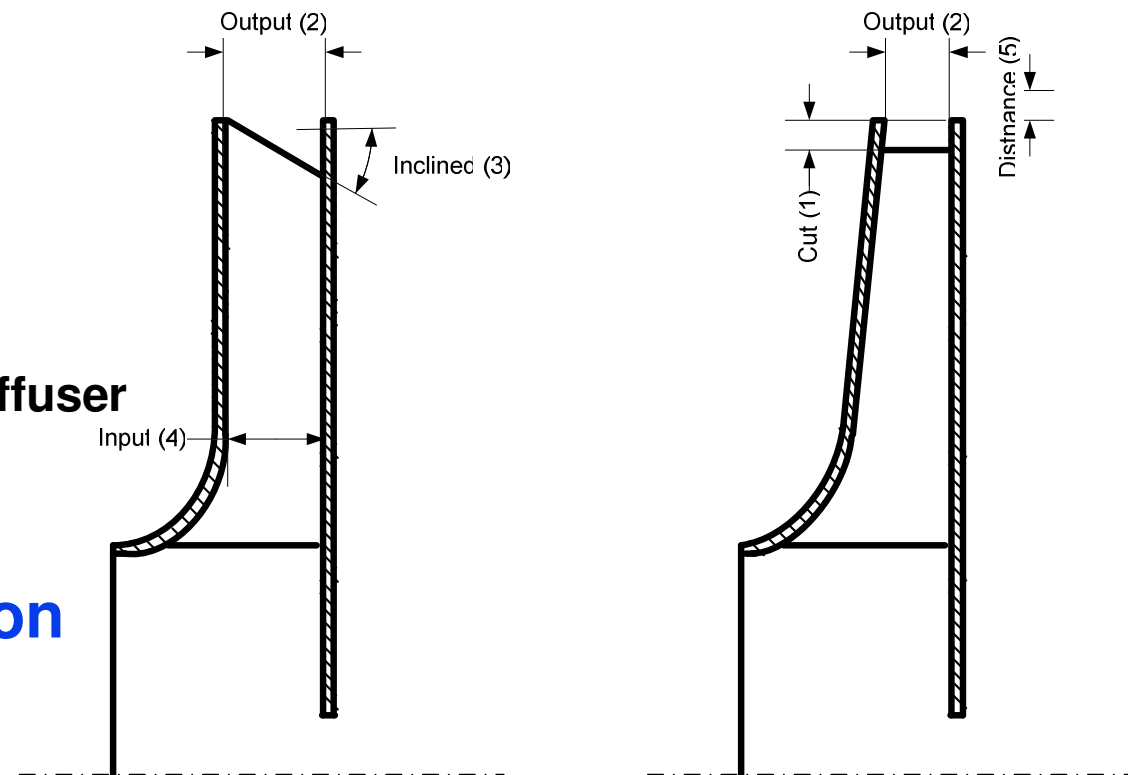
- A – 6.3 mm - (current impeller fi 90)
- B – 8.0 mm

### 5 – distance between impeller and diffuser

- A – 1 mm - (current impeller fi 90)
- B – 0.5 mm (bigger impeller diameter)

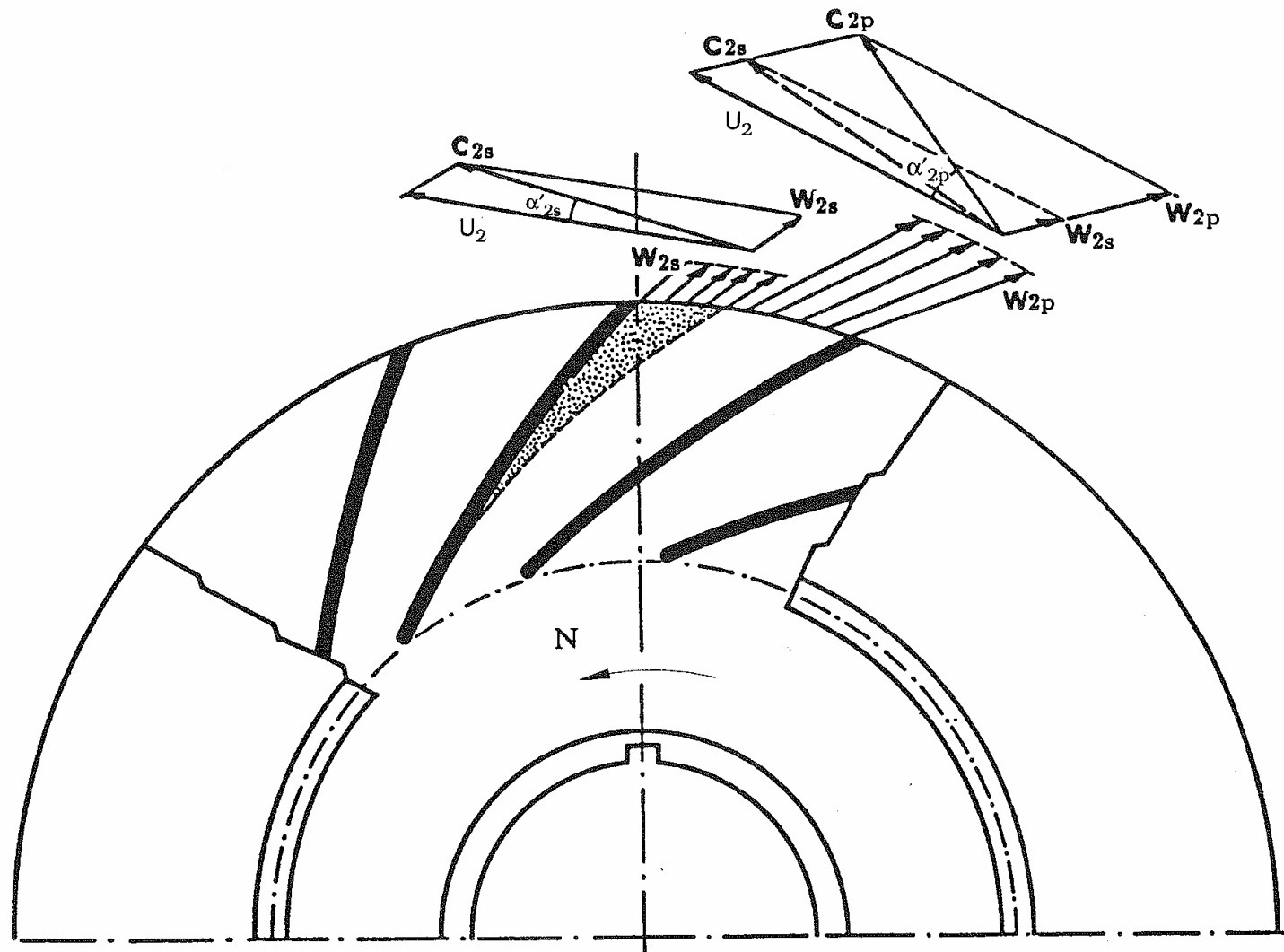
### ■ Taguchi system

Prepared on the base of experiences and literature review



**Result: 3 dB noise reduction**

# Primary and secondary flow: reason for Blade Passing Frequency





# Helmholtz Resonator – technical principle

$$f \text{ [Hz]} = \frac{c}{2\pi} \sqrt{\frac{S}{lV}}$$

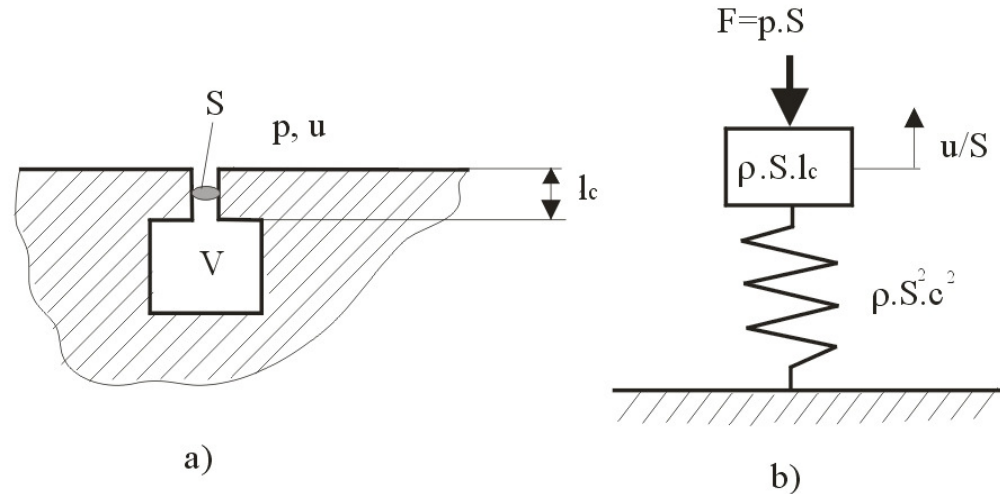
$f$  [Hz] - resonator frequency

$c$  [m/s] – sound speed

$S$  [m<sup>2</sup>] - size of orifice

$l$  [m] - neck size

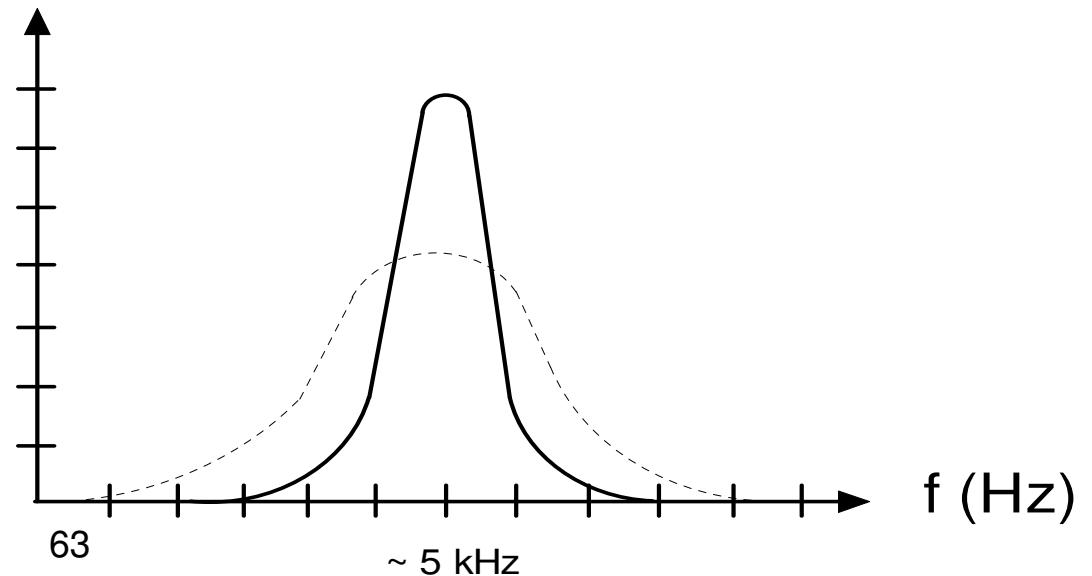
$V$  [m<sup>3</sup>] – volume of resonator



**Resonator  
absorbs energy  
at resonating  
frequency**

**Damping  
level**

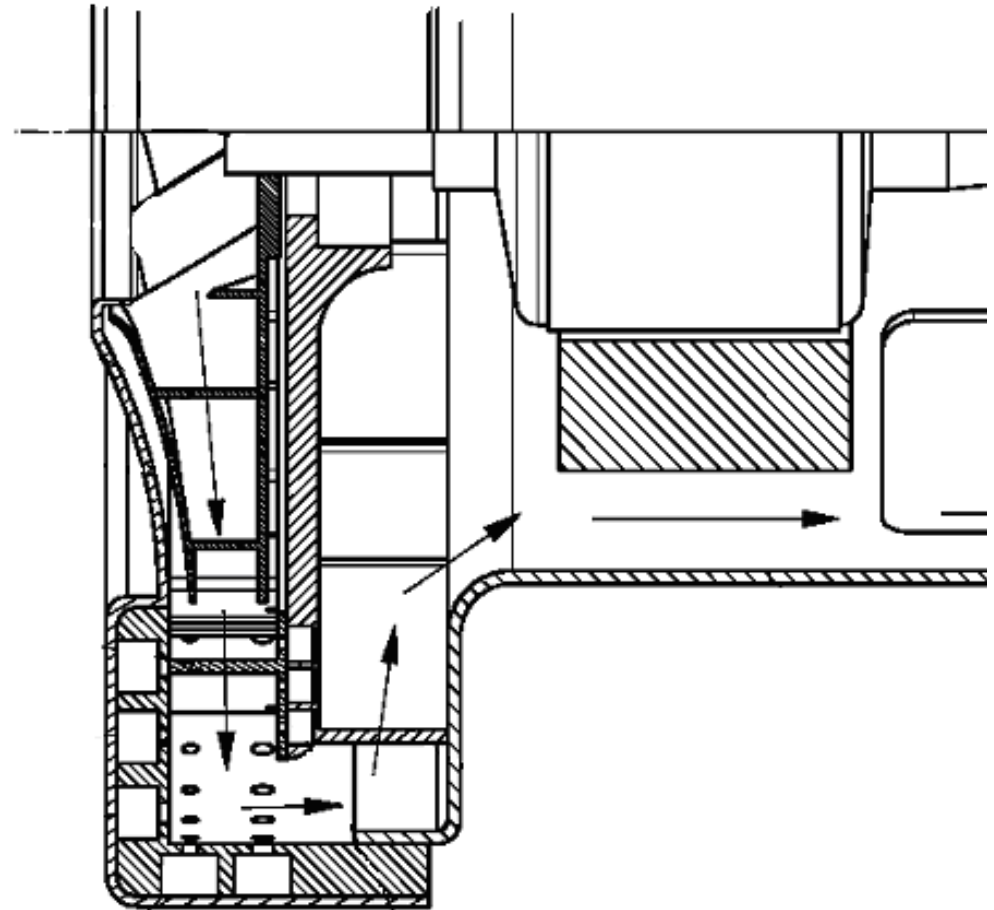
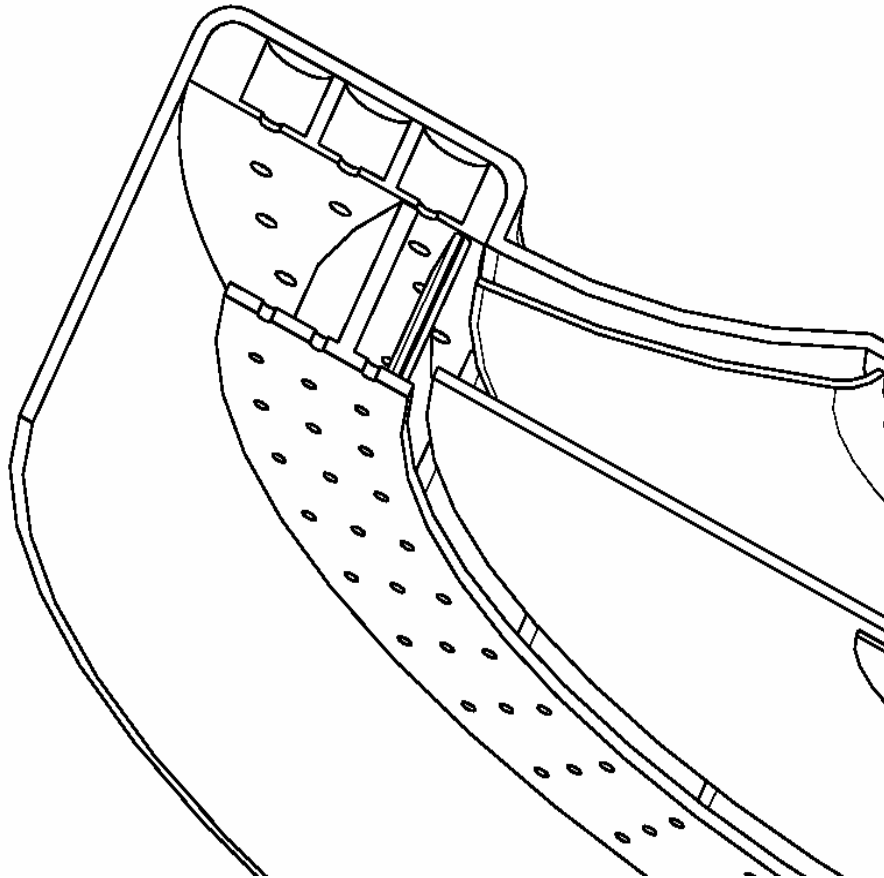
~ 20 dB



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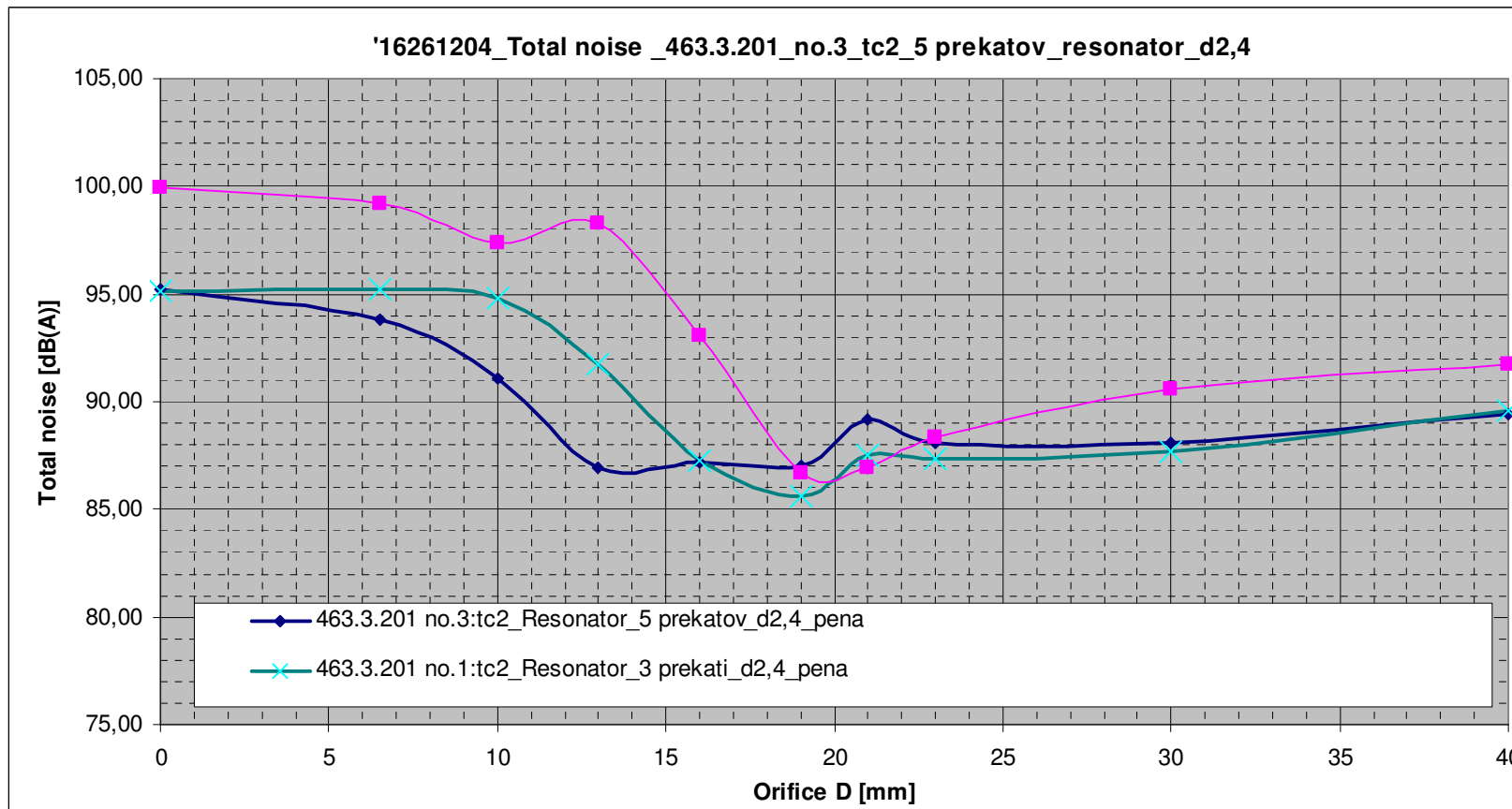
# Resonator – implementation detail

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# Resonator and total noise level

Pink line -VCM without resonator



# Noise control

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## Active noise control

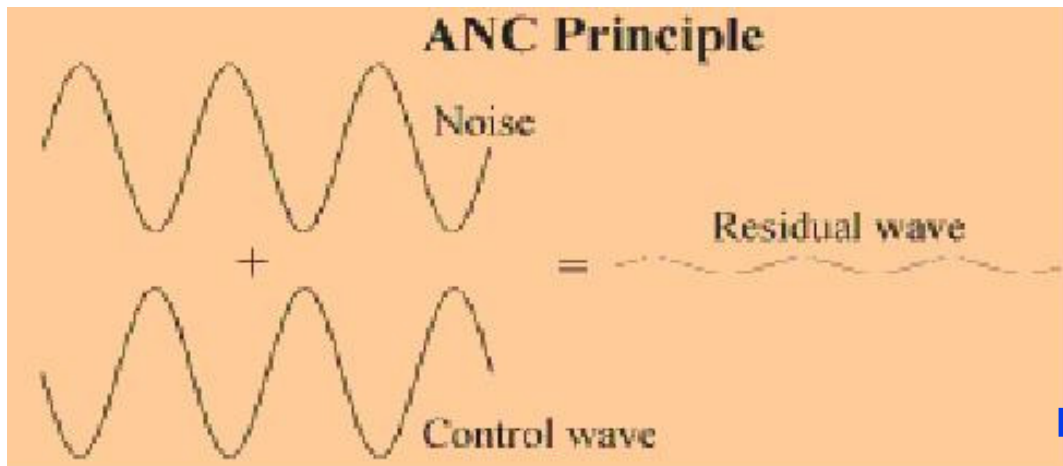


# Active noise control I

- Idea comes from 1930's, more development in 1950's
- several commercial application in the last 15 years (from simple headphone (cancel low-frequency noise) , vehicle cabins, military applications in helicopter)

## Physical principle:

- Control wave have the same amplitude and shifted phase therefore is the noise eliminated or significantly reduced.
- active noise cancellation (ANC) and
- active structural-acoustic control (ASAC)



Experiment of ANC with two microphones from Virginia university

# Active noise control II

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- Active noise control is more efficient at lower frequencies ( $< 1000$  Hz)
- Passive damping is more efficient at higher frequencies ( $> 1000$  Hz)

## LIMITATIONS:

Costs of the advanced equipment

(microphone, speaker, feedback control system)

Efficiency depend on many circumstances:

- ANC works best for sound fields that are spatially simple

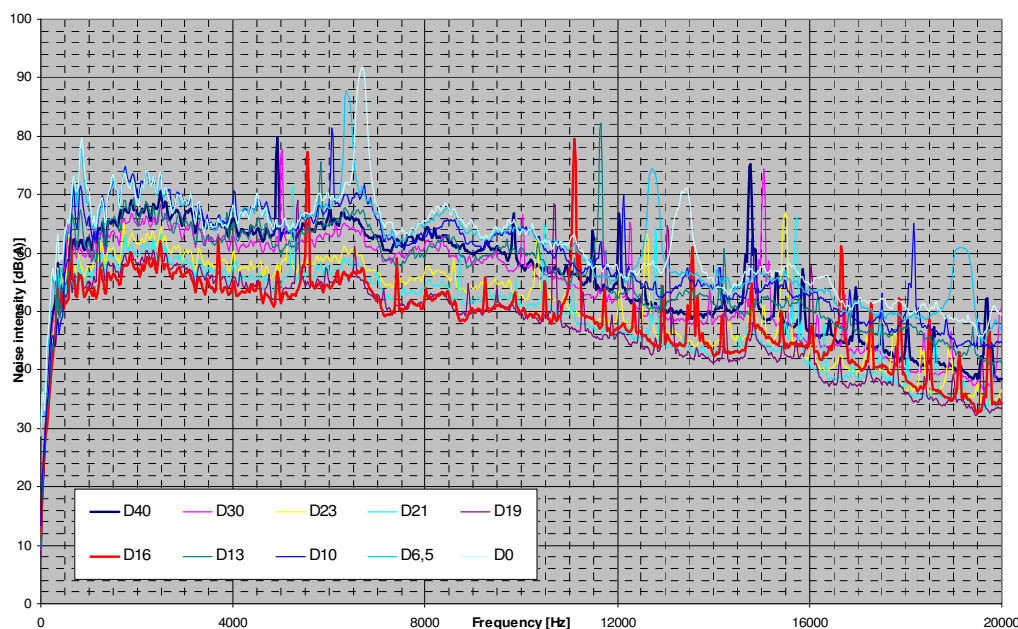
Controlling a spatially complicated sound field is beyond today's techn.

It is easier to control noise in an enclosed space

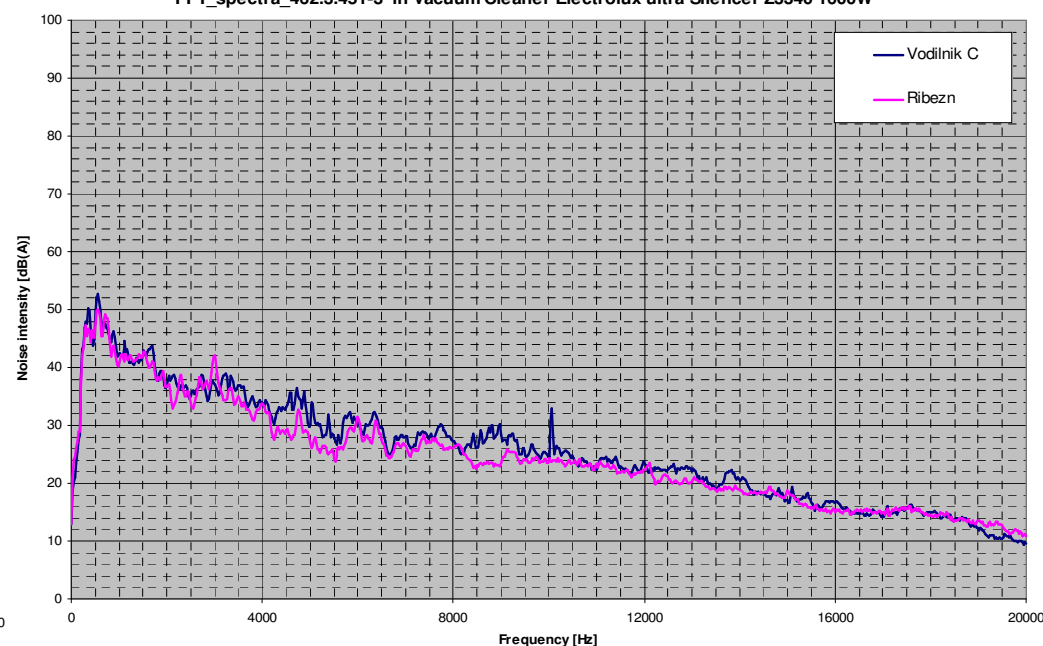
- Broadband noise is harder to control than tonal noise
- ANC works best when the wavelength is long compared to the dimensions of its surroundings (500 Hz  $\Rightarrow$  0.68 m)

# Application of ANC and EC motors

FFT\_spectra\_462.3.451-3\_diffuser\_c\_(open)



FFT\_spectra\_462.3.451-3 in Vacuum Cleaner Electrolux ultra Silencer Z3340 1600W



- Running project: application of ANC to EC motors

Active noise control is more efficient at lower frequencies (< 1000 Hz)  
=> this is the speed of rotation and dominated peak

Use of ANC for reduction of rotating speed frequency at 400 Hz  
ANC will be applied inside the motor or inside the appliance



# Conclusions

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**Noise reduction is possible through:**

- **Integrated approach**
- **Understanding physical background of the noise sources**
- **Advanced numerical and measurement methods**
- **Innovative solutions**
  
- **Close cooperation between motor and appliance manufacturer**

information: [www.domel.com](http://www.domel.com)

<http://www.burger.si/SLOIndex.htm>

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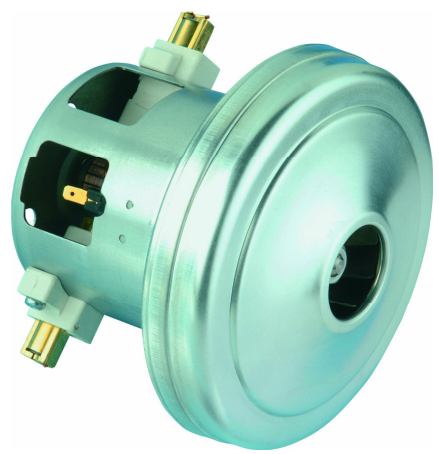




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